

Carleson measures and elliptic boundary value problems

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Abstract. In this article, we highlight the role of Carleson measures in elliptic boundary value problems, and discuss some recent results in this theory. The focus here is on the Dirichlet problem, with measurable data, for second order elliptic operators in divergence form. We illustrate, through selected examples, the various ways Carleson measures arise in characterizing those classes of operators for which Dirichlet problems are solvable with classical non-tangential maximal function estimates.

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1. Introduction

Measures of Carleson type were introduced by L. Carleson in [9] and [10] to solve a problem in analytic interpolation, via a formulation that exploited the duality between Carleson measures and non-tangential maximal functions (defined below). Carleson measures have since become one of the most important tools in harmonic analysis, playing a fundamental role in the study of singular integral operators in particular, through their connection with BMO , the John-Nirenberg space of functions of bounded mean oscillation. We aim to describe, through some specific examples, the ubiquitous role of measures of this type in the theory of boundary value problems, especially with regard to sharp regularity of “elliptic” measure, the probability measure arising in the Dirichlet problem for second order divergence form elliptic operators. Perhaps the first connection between Carleson measures and boundary value problems was observed by C. Fefferman in [18], namely that every BMO function on \mathbb{R}^n has a harmonic extension to the upper half space \mathbb{R}_+^{n+1} which satisfies a certain Carleson measure condition. This established an important link between solutions to boundary value problems for the Laplacian and the function space BMO . It may be surprising to see the extent to which this link exists for operators other than the Laplacian, and in the context of more general domains.

In order to define Carleson measures, we introduce the geometric notion of a Carleson region above a cube. If $Q \subset \mathbb{R}^n$ is a cube with side length $l(Q)$ set $T_Q = \{(x, t) \in \mathbb{R}_+^{n+1} : x \in Q, 0 < t < l(Q)\}$, a cube sitting above its boundary face Q . (The notation T_Q comes from an equivalent formulation involving “tents” over cubes.)

Definition 1.1. The measure $d\mu$ is a Carleson measure in the upper half space \mathbb{R}_+^{n+1} if there exists a constant C such for all cubes $Q \subset \mathbb{R}^n$, $\mu(T(Q)) < C|Q|$, where $|Q|$ denotes the

35 Lebesgue measure of the cube Q .

36 The classical theory of harmonic functions in the upper half space, or the ball, considers
 37 solutions to the Dirichlet problem with measurable, specifically L^p , data. Given a function
 38 $f \in L^p(\mathbb{R}^n)$, the convolution of f and the Poisson kernel is an absolutely convergent integral
 39 when $1 < p < \infty$, giving meaning to the harmonic extension $u(x, t)$ of an L^p function.
 40 And the sense in which this extension u converges to its boundary values is “non-tangential”.
 41 That is, for every $x_0 \in \mathbb{R}^n$, one can define a non-tangential approach region to x_0 , $\Gamma_a(x_0) =$
 42 $\{(x, t) : |x - x_0| < at\}$. Then if $u(x, t)$ is the Poisson extension of $f \in L^p(\mathbb{R}^n)$, for
 43 almost every x_0 , $u(x, t) \rightarrow f(x_0)$ as $(x, t) \in \Gamma_a(x_0)$ approaches x_0 . Moreover, one has
 44 a non-tangential maximal function estimate, specified below, which yields solvability and
 45 uniqueness of this L^p Dirichlet problem.

46 The result of C. Fefferman about harmonic functions, which proved to be a powerful tool
 47 in harmonic function theory, is this: if $u(x, t)$ is the Poisson extension of $f \in BMO$, then
 48 $d\mu = t|\nabla u|^2 dx dt$ is a Carleson measure in the upper half space \mathbb{R}_+^{n+1} . The converse also
 49 holds for functions that are not too large at ∞ .

50 In the last several decades, there have been many significant developments in the theory of
 51 boundary value problems with data in L^p spaces, for harmonic (or poly-harmonic) functions
 52 defined in very general domains, and for solutions to second order divergence form (and
 53 higher order) elliptic operators with non-smooth coefficients. We will highlight a selection
 54 of these developments in which the role of Carleson measures has been decisive.

55 For simplicity of notation, we will formulate the results in the upper half plane, \mathbb{R}_+^{n+1} ,
 56 but in fact these results are more naturally formulated on Lipschitz domains - see the cited
 57 references for this generality. In some cases, the perturbation results hold in more general
 58 (chord-arc) domains: [41–43].

