

# Five Point Energy Minimization 3: Local Analysis

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## Abstract

This is Paper 3 of series of 7 self-contained papers which together prove the Melnyk-Knopf-Smith phase transition conjecture for 5-point energy minimization. (Paper 0 has the main argument.) This paper deals with a local analysis of configurations near the triangular bi-pyramid.

## 1 Introduction

### 1.1 Context

Let  $S^2$  be the unit sphere in  $\mathbf{R}^3$ . Given a configuration  $\{p_i\} \subset S^2$  of  $N$  distinct points and a function  $F : (0, 2] \rightarrow \mathbf{R}$ , define

$$\mathcal{E}_F(P) = \sum_{1 \leq i < j \leq N} F(\|p_i - p_j\|). \quad (1)$$

This quantity is commonly called the  $F$ -potential or the  $F$ -energy of  $P$ . A configuration  $P$  is a *minimizer* for  $F$  if  $\mathcal{E}_F(P) \leq \mathcal{E}_F(P')$  for all other  $N$ -point configurations  $P'$ . The question of finding energy minimizers has a long literature; the classic case goes back to Thomsom [**Th**] in 1904.

We are interested in the case  $N = 5$  and the *Riesz potential*  $F = R_s$ , where

$$R_s(d) = d^{-s}, \quad s > 0. \quad (2)$$

The *Triangular Bi-Pyramid* (TBP) is the 5 point configuration having one point at the north pole, one point at the south pole, and 3 points arranged in an equilateral triangle on the equator. A *Four Pyramid* (FP) is a 5-point configuration having one point at the north pole and 4 points arranged in a square equidistant from the north pole.

Define

$$15_+ = 15 + \frac{25}{512}. \quad (3)$$

My monograph [S0] proves the following result.

**Theorem 1.1 (Phase Transition)** *There exists  $\vartheta \in (15, 15_+)$  such that:*

1. *For  $s \in (0, \vartheta)$  the TBP is the unique minimizer for  $R_s$ .*
2. *For  $s = \vartheta$  the TBP and some FP are the two minimizers for  $R_s$ .*
3. *For each  $s \in (\vartheta, 15_+)$  some FP is the unique minimizer for  $R_s$ .*

This result verifies the phase-transition for 5 point energy minimization first observed in [MKS], in 1977, by T. W. Melnyk, O. Knop, and W. R. Smith. This work implies and extends my solution [S1] of Thomson's 1904 5-electron problem [Th]. To make [S0] easier to referee, I have broken down the proof into a series of 7 independent papers, each of which may be checked without any reference to the others.

## 1.2 The Result of This Paper

In this paper we do some local analysis which automatically eliminates all the configurations in a definite, explicit neighborhood of the TBP.

**Stereographic Projection:** Let  $S^2 \subset \mathbf{R}^3$  be the unit 2-sphere. *Stereographic projection* is the map  $\Sigma : S^2 \rightarrow \mathbf{R}^2 \cup \infty$  given by the following formula.

$$\Sigma(x, y, z) = \left( \frac{x}{1-z}, \frac{y}{1-z} \right). \quad (4)$$

Here is the inverse map:

$$\Sigma^{-1}(x, y) = \left( \frac{2x}{1+x^2+y^2}, \frac{2y}{1+x^2+y^2}, 1 - \frac{2}{1+x^2+y^2} \right). \quad (5)$$

$\Sigma^{-1}$  maps circles in  $\mathbf{R}^2$  to circles in  $S^2$  and  $\Sigma^{-1}(\infty) = (0, 0, 1)$ .

**Avatars:** Stereographic projection gives us a correspondence between 5-point configurations on  $S^2$  having  $(0, 0, 1)$  as the last point and planar configurations:

$$\widehat{p}_0, \widehat{p}_1, \widehat{p}_2, \widehat{p}_3, (0, 0, 1) \in S^2 \iff p_0, p_1, p_2, p_3 \in \mathbf{R}^2, \quad \widehat{p}_k = \Sigma^{-1}(p_k). \quad (6)$$

We call the planar configuration the *avatar* of the corresponding configuration in  $S^2$ . By a slight abuse of notation we write  $\mathcal{E}_F(p_0, p_1, p_2, p_3)$  when we mean the  $F$ -potential of the corresponding 5-point configuration. One of the avatars representing the TBP is given by  $p_0 = -p_2 = (1, 0)$  and  $p_1 = -p_3 = (0, -\sqrt{3}/3)$ .

