# Generalized Dynamical systems: Preliminary Report

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# Dynamical Systems

#### Definition

We say a pair (S, f) is a (discrete) dynamical system when  $f : S \to S$  is a self map.

$$P \xrightarrow{f} f(P) \xrightarrow{f} f(f(P))$$

#### Definition

We define the orbit of P under f to be

$$\mathcal{O}_f(P) := \{P, f(P), f^2(P), \cdots, f^m(P), \cdots\}$$

where  $f^m$  is m-th iterate of f.

### Definition (Dynamical Classification)

We say a point  $P \in S$  is fixed if  $\mathcal{O}_f(P) = \{P\}$ , periodic if  $f^m(P) = P$  for some  $m \ge 1$  and preperiodic if  $\mathcal{O}_f(P)$  is finite.

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#### Remark

We can study properties of preperiodic points by comparing information of P and f(P). For example, is

$$\deg f \cdot h(P) - h(f(P))$$

bounded?

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### Theorem (Northcott)

### Let $\phi : \mathbb{P}^n(\overline{\mathbb{Q}}) \to \mathbb{P}^n(\overline{\mathbb{Q}})$ be a morphism of degree d. Then,

 $h(\phi(P)) > d \cdot h(P) + O(1).$ 

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### Corollary

If  $f: \mathbb{P}^n \to \mathbb{P}^n$  is a rational map with at least ont indeterminacy point, then  $\frac{1+\epsilon}{\det f}h(f(P))$  cannot be an upper bound of h(P).

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### Theorem (Weak Version)

Let  $\phi : \mathbb{A}^n(\overline{\mathbb{Q}}) \to \mathbb{A}^n(\overline{\mathbb{Q}})$  be a polynomial map. If

 $h(\phi(P)) > (1+\epsilon) \cdot h(P) + O(1)$ 

holds for all  $P \in \mathbb{A}^n(\overline{\mathbb{Q}})$ , then the set of preperiodic points is of bounded height.

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Northcott's theorem works only for polarizable endomorphisms, like endomorphisms on projective spaces.

Theorem (Silverman, L.)

Let  $f_1, \dots, f_k : \mathbb{A}^n \to \mathbb{A}^n$  be jointly regular family of polynomial maps (whose meromorphic extensions on  $\mathbb{P}^n$  share no indeterminacy point.) Then

$$\sum_{i=1}^{k} \frac{1}{\deg f_i} h(f_i(P)) > (1+r) h(P) + O(1).$$

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#### Corollary

Let  $M = \langle f_1, \cdots, f_k \rangle$  be a monoid generated by  $f_1, \cdots, f_k$ . Then  $\mathsf{Preper}(M) := \left\{ P \in \mathbb{A}^n(\overline{\mathbb{Q}}) \mid \{f(P) \mid f \in M\} \right\}$ 

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Proposition

Let  $M = \langle f_1, \cdots, f_k \rangle$  be a monoid generated by  $f_1, \cdots, f_k$ . Then

$$\mathsf{Preper}(M) \subset \bigcap_{i=1}^k \mathsf{Preper}(f_i)$$

is of bounded height

#### Remark

Let  $M = \langle f, g \rangle$  be a monoid generated by f, g. Then 'M-periodic'  $(P \in \operatorname{Preper}(M))$  is quite strong condition.

#### Example

Let S be a K3-surface with two noncommuting involutions,  $\iota_1, \iota_2$ . Then, Preper $(\iota_j) = S$  while Preper $(\langle \iota_1, \iota_2 \rangle)$  is of bounde height.

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#### Question

Let  $f, g : \mathbb{A}^n \to \mathbb{A}^n$  be polynomial maps whose meromorphic extensions share no indeterminacy point. Is there any way to study

 $\operatorname{Preper}(f) \cap \operatorname{Preper}(g)$ ?

### Theorem (Baker-DeMarco, Yuan-Zhang)

Let  $\phi, \psi : \mathbb{P}^n \to \mathbb{P}^n$  be endomorphisms of degree at least 2. Then  $|\operatorname{Preper}(\phi) \cap \operatorname{Preper}(\psi)| = \infty$  if and only if  $\operatorname{Preper}(\phi) = \operatorname{Preper}(\psi)$ .

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### Theorem (L.-Ye)

Let f, g be polynomial maps. If  $f \circ g = g \circ f$  and Preper(f) is of bounded height, then  $Preper(f) \subset Preper(g)$ .

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Let f, g be polynomial maps. If  $f \circ g = g \circ f$  and Preper(f) is of bounded height, then  $Preper(f) \subset Preper(g)$ .

#### Question

Is there any f, g such that  $Preper(f) \cap Preper(g)$  is of bounded height while Preper(f), Preper(g) are unbounded?

# **Dynamics Revisited**

#### Definition

Let (S, f) be a dynamical system. We consider the monoid generated by f,

$$M_f := \langle f \rangle = \{ Id, f, f^2 \cdots \}.$$

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# Dynamics Revisited

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$$M_f := \langle f \rangle = \{ Id, f, f^2 \cdots \}.$$

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#### Definition

We define the orbit of P under  $M_f$ -action to be

$$\mathcal{O}_{M_f}(P) := \{f(P) \mid f \in M_f\}.$$

#### Definition

We say a point  $P \in S$  is preperiodic if  $\mathcal{O}_f(P)$  is finite.

# Action of Monoid

#### Definition

Let M be a monoid consisting of self maps on S:

$$M:=\langle f_1,\cdots,f_k\rangle.$$

Then we say (S, M) is a dynamical system with several maps.

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## Action of a Set of self maps

#### Definition

Let  $\mathcal{M}$  be a set of self maps on S:

$$\mathcal{M} := \{f_i : S \to S \mid i \in I\}.$$

Then we say  $(S, \mathcal{M})$  is a dynamical system.