59 2. Definitions and background

A divergence form elliptic operator

$$L := -\operatorname{div} A(x)\nabla,$$

60 defined in \mathbb{R}^{n+1} , where A is a (possibly non-symmetric) $(n+1) \times (n+1)$ matrix of bounded
 61 real coefficients, satisfies the uniform ellipticity condition

$$\lambda|\xi|^2 \leq \langle A(x)\xi, \xi \rangle := \sum_{i,j=1}^{n+1} A_{ij}(x)\xi_j\xi_i, \quad \|A\|_{L^\infty(\mathbb{R}^n)} \leq \lambda^{-1}, \quad (2.1)$$

for some $\lambda > 0$, and for all $\xi \in \mathbb{R}^{n+1}$, $x \in \mathbb{R}^n$. As usual, the divergence form equation is
 interpreted in the weak sense, i.e., we say that $Lu = 0$ in a domain Ω if $u \in W_{loc}^{1,2}(\Omega)$ and

$$\int A\nabla u \cdot \nabla \Psi = 0,$$

62 for all $\Psi \in C_0^\infty(\Omega)$.

63 For notational simplicity, Ω will henceforth be the half-space $\mathbb{R}_+^{n+1} := \{(x, t) \in \mathbb{R}^n \times$
 64 $(0, \infty)\}$ even though the results are more naturally formulated on Lipschitz domains. See the
 65 cited references for this generality.

66 The solvability of the Dirichlet problem for L with data in $L^p(dx)$ is a function of a
 67 precise relationship between the elliptic measure ω associated to L and Lebesgue measure.

68 The elliptic measure associated to L is analogous to the harmonic measure: it is the
 69 representing measure for solutions to L with continuous data on the boundary.

70 **Definition 2.2.** A non-negative Borel measure ω defined on \mathbb{R}^n is said to belong to the class
 71 A_∞ if there are positive constants C and θ such that for every cube Q , and every Borel set
 72 $F \subset Q$, we have

$$\omega(F) \leq C \left(\frac{|F|}{|Q|} \right)^\theta \omega(Q). \quad (2.3)$$

73 A real variable argument shows that a measure, ω , belongs to $A_\infty(dx)$ if and only if it is
 74 absolutely continuous with respect to Lebesgue measure and there is an exponent $q > 1$ such
 75 that the Radon-Nikodym derivative $k := d\omega/dx$ satisfies

$$\left(\int_Q k(x)^q dx \right)^{1/q} \leq C \int_Q k(x) dx, \quad (2.4)$$

76 uniformly for every cube Q . This property is called a reverse-Hölder estimate of order q .

77 If ω is the elliptic measure associated to an operator L , then the existence of such a $q > 1$
 78 is, in turn, equivalent to the solvability of the Dirichlet problem for L with boundary data
 79 $f \in L^p$ (for p dual to q), in the sense of non-tangential convergence and non-tangential
 80 estimates on the boundary. These non-tangential estimates are expressed in terms of L^p
 81 bounds on two classical operators associated to solutions: the square function

$$S^\alpha(u)(x) := \left(\iint_{|x-y| < \alpha t} |\nabla u(y, t)|^2 \frac{dy dt}{t^{n-1}} \right)^{1/2}, \quad (2.5)$$

82 and the non-tangential maximal function

$$N_*^\alpha(u)(x) := \sup_{(y, t): |x-y| < \alpha t} |u(y, t)| \quad (2.6)$$

83 Precisely, the elliptic measure satisfies a reverse Hölder estimate of order q if and only if the
 84 following L^p Dirichlet problem is solvable, for p dual to the exponent q :

$$\begin{cases} Lu = 0 \text{ in } \mathbb{R}_+^{n+1} \\ \lim_{t \rightarrow 0} u(\cdot, t) = f \text{ in } L^p(\mathbb{R}^n) \text{ and n.t.} \\ \|N_*(u)\|_{L^p(\mathbb{R}^n)} < C \|f\|_p. \end{cases} \quad (D_p)$$

85 Here, the notation “ $u \rightarrow f$ n.t.” means that $\lim_{(y, t) \rightarrow (x, 0)} u(y, t) = f(x)$, for a.e. $x \in \mathbb{R}^n$,
 86 where the limit runs over $(y, t) \in \Gamma(x) := \{(y, t) \in \mathbb{R}_+^{n+1} : |y - x| < t\}$. The constant C
 87 depends only on ellipticity and dimension.

88 We will usually suppress the dependence on the aperture α , since the choice of aperture
 89 does not affect the range of available L^p estimates.

