

Addendum to  
Logarithmic Geometry and Moduli  
Tropical Geometry and Moduli Spaces  
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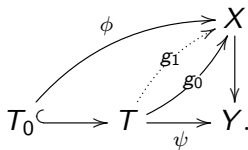
Brown University

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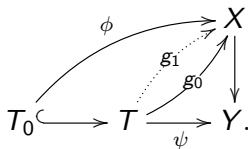
# Differentials

Say  $T_0 = \operatorname{Spec} k$  and  $T = \operatorname{Spec} k[\epsilon]/(\epsilon^2)$ , and consider a morphism  $X \rightarrow Y$ .

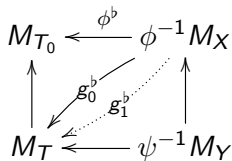
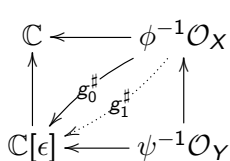
We contemplate the following diagram:



# Differentials (continued)



This translates to a diagram of groups and a diagram of monoids



## Differentials (continued)

$$\begin{array}{ccc}
 \mathbb{C} & \xleftarrow{\quad} & \phi^{-1}\mathcal{O}_X \\
 \uparrow & \swarrow g_0^\sharp & \uparrow \\
 \mathbb{C}[\epsilon] & \xleftarrow{\quad} & \psi^{-1}\mathcal{O}_Y
 \end{array}$$

(Dotted arrow from  $\mathbb{C}[\epsilon]$  to  $\phi^{-1}\mathcal{O}_X$  labeled  $g_1^\sharp$ )

$$\begin{array}{ccc}
 M_{T_0} & \xleftarrow{\phi^b} & \phi^{-1}M_X \\
 \uparrow & \swarrow g_0^b & \uparrow \\
 M_T & \xleftarrow{\quad} & \psi^{-1}M_Y
 \end{array}$$

(Dotted arrow from  $M_T$  to  $\phi^{-1}M_X$  labeled  $g_1^b$ )

The difference  $g_1^\sharp - g_0^\sharp$  is a **derivation**  $\phi^{-1}\mathcal{O}_X \xrightarrow{d} \epsilon\mathbb{C} \simeq \mathbb{C}$   
 It comes from the sequence

$$0 \rightarrow J \rightarrow \mathcal{O}_{\underline{I}} \rightarrow \mathcal{O}_{\underline{I}_0} \rightarrow 0.$$

The multiplicative analogue

$$1 \rightarrow (1 + J) \rightarrow \mathcal{O}_{\underline{I}}^\times \rightarrow \mathcal{O}_{\underline{I}_0}^\times \rightarrow 1$$

means, if all the logarithmic structures are integral,

$$1 \rightarrow (1 + J) \rightarrow M_T \rightarrow M_{T_0} \rightarrow 1.$$

## Differentials (continued)

$$\begin{array}{ccc}
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 \uparrow & \swarrow g_0^\# & \uparrow \\
 \mathbb{C}[\epsilon] & \xleftarrow{\quad} & \psi^{-1}\mathcal{O}_Y
 \end{array}
 \qquad
 \begin{array}{ccc}
 M_{T_0} & \xleftarrow{\phi^b} & \phi^{-1}M_X \\
 \uparrow & \swarrow g_0^b & \uparrow \\
 M_T & \xleftarrow{\quad} & \psi^{-1}M_Y
 \end{array}$$

$$1 \rightarrow (1 + J) \rightarrow M_T \rightarrow M_{T_0} \rightarrow 1$$

means that we can take the “difference”

$$g_1^b(m) = (1 + D(m)) + g_0^b(m).$$

Namely  $D(m) = “g_1^b(m) - g_0^b(m)” \in J$ .

## Key properties:

- $D(m_1 + m_2) = D(m_1) + D(m_2)$
- $D|_{\psi^{-1}M_Y} = 0$
- $\alpha(m) \cdot D(m) = d(\alpha(m)),$

in other words,

$$D(m) = d \log (\alpha(m)),$$

which justifies the name of the theory.

### Definition

A **logarithmic derivation**:

$$\begin{aligned} d : \mathcal{O} &\rightarrow J; \\ D : M &\rightarrow J \end{aligned}$$

satisfying the above.

# Logarithmic derivations

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satisfying the above.

The universal derivation:

$$d : \mathcal{O} \rightarrow \Omega_{\underline{X}/\underline{Y}}^1 = \mathcal{O} \otimes_{\mathbb{Z}} \mathcal{O} / \text{relations}$$

The universal logarithmic derivation takes values in

$$\Omega_{X/Y}^1 = \left( \Omega_{\underline{X}/\underline{Y}}^1 \oplus (\mathcal{O} \otimes_{\mathbb{Z}} M^{\text{gp}}) \right) / \text{relations}$$

# Prestable curves

A *prestable  $n$ -marked curve*  $C/S$  is a flat, proper morphism with connected reduced fibers of dimension 1, along with disjoint sections  $s_i : S \rightarrow C$  for  $i = 1, \dots, n$  in the smooth locus of  $C/S$ . We require all fibers have at most nodes as singularities.