#### Definition

We define the orbit of P to be

$$\mathcal{O}_{\mathcal{M}}(P) := \{ f(P) \mid f \in \mathcal{M} \}.$$

#### Definition

We say a point  $P \in S$  is preperiodic if  $\mathcal{O}_{\mathcal{M}}(P)$  is finite.

# Action of a Set of maps

#### Definition

Let  $\mathcal{F}$  be a set consisting of maps from T to S:

$$\mathcal{F}:=\{f:T\to S\}.$$

Then we say  $(T, S, \mathcal{F})$  a dynamical system.

#### Definition

We define the orbit of P under  $\mathcal{F}$  to be

$$\mathcal{O}_{\mathcal{F}}(P) := \{f(P) \mid f \in \mathcal{F}\} \subset S.$$

#### Definition

We say a point  $P \in T$  is preperiodic if  $\mathcal{O}_{\mathcal{F}}(P)$  is finite.

### Examples : Isogenies

#### Example

Let  $E_1, E_2$  be elliptic curves defined over  $\overline{\mathbb{Q}}$  and let  $\mathcal{F} = \text{Hom}(E_1, E_2)$  be the set of isogenies between  $E_1$  and  $E_2$ . Then

 $\mathsf{Preper}(\mathcal{F}) = (E_1)_{tor}.$ 

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 $\mathsf{Preper}(\mathcal{F}) = (E_1)_{tor}.$ 

#### Example

Let  $\phi, \psi$  be isogeneous Drinfeld module and let  $\mathcal{F} = \text{Hom}(\phi, \psi)$  be the sets of isogenies between  $\phi$  and  $\psi$ . Then,

$$\mathsf{Preper}(\mathcal{F}) = (\phi)_{tor}.$$

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# $Preper(f) \cap Preper(g)$ and Product map

#### Definition

Let  $f, g : \mathbb{A}^n \to \mathbb{A}^n$  be polynomial maps. We define

 $f \times g : \mathbb{A}^n \to \mathbb{A}^{2n}, \quad P \mapsto (f(P), g(P)).$ 

# $Preper(f) \cap Preper(g)$ and Product map

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#### Proposition

$$\operatorname{Preper}(f) \cap \operatorname{Preper}(g) = \operatorname{Preper}(f \times g).$$

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#### Proposition

$$\operatorname{Preper}(f) \cap \operatorname{Preper}(g) = \operatorname{Preper}(f \times g).$$

#### Proposition

Let f, g have the same degree. Then f and g are jointly regular if  $f \times g$  extends continuously on  $\mathbb{P}^n$ .

# Application to Rational dynamical systems

#### Proposition

Let  $(\mathbb{P}^n, \mathbb{P}^{2n}, \{F_k := f^k \times g^k\})$  be the generalized dynamical system, and let  $G : \mathbb{P}^{2n} \to \mathbb{P}^{2n}$  be the meromorphic extension of

$$f \cdot g : \mathbb{A}^{2n} \to \mathbb{A}^{2n}, \quad (P,Q) \mapsto (f(P),g(Q)).$$

Then



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# Application to Rational dynamical systems

#### Theorem

Let  $f : \mathbb{A}^n \to \mathbb{A}^n$  be a regular polynomial automorphism and let  $f^{-1}$  be its inverse. Then there is an integer  $1 \le l \le n-1$  such that

$$\deg f' = \deg(f^{-1})^{n-l}.$$

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Theorem (Kawaguchi)

Let 
$$\mathcal{F} := \{F_i = f^{li} \times f^{-(n-l)i} \mid i = 1, 2, \cdots\}$$
. Then

$$\widehat{h}(P) := \lim_{i \to \infty} \frac{1}{\deg F_i} h(F_i(P))$$

converges.

#### Proposition

$$\mathsf{Preper}(f) = \mathsf{Preper}(f') \cap \mathsf{Preper}(f^{-1}) = \mathsf{Preper}(\mathcal{F})$$

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#### Introduction

# Generalization

### Theorem (L., In progress)

Let  $f, g : \mathbb{A}^n \to \mathbb{A}^n$  be polynomial maps such that

- algebraically stable,
- jointly regular,
- $h(f^2(P)) > \deg(g \circ f)h(P) O(1)$  and
- $h(g^2(P)) > deg(f \circ g)h(P) O(1).$

Then the canonical height of  $\mathcal{F} := \{f^i \times g^i \mid i = 1, 2, 3, \cdots\},\$ 

$$\widehat{h}_{\mathcal{F}}(P) := \lim_{i \to \infty} d^{-i} h((f^i \times g^i)(P))$$

is well-defined: it is equivalent to the Weil height on  $\mathbb{P}^n$  and  $\hat{h}_{\mathcal{F}}(P) = 0$  if and only if  $P \in \operatorname{Preper}(f) \cap \operatorname{Preper}(g)$ .

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# General Theorem

### Theorem (L., In progress)

Let F be a countable set of morphisms between projective spaces defined over a number field K:

$$\mathcal{F}:=\{f_i:\mathbb{P}^n\to\mathbb{P}^N\}.$$

Suppose

$$\left| d_i^{-1} h(f_i(P)) - d_{i+1}^{-1} h(f_{i+1}(P)) \right|, \quad d_i = \deg f_i$$

converge uniformly. Then we can define the canonical height

$$\widehat{h}_{\mathcal{F}}(P) := \lim_{i \to \infty} \frac{1}{d_i} h(f_i(P))$$

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#### Corollary

The set of preperiodic point is of bounded height.

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Introduction

# Appreciation

Thanks for your hearing!

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