90 Solutions to L are said to satisfy De Giorgi-Nash-Moser bounds when the following local
 91 Hölder continuity estimates hold. Assume that $Lu = 0$ in \mathbb{R}_+^{n+1} in the weak sense and

92 $B_{2R}(X) \subset \mathbb{R}_+^{n+1}$, $X \in \mathbb{R}_+^{n+1}$, $R > 0$. Then

$$|u(Y) - u(Z)| \leq C \left(\frac{|Y - Z|}{R} \right)^\mu \left(\int_{B_{2R}(X)} |u|^2 \frac{dx}{|B_{2R}(X)|} \right)^{\frac{1}{2}}, \quad \text{for all } Y, Z \in B_R(X),$$

(2.7)

93 for some constants $\mu > 0$ and $C > 0$. In particular, one can show that for any $p > 0$

$$|u(Y)| \leq C \left(\int_{B_{2R}(X)} |u|^p \frac{dx}{|B_{2R}(X)|} \right)^{\frac{1}{p}}, \quad \text{for all } Y, Z \in B_R(X).$$

(2.8)

94 The De Giorgi-Nash-Moser bounds always hold when the coefficients of the underlying
 95 equation are real [14, 40, 44], and the constants depend quantitatively only upon ellipticity and
 96 dimension. We will assume that for the complex equations considered later on (t -independent
 97 coefficients), that solutions satisfy the De Giorgi-Nash-Moser bounds, which may not in
 98 general obtain ([25, 39]).

99 3. Perturbations of elliptic operators

100 In this section, we briefly discuss some background which will motivate certain topics treated
 101 later, and for which Carleson measure estimates have played a decisive role.

102 In the upper half space, the Dirichlet problem is uniquely solvable for the Laplacian when
 103 the boundary data belongs to $L^p(dx)$, $1 < p < \infty$, in the sense that the Poisson extension
 104 $u(x, t)$ of f satisfies the estimate $\|N(u)\|_p \leq C\|f\|_p$. The same holds for solutions to
 105 $L := -\operatorname{div} A(x)\nabla$, when coefficients of A are smooth, or even just C^1 ([20]). However,
 106 without some regularity assumptions, the elliptic measure associated to L may be singular
 107 with respect to Lebesgue measure ([7]), and no estimate of this type will hold.

108 Many interesting examples of elliptic operators in divergence form arise as pullbacks of
 109 the Laplacian from a change of variable. From the viewpoint of complex function theory, it is
 110 natural to consider boundary behavior of harmonic functions in domains other than the ball or
 111 the upper half space. One approach to solving boundary value problems for harmonic func-
 112 tions in, say, a domain above a graph, is to invoke a change variables, mapping the harmonic
 113 function v to a solution u of a new divergence form elliptic operator, L . Thus, if the domain
 114 were bounded by a smooth curve, an appropriate change of variables results in a real sym-
 115 metric divergence form operator with smooth coefficients. But if the boundary of the domain
 116 is not regular, the resulting operator has non-smooth coefficients, and the problem has not
 117 become easier. For a variety of reasons, including scale invariance and naturally arising geo-
 118 metric constructions, attention focused on the class of Lipschitz domains. In [12], Dahlberg
 119 showed that harmonic measure on any Lipschitz domain belonged to A_∞ with respect to the
 120 surface measure on the boundary. In fact, he showed that the L^2 Dirichlet problem, D_2 ,
 121 was solvable, but that D_p was not uniformly solvable on all Lipschitz domains when $p < 2$.
 122 More recently, the theory has developed to include a body of results for non-graph domains
 123 described by geometric conditions (non-tangentially accessible, chord-arc, Reifenberg flat.).

124 Consider the following example of a particularly straightforward change of variables. The
 125 domain is the region above a graph $t = \phi(x)$, where $\phi(x)$ is Lipschitz. The change of

126 variables, $(x, t) \rightarrow (x, t - \phi(x))$, “flattens” it to the upper half space. Under this change of
 127 variable, from the Lipschitz domain to \mathbb{R}_+^{n+1} , harmonic functions are mapped to solutions of a
 128 symmetric elliptic divergence form operator L whose coefficients involve the Jacobian of this
 129 transformation and are therefore merely bounded and measurable. However, the coefficients
 130 have one redeeming feature: they are independent of the transverse variable t . Jerison and
 131 Kenig (JK) discovered how to put Dahlberg’s result in a larger context when they showed that
 132 D_2 was solvable in \mathbb{R}_+^{n+1} for all elliptic symmetric t -independent operators. Their well known
 133 result was based on an L^2 identity (a “Rellich” identity) which decisively used these three
 134 properties of the (real) operator L : symmetry, ellipticity, t -independence of the coefficients.
 135 Specifically, if $Lu = 0$, and \vec{e} is the unit normal at the boundary of \mathbb{R}_+^{n+1} , then

$$\operatorname{div}(A\nabla u \cdot \nabla u \vec{e}) = 2 \operatorname{div}(D_{n+1}(u)A\nabla u). \quad (3.1)$$

136 Integrating this identity and applying the divergence theorem results in a boundary identity
 137 that can be used to show that the normal and tangential derivatives of a solution are compa-
 138 rable in L^2 norm. This boundary identity scales to show that the elliptic measure is not only
 139 absolutely continuous but satisfies a reverse Hölder condition of order two. Therefore, the
 140 Dirichlet problem with data in L^2 is solvable.

141 Many subsequent advances in the theory of boundary value problems for real symmetric
 142 elliptic equations and systems were based on variants of this Rellich identity.