**The Special Potentials:** Rather than work with the Riesz potentials, we work with potentials that have a more polynomial flavor. Compare [CK].

$$G_k(r) = (4 - r^2)^k. \quad (7)$$

$$G_5^b = G_5 - 25G_1, \quad G_{10}^{\#\#} = G_{10} + 28G_5 + 102G_2, \quad G_{10}^{\#} = G_{10} + 13G_5 + 68G_2$$

**The Definite Neighborhood:** We specially treat avatars very near the TBP. When we string out the points of  $\xi_0$ , we get  $(1, \cdot, 0, -u, -1, 0, 0, u)$  where  $u = \sqrt{3}/3$ . The  $(\cdot)$  indicates that we do not record  $p_{02} = 0$ . We let  $\Omega_0$  denote the cube of side-length  $2^{-17}$  centered at  $\xi_0$ . For all our choices of  $F$ , the function  $\mathcal{E}_F$  is a smooth function on  $\mathbf{R}^7$ . We check first of all that the gradient of  $\mathcal{E}_F$  vanishes at  $\xi_0$ . This probably follows from symmetry, but to be sure we make a direct calculation in all cases.

Recall that the *Hessian* of a function is its matrix of second partial derivatives. Here is the main result of this paper.

**Theorem 1.2 (Local Convexity)** *For each  $F = G_4, G_6, G_5^b, G_{10}^{\#}, G_{10}^{\#\#}$ , the Hessian of  $\mathcal{E}_F$  is positive definite at every point of  $\Omega_0$ .*

**Corollary 1.3** *Let  $F$  be any of  $G_4, G_5^b, G_5, G_6, G_{10}^{\#}, G_{10}^{\#\#}$ . Then  $\xi_0$  is the unique minimizer for  $\mathcal{E}_F$  inside  $\Omega_0$ .*

**Proof:** Let  $F$  be any of the functions from the Local Convexity Theorem. Let  $\xi \in \Omega_0$  be other than  $\xi_0$ . The Local Convexity Theorem combines with the vanishing gradient to show that the restriction of  $\mathcal{E}_F$  to the line segment  $\gamma$  joining  $\xi_0$  to  $\xi$  is convex and has 0 derivative at  $\xi_0$ . Hence  $\mathcal{E}_F(\xi) > \mathcal{E}_F(\xi_0)$ .

It remains to deal with  $F = G_5$  and  $F = G_{10}^{\#\#}$ . As is well known,  $\xi_0$  is a minimizer for  $G_1$ . Since  $\xi_0$  is the unique minimizer for  $G_5^b$  in  $\Omega_0$ , we see that  $\xi_0$  is also the unique minimizer for  $G_5 = G_5^b + 25G_1$  in  $\Omega_0$ .

By the main result in [T],  $\xi_0$  is the unique global minimizer for  $G_2$ . With this in mind, we see that the same kind of argument we just gave for  $G_5$  also works for  $G_{10}^{\#\#} = G_{10}^{\#} + 15G_5 + 34G_2$ . ♠

The proofs in this paper are computer-assisted. All calculations are all done using exact arithmetic in Mathematica. The reader can download and inspect the files I wrote for this.

## 2 Proof of the Local Convexity Theorem

### 2.1 Reduction to Simpler Statements

We consider  $F$  to be any of the 4 functions

$$G_4, \quad G_6, \quad G_5^b = G_5 - 25G_1, \quad 2^{-5}G_{10}^{\sharp} = 2^{-5}(G_{10} + 13G_5 + 68G_2).$$

Scaling the last function by  $2^{-5}$  makes our estimates more uniform.