We denote by  $p_i$  the images of  $s_i$ .



# Stable curves

## Definition

A prestable curve  $C/S$  is *stable* if for every geometric fiber the automorphism group  $\text{Aut}(C_0, p_1, \dots, p_n)$  is finite.

## Definition

A prestable curve  $C/S$  is *stable* if for every irreducible component  $C'$  of the normalization  $C^\nu$  of a geometric fiber

- If  $C' \simeq \mathbb{P}^1$  then  $C'$  contains at least 3 special points.
- If  $g(C') = 1$  then  $C'$  contains at least 1 special point.

## Definition

A prestable curve  $C/S$  is *stable* if  $\omega_{C/S}(\sum p_i)$  is  $\pi$ -ample.

## Proposition

*All three definitions coincide*

# Moduli of stable curves

## Theorem (Deligne–Mumford–Knudsen)

*Stable curves form a proper, smooth Deligne–Mumford stack  $\overline{\mathcal{M}}_{g,n}$  over  $\mathbb{Z}$  with projective coarse moduli space. The universal curve is  $\overline{\mathcal{M}}_{g,n+1}$ .*

What is a moduli problem?

We all learned about “representable functors”

These work sometimes, but often replaced by “coarse moduli spaces”, a compromise

The reason is that moduli functors dance around the problem instead of facing it directly - the problem of automorphisms.

# Moduli as Categories

The object of interest are **families**  $X \rightarrow S$ .

First and foremost: Families can be **pulled back**.

So they form a **category**  $\mathcal{M}$ , arrows being cartesian diagrams

$$\begin{array}{ccc} X_1 & \longrightarrow & X_2 \\ \downarrow & & \downarrow \\ S_1 & \longrightarrow & S_2 \end{array}$$

With the forgetful functor  $(X \rightarrow S) \mapsto S$  this is a **category fibered in groupoids**.

# Moduli as Stacks

Second, both maps between families in  $\mathcal{M}$  and the families themselves can be **glued**:

If  $f_i : C_1|_{U_i} \rightarrow C_2|_{U_i}$  are maps between families over  $S$  which agree on  $U_i \cap U_j$ , then there is a glued map  $f$ .

If  $C_i$  are families over  $U_i$  and  $\phi_{i,j}$  are isomorphisms of  $C_i|_{U_i \cap U_j}$  with  $C_j|_{U_i \cap U_j}$  which are compatible on triple intersections then there is a glued family  $C \rightarrow S$ .

This makes the category  $\mathcal{M}$  into a **stack**.

# Algebraic stacks

What makes a stack algebraic is that it is approximated by a scheme.

A scheme  $Z$  defines a stack which is the category  $\mathcal{S}ch/Z$ .

A map  $Z \rightarrow \mathcal{M}$  is **smooth** if it provides geometric objects of  $\mathcal{M}$  with **versal deformation spaces**

A stack is algebraic essentially if it admits a smooth map from a scheme.

For instance,  $\overline{\mathcal{M}}_g$  is an algebraic stack since it has a smooth map from the Hilbert scheme of 3-canonically embedded stable curve.

# Artin's criteria

Michael Artin listed criteria for a moduli problem to be an algebraic stack  
Most of them often apply by general nonsense (though I have met surprises!)

Often the crucial criterion is the existence of versal deformation spaces.

# Stable maps

A **stable map** is a diagram

$$\begin{array}{ccc} C & \xrightarrow{f} & X \\ \downarrow \pi & & \\ S & & \end{array} \quad \begin{array}{c} \nearrow s_i \\ \searrow \end{array}$$

where

- $(C/S, s_i)$  is a prestable curve, and
- in fibers  $\text{Aut}(C_s \rightarrow X, s_i)$  is finite.



# Gromov–Witten theory

We want to count curves on  $X$  of class  $\beta \in H_2(X, \mathbb{Z})$  meeting cycles  $\Gamma_1, \dots, \Gamma_n$  corresponding to cohomology classes  $\gamma_i$ . For instance: lines through  $p_1, p_2$ .

Kontsevich's method: the moduli of stable maps  $M := \overline{\mathcal{M}}_{g,n,\beta}(X)$  is a Deligne–Mumford stack with projective coarse moduli space.

There are evaluation maps

$$\begin{array}{ccc} M & \xrightarrow{e_i} & X \\ (C/S, p_i) & \mapsto & f(p_i) \end{array}$$

and one defines the *Gromov–Witten invariants*

$$\langle \gamma_1 \cdots \gamma_n \rangle_{g,\beta}^X = \int_{[M]^{\text{vir}}} e_1^* \gamma_1 \cdots e_n^* \gamma_n.$$

# Gromov–Witten theory (continued)

The mysterious part is  $[M]^{\text{vir}}$ . This is there to make this a homological and deformation invariant.

This is akin to the fact that the number of lines through  $p_1, p_2$ , namely the intersection number of the locus of lines through  $p_1$  with the locus of lines through  $p_2$ , is 1, whether or not  $p_1 = p_2$ .

In order to define this one uses a *perfect obstruction theory*. In this case it is given by  $R^\bullet \pi_* f^* T_X$ , represented by a 2-term complex on  $S$ .