143 The theory of perturbations of elliptic operators arose from several separate points of
 144 view. One source was T. Kato’s interest in the analyticity of square roots of complex sec-
 145 ond order divergence form elliptic operators, which led to a question about analyticity of
 146 small L^∞ perturbations of self-adjoint elliptic operators. There is extensive literature on
 147 this subject which we are not going to delve into in this article. (See [4] for the solution to
 148 Kato’s conjecture.) Another, and related, source of interest, stemmed from the the discov-
 149 ery that independence in the t variable in \mathbb{R}_+^{n+1} (or similarly, of the radial variable in the
 150 unit ball) endows the elliptic measure ω with good properties. One may then try to relax
 151 this condition and understand more precisely the relationship between the smoothness that
 152 is required in the t direction and good estimates for elliptic measure. This was the approach
 153 taken in [13, 19, 30, 34], and see also [2, 3, 26] for later developments in perturbation theory.
 154 Dahlberg, [13], imposed a “vanishing” condition on the Carleson discrepancy between the
 155 coefficients and proved strong results about preservation of reverse Hölder estimates for the
 156 elliptic measure. An entirely new approach to the vanishing Carleson condition was taken in
 157 [2] that provided major extensions of the perturbation theory to complex coefficient opera-
 158 tors.

159 Consider an operator $L_1 := -\operatorname{div} A(x, t)\nabla$, in \mathbb{R}_+^{n+1} , regarded as a perturbation of $L_0 :=$
 160 $-\operatorname{div} A(x, 0)\nabla$, and suppose one asks for some quantitative conditions on $|A(x, t) - A(x, 0)|$
 161 that yield good estimates for the elliptic measure ω_{L_1} . More generally, one can formulate the
 162 question as follows: what are the optimal conditions on the difference of the coefficients such
 163 that the perturbation L_1 of a “good” operator L_0 , not necessarily t -independent, also satisfies
 164 good estimates for solvability of a boundary value problem. In [19], optimal conditions were
 165 found.

166 **Theorem 3.2.** *Let $L_0 = \operatorname{div} A_0\nabla$ and $L_1 = \operatorname{div} A_1\nabla$ and define the disagreement function*
 167 *$a(x, t)$ by*

$$a(x, t) = \sup\{|A_0(y, s) - A_1(y, s)| : |y - x| < t, t/2 < s < 2t\}. \quad (3.3)$$

168 *If $a^2(x, t)t^{-1}dxdt$ is a Carleson measure, then $\omega_{L_0} \in A_\infty$ implies $\omega_{L_1} \in A_\infty$.*

169 4. Linking A_∞ to Carleson measure estimates

170 Prior to the approach taken in [32], the regularity of elliptic measure for an operator L was
 171 essentially derived either from a Rellich identity, or as a consequence of the perturbation
 172 theory. There were two obvious classes of operators of interest where these L^2 -identities were
 173 not valid: operators with complex coefficients and operators with non-symmetric coefficients.
 174 In the case of operators with complex coefficients, one of the most compelling outstanding
 175 questions was the Kato conjecture. This decades-old problem was finally resolved in the
 176 series of papers [4, 5, 24]. The solution of the Kato conjecture is a long story, summarized
 177 well in C. Kenig's review [31]. We will only mention that the solution also relied on a critical
 178 use of Carleson measures. The situation regarding (non-symmetric) t -independent operators
 179 is discussed in the next section.

180 In [32], it was shown that the elliptic measure associated to adivergence form operator
 181 $L := -\operatorname{div} A(x)\nabla$, belongs to the class A_∞ if and only if every bounded solution could
 182 (locally) be approximated arbitrarily well by a continuous function whose gradient satisfied a
 183 Carleson measure condition. This criteria was dubbed " ϵ -approximability", and was imme-
 184 diately applied to t -independent operators in dimension two.

185 **Definition 4.1.** Let $u \in L^\infty(\mathbb{R}_+^{n+1})$, with $\|u\|_\infty \leq 1$. Given $\epsilon > 0$, we say that u is ϵ -
 186 **approximable** if for every cube $Q_0 \subset \mathbb{R}^n$, there is a $\varphi = \varphi_{Q_0} \in W^{1,1}(T_{Q_0})$ such that

$$\|u - \varphi\|_{L^\infty(T_{Q_0})} < \epsilon, \quad (4.2)$$

187 and

$$\sup_{Q \subset Q_0} \frac{1}{|Q|} \iint_{T_Q} |\nabla \varphi(x, t)| \, dx dt \leq C_\epsilon, \quad (4.3)$$

188 where C_ϵ depends also upon dimension and ellipticity, but not on Q_0 .