Recall that  $\Omega_0$  is the cube of side length  $2^{-17}$  centered at the point

$$\xi_0 = \left(1, 0, \frac{-1}{\sqrt{3}}, -1, 0, 0, \frac{1}{\sqrt{3}}\right) \in \mathbf{R}^7 \quad (8)$$

In general, the point  $(x_1, \dots, x_7)$  represents the avatar

$$p_0 = (x_1, 0), \quad p_1 = (x_2, x_3), \quad p_2 = (x_4, x_5), \quad p_3 = (x_6, x_7). \quad (9)$$

The quantity  $\mathcal{E}_F(x_1, \dots, x_7)$  is the  $F$ -potential of the 5-point configuration associated to the avatar under inverse stereographic projection  $\Sigma^{-1}$ .

$$\mathcal{E}_F(x_1, \dots, x_7) = \sum_{i < j} F(\|\hat{p}_i - \hat{p}_j\|), \quad \hat{p} = \Sigma^{-1}(p). \quad (10)$$

Equation 5 gives the formula for  $\Sigma^{-1}$ .

Let  $H\mathcal{E}_F$  be the Hessian of  $\mathcal{E}_F$ . The Local Convexity Theorem says  $H\mathcal{E}_F$  is positive definite in  $\Omega_0$ . Let  $\partial_J \mathcal{E}_F$  be the (iterated) partial derivative of  $\mathcal{E}_F$  with respect to a multi-index  $J = (j_1, \dots, j_7)$ . Let  $|J| = j_1 + \dots + j_7$ . Let

$$M_N = \sup_{|J|=N} M_J, \quad M_J = \sup_{\xi \in \Omega_0} |\partial_J \mathcal{E}_F(\xi)|, \quad (11)$$

Let  $\lambda(M)$  be the smallest eigenvalue of a real symmetric matrix  $M$ . The Local Convexity Theorem is an immediate consequence of the following two lemmas.

**Lemma 2.1** *If  $M_3(\mathcal{E}_F) < 2^{12}\lambda(H\mathcal{E}_F(\xi_0))$  then  $\lambda(H\mathcal{E}_F(\xi)) > 0$  for all points  $\xi \in \Omega_0$ .*

**Lemma 2.2**  *$M_3(\mathcal{E}_F) < 2^{12}\lambda(H\mathcal{E}_F(\xi_0))$  in all cases.*

## 2.2 Proof of Lemma L1

Let

$$H_0 = H\mathcal{E}_F(\xi_0), \quad H = H\mathcal{E}_F(\xi), \quad \Delta = H - H_0. \quad (12)$$

For any real symmetric matrix  $X$  define the  $L_2$  matrix norm:

$$\|X\|_2 = \sqrt{\sum_{ij} X_{ij}^2} = \sup_{\|v\|=1} \|Xv\|. \quad (13)$$

Given a unit vector  $v \in \mathbf{R}^7$  we have  $H_0v \cdot v \geq \lambda$ . Hence

$$Hv \cdot v = (H_0v + \Delta v) \cdot v \geq H_0v \cdot v - |\Delta v \cdot v| \geq \lambda - \|\Delta v\| \geq \lambda - \|\Delta\|_2 > 0.$$

So, to prove Lemma L1 we just need to establish the implication

$$M_3 < 2^{12}\lambda(H_0) \implies \|\Delta\|_2 < \lambda(H_0).$$

Let  $t \rightarrow \gamma(t)$  be the *unit speed parametrized* line segment connecting  $p_0$  to  $p$  in  $\Omega_0$ . Note that  $\gamma$  has length  $L \leq \sqrt{7} \times 2^{-18}$ . We write  $\gamma = (\gamma_1, \dots, \gamma_7)$ . Let  $H_t$  denote the Hessian of  $\mathcal{E}_F$  evaluated at  $\gamma(t)$ . Let  $D_t$  denote the directional derivative along  $\gamma$ .

