

Notes 02/18/04

Rank of a matrix (Rank theorem)

The subspaces of $\mathbb{R}^2$:
 of dimension 0: $\{\vec{0}\}$ of dimension 1: all lines through origin
 of dimension 2: $\mathbb{R}^2$

for $\mathbb{R}^3$: $\{\vec{0}\}$, all lines through origin, all planes through origin, $\mathbb{R}^3$

Def: Rank of $A = \dim(\text{Ran } A) = \dim(\text{Col } A) = \text{Rank } A$

Computing basis in fundamental subspaces

$$\begin{pmatrix} 1 & 1 & 2 & 2 & 1 \\ 2 & 2 & 1 & 1 & 1 \\ 3 & 3 & 3 & 3 & 2 \\ 1 & 1 & -1 & -1 & 0 \end{pmatrix} \begin{matrix} -2r_1 \\ -3r_1 \\ -r_1 \end{matrix} \sim \begin{pmatrix} 1 & 1 & 2 & 2 & 1 \\ 0 & 0 & -3 & -3 & -1 \\ 0 & 0 & -3 & -3 & -1 \\ 0 & 0 & -3 & -3 & -1 \end{pmatrix} \begin{matrix} \\ -r_2 \\ -r_2 \end{matrix} \sim \begin{pmatrix} 1 & 1 & 2 & 2 & 1 \\ 0 & 0 & -3 & -3 & -1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

to compute basis in $\text{Col } A$:

Take pivot columns of A (non echelon)

$$\text{Col } A = \left(\begin{pmatrix} 1 \\ 2 \\ 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 3 \\ -1 \end{pmatrix} \right)$$

The basis in the row space: $\text{Col } A^T$:

Take pivot rows of echelon form of A and write vertically

$$\text{Col } A^T = \left(\begin{pmatrix} 1 \\ 1 \\ 2 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ -3 \\ -1 \end{pmatrix} \right)$$

Reduced Echelon:

$$\begin{pmatrix} 1 & 1 & 2 & 2 & 1 \\ 0 & 0 & -3 & -3 & -1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix} \begin{matrix} \times 3 \\ \\ \\ \end{matrix} \sim \begin{pmatrix} 3 & 3 & 6 & 6 & 3 \\ 0 & 0 & -3 & -3 & -1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix} \begin{matrix} +2r_2 \\ \\ \\ \end{matrix} \sim \begin{pmatrix} 3 & 3 & 0 & 0 & 1 \\ 0 & 0 & -3 & -3 & -1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix} \begin{matrix} \div 3 \\ \times 3 \\ \\ \end{matrix} \sim \begin{pmatrix} 1 & 1 & 0 & 0 & 1/3 \\ 0 & 0 & 1 & 1 & 1/3 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Solving: $x_5 = \text{free}$ $x_4 = \text{free}$ $x_3 = -x_4 - \frac{x_5}{3}$ $t_2 = \text{free}$

$x_1 = -x_2 - \frac{x_5}{3}$ This is $\text{Ker } A$
 a basis

$$\begin{pmatrix} -x_2 - \frac{x_5}{3} \\ x_2 \\ -x_4 - \frac{x_5}{3} \\ x_4 \\ x_5 \end{pmatrix} = x_2 \begin{pmatrix} -1 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} 0 \\ 0 \\ -1 \\ 1 \\ 0 \end{pmatrix} + x_5 \begin{pmatrix} -1/3 \\ 0 \\ -1/3 \\ 0 \\ 1 \end{pmatrix} \quad \text{these three vectors}^{(3)} \\ \text{form a basis} \\ \text{in Ker } A$$

to find $\text{Ker } A^T$ you must repeat this process with A^T

Rank Theorem: $\text{Rank } A = \text{Rank } A^T$

if $A = m \times n$

$$\text{Rank } A + \dim \text{Ker } A = n \quad \text{Rank } A + \dim \text{Ker } A^T = m$$