189 To motivate this definition, we recall that harmonic functions in the upper half space
 190 possess the property of ϵ -approximability ([21, 45]). Although bounded harmonic func-
 191 tions in \mathbb{R}_+^{n+1} satisfy an L^2 -Carleson measure condition, the (technically more desirable)
 192 L^1 -Carleson condition fails to hold. It turns out that the approximation property is a good
 193 substitute for certain applications. In [11], Dahlberg showed that ϵ -approximability holds
 194 for bounded harmonic functions on Lipschitz domains as well. His proof used the previously
 195 established equivalence in L^p -norm between the square function and the non-tangential max-
 196 imal function on Lipschitz domains.

197 **Theorem 4.4** ([32]). *Let $L := -\operatorname{div} A(x)\nabla$, be an elliptic divergence form operator, not*
 198 *necessarily symmetric, with bounded measurable coefficients, defined in \mathbb{R}_+^{n+1} . Then there*
 199 *exists an ϵ , depending on the ellipticity constant of L such that if every solution to $Lu = 0$ in*
 200 *\mathbb{R}_+^{n+1} with $|u| \leq 1$ is ϵ -approximable then ω belongs to A_∞ .*

201 We will now sketch the main steps in the proof in [32] of this result, and then describe a
 202 recent modification of these ideas that yields a much stronger statement. The references give
 203 details, including certain technicalities, that we shall not describe in detail here.

204 The A_∞ class has many equivalent characterizations, and it will be convenient to work
 205 with this one:

206 *Given any $\eta > 0$, there exists a $\delta > 0$ such that for any cube $Q \subset \mathbb{R}^n$ and any $E \subset Q$,*
 207 *we have that $|E|/|Q| < \eta$ whenever $\omega(E)/\omega(Q) < \delta$.*

The main idea in the proof of Theorem 4.4 is as follows. Fix a cube Q of side length r , and suppose that E is a set whose elliptic measure, $\omega(E)$, is small. Let ϕ denote the ϵ -approximation of u . If E has sufficiently small measure, it will be shown that a truncated L^1 -version of the square function of ϕ is large. That is, the r -truncated $A_r(\phi)(x) := \left(\iint_{|x-y|<t<r} |\nabla\phi(y,t)| \frac{dydt}{t^n} \right)^{1/2}$ will be larger than some prescribed value $k = k(\epsilon)$. The desired conclusion will follow from the Carleson measure estimate by integrating:

$$|E|k^2 < \int_E A_r^2(\phi)(x)dx < \int_Q A_r^2(\phi)(x)dx < \iint_{T_Q} |\nabla\varphi(x,t)| dxdt$$

208 By the Carleson measure property, this latter expression is bounded by a constant C_ϵ times
209 $|Q|$, and thus $|E|/|Q| < \eta$ where $\eta \approx 1/k^2$.

210 In order to show that $A(\phi)$ is large on sets of small elliptic measure, a solution u to $Lu = 0$
211 was constructed with the property that u that oscillates by at least some fixed value a large
212 number of times in cones over points $x \in E$. Because u can be approximated arbitrarily
213 well by ϕ , this entailed that ϕ also oscillates a large number of times. This lower bound on
214 oscillation translated, via interior estimates, into an estimate from below for $\nabla\phi$ in disjoint
215 layers of a truncated cone over x .

216 There are several constructions that drive this proof, the first of which is Christ's con-
217 struction of dyadic grids on spaces of homogeneous type. Thus $Q \subset \mathbb{R}^n$ possesses a *dyadic*
218 *grid* adapted to ω , which is a collection of subsets $\{I_{j,l}\}$ of $Q \subset \mathbb{R}^n$ such that for each fixed
219 $j \geq 0$,

- 220 (1) $\mathbb{R}^n = \bigcup_l I_{j,l}$, and $I_{j,l_1} \cap I_{j,l_2} = \emptyset$ if $l_1 \neq l_2$.
221 (2) Each $I_{j,l}$ contains $B(2^{-j}, x_l)$, and is contained in an M -fold dilate $B(M2^{-j}, x_l)$,
222 where $B(2^{-j}, x_l)$ denotes the ball of radius 2^{-j} about the point $x_l \in \mathbb{R}^n$.
223 (3) If $I_{j,l} \cap I_{j',l} \neq \emptyset$ then either $I_{j,l} \subset I_{j',l}$ or $I_{j',l} \subset I_{j,l}$. Moreover, there exists a $C_M < 1$
224 such that $\omega(I_{j,l}) < C_M \omega(I_{j',l})$ whenever $I_{j,l} \subset I_{j',l}$.
225 (4) Any open set \mathcal{O} can be decomposed as $\mathcal{O} = \bigcup I_{j,l}$ where the $I_{j,l}$ are non-overlapping.
226 For each $I_{j,l}$ in this decomposition, there exists a point $p_{j,l}$ such that the distance from
227 $p_{j,l}$ to $I_{j,l}$ is comparable to $\text{diam}(I_{j,l})$.