Now  $\|D_t(H_t)\|_2$  is the speed of the path  $t \rightarrow H_t$  in  $\mathbf{R}^{49}$ , and  $\|\Delta\|_2$  is the Euclidean distance between the endpoints of this path. Therefore

$$\|\Delta\|_2 \leq \int_0^L \|D_t(H_t)\|_2 dt. \quad (14)$$

Let  $(H_t)_{ij}$  denote the  $ij$ th entry of  $H_t$ . From the definition of directional derivatives, and from the Cauchy-Schwarz inequality, we have

$$(D_t H_t)_{ij}^2 = \left( \sum_{k=1}^7 \frac{d\gamma_k}{dt} \frac{\partial H_{ij}}{\partial k} \right)^2 \leq 7M_3^2. \quad \|D_t(H_t)\|_2 \leq 7^{3/2}M_3. \quad (15)$$

The second inequality follows from summing the first one over all  $7^2$  pairs  $(i, j)$  and taking the square root. Equation 14 now gives

$$\|\Delta\|_2 \leq L \times 7^{3/2}M_3 = 49 \times 2^{-18}M_3 < 2^{-12}M_3 < \lambda(H_0). \quad (16)$$

This completes the proof.

### 2.3 Proof of Lemma 2.2

Let  $F$  be any of our functions. Let  $H_0 = H\mathcal{E}_F(\xi_0)$ .

**Lemma 2.3**  $\lambda(H_0) > 39$ .

**Proof:** Let  $\chi$  be the characteristic polynomial of  $H_0$ . This turns out to be a rational polynomial. We check in Mathematica that the signs of the coefficients of  $\chi(t + 39)$  alternate. Hence  $\chi(t + 39)$  has no negative roots. The file we use is `LemmaL21.m`. ♠

Recalling that  $\xi_0 \in \mathbf{R}^7$  is the point representing the TBP, we define

$$\mu_N(\mathcal{E}_F) = \sup_{|I|=N} |\partial_I \mathcal{E}_F(\xi_0)|. \quad (17)$$

**Lemma 2.4** *For any of our functions we have the bound*

$$\mu_3 < 45893, \quad \frac{(7 \times 2^{-18})^j}{j!} \mu_{j+3} < 38, \quad j = 1, 2, 3. \quad (18)$$

**Proof:** We compute this in Mathematica. The file we use is `LemmaL22.m`. ♠

**Lemma 2.5** *For any of our functions we have the bound*

$$\frac{(7 \times 2^{-18})^4}{4!} M_7 < 2354.$$

**Proof:** We give this proof in the next section. ♠

**Lemma 2.6** *We have*

$$M_3 \leq \mu_3 + \sum_{j=1}^3 \frac{(7 \times 2^{-18})^j}{j!} \mu_{j+3} + \frac{(7 \times 2^{-18})^4}{4!} M_7 \quad (19)$$

**Proof:** Choose any multi-index  $J$  with  $|J| = 3$ . Let  $\gamma$  be the line segment connecting  $\xi_0$  to any  $\xi \in \Omega$ . We parametrize  $\gamma$  by unit speed and furthermore set  $\gamma(0) = \xi_0$ . Let

$$f(t) = \partial_J \mathcal{E}_F \circ \gamma(t).$$

The bound for  $|M_J|$  follows from Taylor's Theorem with remainder once we notice that

$$0 \leq t \leq \sqrt{7} \times 2^{-18}, \quad \left| \frac{\partial^n f(0)}{\partial t^n} \right| \leq (\sqrt{7})^n \mu_n \quad \left| \frac{\partial^n f}{\partial t^n} \right| \leq (\sqrt{7})^n M_n.$$

Since this works for all  $J$  with  $|J| = 3$  we get the same bound for  $M_3$ . ♠

The lemmas above and Equation 18 imply

$$M_3 < 45893 + 3 \times 38 + 2354 \leq 65536 = 2^{16} \leq 2^{12} \lambda(H_0).$$

This completes the proof of Lemma 2.2.