228 **Definition 4.5.** Let ϵ be small and given. If $E \subset Q$, a *good ϵ -cover of E of length k* is a
229 collection of nested open sets $\{\mathcal{O}_i\}_{i=1}^k$ with $E \subset \mathcal{O}_k \subset \mathcal{O}_{k-1} \dots \subset \mathcal{O}_0 \subset Q$ where each
230 $\mathcal{O}_i = \bigcup S_i^j$ such that

- 231 (1) each S_i^j belongs to the dyadic grid, and
232 (2) for all $0 < i < k$, $\omega(\mathcal{O}_i \cap S_i^{i-1}) < \epsilon \omega(S_i^{i-1})$.

233 Note that a good ϵ -cover has the property that each S_j^i is properly contained in some S_l^{i-1} ,
234 as well as the further nesting property that for $k > i > m > 0$, $\omega(S_j^m \cap \mathcal{O}_i) < \epsilon^{i-m} \omega(S_j^m)$.

235 **Lemma 4.6** ([32]). *Given $\epsilon > 0$, there exists a $\delta > 0$ such that if $\omega(E) < \delta$, then E has a*
236 *good ϵ -cover of length k where $k \rightarrow \infty$ as $\omega(E) \rightarrow 0$.*

237 The good ϵ -cover of length k is used to construct the boundary data f which will give
238 rise to a bounded, oscillating solution u to L . Set:

$$f = \sum_{i=0}^k (-1)^i \mathcal{X}_{\mathcal{O}_i}. \quad (4.7)$$

and let u be the solution to $Lu = 0$, with $u(x, 0) = f$.

Note that $f \leq 1$, and so $0 \leq u \leq 1$. For each point $x \in E$, we find a sequence of points, $X_m = (x_m, t_m)$ in the cone $\Gamma(x)$ with the property that, for $0 < m < k$ even, $u(X_m) > c_1$, and for $0 < m < k$ odd, $u(X_m) < c_2$ and $c_1 - c_2 > c(\epsilon)$. To define these X_m , collect the dyadic grid cubes $S_l^m \subset \mathcal{O}_m$ that contain the given point x . Let $l(S)$ denote the side length of S . The point X_m , when m is even, is essentially any point in the top half of the Carleson region over S_l^m . When m is odd, the point $X_m = (x_m, t_m)$ will also be in this Carleson region, but t_m will be closer to the boundary, that is, $t \approx \eta l(S_l^m)$. (In order to make sure that these points X_m descend in the cone, i.e., have the property that $t_m < \rho t_{m-1}$ for some $\rho < 1$, we may have to skip a finite number of levels m . Details are in [32].)

We give a rough sketch of these estimates. Recall the integral representation of solutions: $u(x, t) = \int K(x, t; y, 0)f(y)d\omega(y)$.

Fix an even m . We can then write $u(X_m) = u_1(X_m) + u_2(X_m)$ where $u_1(x, 0) = f_1(x) := \sum_{i=0}^m \mathcal{X}_{\mathcal{O}_i}$. Moreover, since $u > 0$, we have that, for some c_1 depending only on ellipticity,

$$u(X_m) > \int K(x_m, t_m; y, 0)f(y)d\omega(y) \geq c \frac{1}{\omega(S_l^m)} \int_{S_l^m} f(y)d\omega(y).$$

Because m is even, the function $f_1 = 1$ on S_l^m , and so $u_1 > c'_1$. By the nesting property of the cover,

$$\frac{1}{\omega(S_l^m)} \int_{S_l^m} f_2(y)d\omega(y) < \frac{1}{\omega(S_l^m)} \sum_{i=m+1}^k \omega(\mathcal{O}_i \cap S_l^m) < 2\epsilon,$$

and thus $u(X_m) > c'_1 - 2\epsilon > c_1$. When m is odd, the boundary function f is split similarly, and a more technical analysis is needed to show that the main term is indeed given by f_1 , which vanishes on the dyadic cube S_l^m . Since (x_m, t_m) was chosen so that $t_m \approx l(S_l^m)$, the Hölder decay of the solution near the boundary where it vanishes will be used to show that $u(x_m, t_m) < c_2 < c_1 - \epsilon$, if ϵ and η are chosen appropriately.

In conclusion, one can extract from this construction a sequence of points $\{x_m, t_m\}_{m=0}^k \in \Gamma(x)$ such that $|u(x_m, t_m) - u(x_{m-1}, t_{m-1})| > \epsilon$, and such that $t_m < \rho t_{m-1}$. One can then derive a lower bound for the L^1 -square function $A(u)$, and likewise for $A(\phi)$ where ϕ is the approximate to u .

This approximation theorem, and its proof, yielded several applications to specific classes of operators ([15, 22, 36, 37]): [22] is explained in more detail in the next section. Since one cannot expect the actual solution to L to satisfy an L^1 -Carleson condition (as the approximate does), this program left open the question of the role of classical Carleson measure estimates for solutions.