## 2.4 Proof of Lemma 2.5

Now we come to the interesting part of the proof, the one place where we need to go beyond specific evaluations of our functions. When  $r, s \geq 0$  and  $r + s \leq 2d$  we have

$$\sup_{(x,y) \in \mathbf{R}^2} \frac{x^r y^s}{(1+x^2+y^2)^d} \leq (1/2)^{\min(r,s)}. \quad (20)$$

One can prove Equation 20 by factoring the expression into pieces with quadratic denominators. Here is a more general version. Say that a function  $\phi : \mathbf{R}^4 \rightarrow \mathbf{R}$  is *nice* if it has the form

$$\sum_i \frac{C_i a^{\alpha_i} b^{\beta_i} c^{\gamma_i} d^{\delta_i}}{(1+a^2+b^2)^{u_i} (1+c^2+d^2)^{v_i}}, \quad \alpha_i, \beta_i, \gamma_i, \delta_i \geq 0, \quad \alpha_i + \beta_i \leq 2u_i, \quad \gamma_i + \delta_i \leq 2v_i.$$

It follows from Equation 20 that

$$\sup_{\mathbf{R}^4} |\phi| \leq \langle \phi \rangle, \quad \langle \phi \rangle = \sum_i |C_i| (1/2)^{\min(\alpha_i, \beta_i) + \min(\gamma_i, \delta_i)}. \quad (21)$$

Equation 21 is useful to us because it allows us to bound certain kinds of functions without having to evaluate them anywhere. We also note that if  $\phi$  is nice, then so is any iterated partial derivative of  $\phi$ . Indeed, the nice functions form a ring that is invariant under partial differentiation. This fact makes it easy to identify nice functions.

For any  $\phi : \mathbf{R}^n \rightarrow \mathbf{R}$  we define

$$\overline{M}_7(\psi) = \sup_{|J|=7} \overline{M}_J(\psi), \quad \overline{M}_J(\psi) = \sup_{\xi \in \mathbf{R}^n} |\partial_J(\psi)|. \quad (22)$$

We obviously have

$$M_7(\mathcal{E}_F) \leq \overline{M}_7(\mathcal{E}_F). \quad (23)$$

Recall that  $\widehat{p} = \Sigma^{-1}(p)$ , the inverse stereographic image of  $p$ . Define

$$f(a, b) = 4 - \|\widehat{(a, b)} - (0, 0, 1)\|^2 = \frac{4(a^2 + b^2)}{1 + a^2 + b^2}. \quad (24)$$

$$g(a, b, c, d) = 4 - \|\widehat{(a, b)} - \widehat{(c, d)}\|^2 = \frac{4(1 + 2ac + 2bd + (a^2 + b^2)(c^2 + d^2))}{(1 + a^2 + b^2)(1 + c^2 + d^2)}. \quad (25)$$

Notice that  $g$  is nice. Hence  $g^k$  is nice and  $\partial_I g^k$  is nice for any multi-index. That means we can apply Equation 21 to  $\partial_I g^k$ .

$\mathcal{E}_{G_k}$  is a 10-term expression involving 4 instances of  $f^k$  and 6 of  $g^k$ . However, each variable appears in at most 4 terms. So, as soon as we take a partial derivative, at least 6 of the terms vanish. Moreover,  $\partial_I f$  is a limiting case of  $\partial_I g$  for any multi-index  $I$ . From these considerations, we see that

$$\overline{M}_7(\mathcal{E}_{G_k}) \leq 4 \times \overline{M}_7(g^k). \quad (26)$$

The function  $\partial_I(g^k)$  is nice in the sense of Equation 21. Therefore

$$4 \times \overline{M}_7(g^k) \leq 4 \times \max_{|I|=7} \langle \partial_I g^k \rangle. \quad (27)$$

Using this estimate, and the Mathematica file `LemmaL23.m`, we get

$$\begin{aligned} \max_{k \in \{1, 2, 3, 4, 5, 6\}} \frac{(7 \times 2^{-18})^4}{4!} \times 4 \times \overline{M}_7(g^k) &\leq \frac{1}{1000}. \\ 2^{-5} \times \frac{(7 \times 2^{-18})^4}{4!} \times 4 \times \overline{M}_7(g^{10}) &\leq 2353. \end{aligned} \quad (28)$$

The bounds in Lemma 2.5 follow directly from Equations 26 - 28 and from the definitions of our functions.



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See Paper 0 for an extended bibliography.