In [16], it was shown that the A_∞ property of elliptic measure is equivalent to the existence of Carleson measure estimates for solutions with boundary data in BMO . The result was proven in Lipschitz domains (and will likely hold for chord-arc domains as well).

Theorem 4.8 ([16]). *Let $L := -\operatorname{div} A(x)\nabla$, be an elliptic divergence form operator, not necessarily symmetric, with bounded measurable coefficients, defined in \mathbb{R}_+^{n+1} . Then $\omega \in A_\infty$ if and only if, for every solution u to $Lu = 0$ with boundary data $f \in BMO$, we have the Carleson measure estimate:*

$$\sup_Q \frac{1}{|Q|} \iint_{T_Q} t |\nabla u(x, t)|^2 dx dt \leq C \|f\|_{BMO}^2, \quad (4.9)$$

272 The proof of Theorem 4.8 used a dual formulation of the A_∞ condition:

273 *Given any $\eta > 0$, there exists a $\delta > 0$ such that for any cube $Q \subset \mathbb{R}^n$ and any*
 274 *$E \subset Q$, we have that $\omega(E)/\omega(Q) < \eta$ whenever $|E|/|Q| < \delta$.*

275 To verify this condition, a construction of [28] was invoked to produce, for any such E ,
 276 a BMO function $f \geq \chi_E$ with small BMO norm. An upper estimate on $\omega(E)/\omega(Q)$ in
 277 terms of the (small) Carleson measure bound on f required a lemma in [34]. See [16] for
 278 details.

279 In turn, this left open the question of whether the A_∞ property of elliptic measure could
 280 be characterized by the existence of Carleson measure conditions for solutions to bounded
 281 data, as opposed to data in the larger class, BMO .

282 The solution u , with boundary data f as in (4.7), has only $A(u)$ large on the set $E \subset Q$
 283 when $\omega(E)$ is small, but not necessarily $S(u)$ large as well. To see why, suppose Q has side
 284 length 1, and cut the cone into dyadic layers: $\Gamma_j(x) = \{(y, t) \in \Gamma(x) : 2^{-j} < t < 2^{-j+1}\}$.

We write

$$S(u)(x) = \sum_j \int_{\Gamma_j(x)} t^{1-n} |\nabla u|^2 dy dt$$

285 Each piece $\int_{\Gamma_j(x)} t^{1-n} |\nabla u|^2 dy dt$ is a scaled average of the gradient of u which, by a Poincaré
 286 estimate, can be bounded from below by the oscillation of u over this dyadic layer of the
 287 cone. However, this construction doesn't yield any information about the oscillation of u
 288 on such dyadic regions because there is no control on the distance between the the points
 289 $\{x_m, t_m\}_{m=0}^k \in \Gamma(x)$ that belong to different levels \mathcal{O}_m .

290 The linking of A_∞ to Carleson measure estimates for L^∞ functions, is the subject of
 291 [33]. Essentially, one can use the same cover, and define a new function f as follows. Each
 292 \mathcal{O}_m is a union of dyadic intervals S_l^m , and each S_l^m has a (bounded) number of immediate
 293 dyadic subintervals. For each S_l^m choose one of its dyadic children and call it \tilde{S}_l^m . If m is
 294 even, define f_m to take the value 1 on $\bigcup_l (S_l^m \setminus \tilde{S}_l^m)$ and 0 elsewhere. If m is odd, we define
 295 f_m to “zero out” the values of f_{m-1} : $f_m = -1$ where $f_{m-1} = 1$ and is 0 elsewhere. Now set
 296 $f = \sum_{m=0}^k f_m$ and let u be the solution to $Lu = 0$ with boundary data f . On each even level
 297 m , f takes on both the values 0 and 1 on dyadic children. Thus, arguments modeled on those
 298 of [32] will yield the following: for some $C, c > 0$, and every $x \in E$, there are sequences
 299 $\{x_m, t_m\}_{m=0}^k$ with $ct_{m-1} < t_m < Ct_{m-1}$ for which $|u(x_m, t_m) - u(x_{m-1}, t_{m-1})| > \epsilon$.

300 From this construction, it can be concluded that if solutions to L with bounded data satisfy
 301 classical Carleson measure estimates, then the elliptic measure associated to L is A_∞ , and
 302 thus the Dirichlet problem with data in L^p is uniquely solvable for some $p > 1$. As a corollary,
 303 we see that solutions with BMO data possess C. Fefferman-type Carleson estimates if
 304 and only if solutions with L^∞ data possess these Carleson estimates.

305 **Theorem 4.10** ([33]). *Let $L := -\operatorname{div} A(x)\nabla$, be an elliptic divergence form operator, not*
 306 *necessarily symmetric, with bounded measurable coefficients, defined in \mathbb{R}_+^{n+1} . Then $\omega \in$*
 307 *A_∞ if and only if, for every solution u to $Lu = 0$ with boundary data $f \leq 1$, we have the*
 308 *Carleson measure estimate:*

$$\sup_Q \frac{1}{|Q|} \iint_{T_Q} t |\nabla u(x, t)|^2 dx dt \leq C. \quad (4.11)$$

5. Application to time-independent operators

The ϵ -approximability theorem of [32] was established by showing the equivalence in L^p norm between the non-tangential maximal function and the square function, and invoking a stopping time construction due to Dahlberg ([11]). Examples were given to demonstrate that, for $p \rightarrow \infty$, there exists elliptic operators in this class for which D_p is not solvable. In other words, no stronger conclusion than A_∞ of the elliptic measure can be concluded from ϵ -approximability. A more precise study of these counterexamples was undertaken in [1], where it was shown that the boundary equation method and the Lax-Milgram method may construct different solutions, thus underscoring the differences between the symmetric and the non-symmetric situation.

As an application of the consequences of norm equivalence between non-tangential maximal function and the square function, [32] contained a proof that two-dimensional t -independent divergence form non-symmetric elliptic operators had elliptic measure belonging to A_∞ . This was a first step in establishing regularity of elliptic measure without recourse to L^2 identities of Rellich type. Although the proof only worked in \mathbb{R}^2 , it worked under a surprisingly flexible condition on the matrix.

Theorem 5.1 ([32]). *Let $L := -\operatorname{div} A(x)\nabla$ be an elliptic operator in \mathbb{R}^2 with bounded measurable coefficients. Suppose that there exists a fixed unit vector \vec{e} such that $A(x, t) = A(x; , t) \cdot \vec{e}$. Then the elliptic measure ω_L belongs to A_∞ in a domain in any Lipschitz domain in \mathbb{R}^2 .*

At this point, we note that the development of the theory of non-symmetric operators has had several motivations. First of all, the boundary value problem for general non-symmetric elliptic operators cannot be solved in L^2 , and L^p solvability requires a different approach than that of Rellich identities. Second, the well-posedness results for equations with real non-symmetric coefficients and associated estimates on solutions are the first step towards understanding operators with complex coefficients in the non-Hermitian case, a case of interest for Kato's analyticity program. Finally, many problems arising in homogenization theory have non-symmetric coefficients [6]. Solving the Dirichlet problem with data in L^p is the first step in the study of the uniform bounds, independent of the scaling parameter in homogenization theory, in the absence of symmetry ([6]).

It is therefore desirable to develop approaches to solving L^p boundary value problems that are neither perturbative nor rely on symmetry of the matrices. However, the proof of Theorem 5.1 did not generalize to higher dimensions, as it relied on a special change of variable to put the matrix of coefficients in upper triangular form. It took almost fifteen years, and the development of the tools used to solve Kato's conjecture (the square root estimates), to be able to prove this result in all dimensions.

Theorem 5.2 ([22]). *Let L be a divergence form elliptic operator as above, with t -independent coefficients. Then there is a $p < \infty$ such that the Dirichlet problem D_p is well-posed; equivalently, for each cube $Q \subset \mathbb{R}^n$, the L -harmonic measure $\omega_L \in A_\infty(Q)$, with constants that are uniform in Q .*

The proof in [22] proceeded, as in two dimensions, by establishing A_∞ of the elliptic measure as consequence of ϵ -approximability of bounded solutions. The boundedness in norm of the non-tangential maximal function by the square function had previously been established (globally) in [2] so the main contribution of [22] was the converse, which had the immediate corollary:

354 **Corollary 5.3** ([22]). *Under the same hypotheses as in Theorem 5.2, for a bounded solution*
 355 *u , we have the Carleson measure estimate*

$$\sup_Q \frac{1}{|Q|} \iint_{T_Q} |\nabla u(x, t)|^2 t dx \leq C \|u\|_{L^\infty(\Omega)}, \quad (5.4)$$

356 *where C depends only upon dimension and ellipticity.*

357 Theorem 4.10 implies that this Carleson measure estimate alone is now sufficient to con-
 358 clude A_∞ , somewhat simplifying the proof of A_∞ for this class of elliptic measures.

359 In [32], it was shown that the equivalence between non-tangential maximal functions and
 360 square functions implied A_∞ , for that equivalence was necessary to prove ϵ -approximation
 361 of bounded solutions. We see now that only half of this information is required, namely the
 362 bounds on the square function in terms of the non-tangential maximal function.

363 **Remark 5.5.** Most of the discussion in this article has centered on the Dirichlet problem.
 364 Over the years, there has been a parallel development for boundary value problems such
 365 as the Neumann and the regularity problems for second order operators, and for higher order
 366 operators and elliptic systems. There is a vast literature on the solvability of these (even more)
 367 challenging problems, which is beyond the scope of the present article.

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