

# Additional problems for Math 0540

December 4, 2015

**A1.** Write out the addition and multiplication tables for  $\mathbb{F}_7$ , the finite field with 7 elements.

**A2.** Let  $V = \mathbb{F}_2^2$ , a vector space over the finite field  $\mathbb{F}_2$ . How many linear maps  $V \rightarrow V$  are there?

**A3.** Let  $U$  be the vector space of real polynomials  $f(x)$  of degree at most 4 such that

$$\int_0^1 f(x)dx = 0.$$

By considering the integration map  $\mathcal{P}_4(\mathbb{R}) \rightarrow \mathbb{R}$  that sends  $f(x)$  to  $\int_0^1 f(x)dx$ , compute the dimension of  $U$ .

**A4.** For each of the following linear maps  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ , write down the matrix of  $T$ , with respect to the standard basis of  $\mathbb{R}^2$  on both copies of  $\mathbb{R}^2$ . (You should convince yourself that each map is linear, but you do not need to prove anything in this problem. Just compute the answer.)

1. Dilation by a factor of 2 with respect to the origin; that is, the map  $T$  that sends each vector  $v$  to  $2v$ .
2. Reflection across the line  $x = y$ . (Here  $x$  and  $y$  denote the usual coordinates  $(x, y)$  of  $\mathbb{R}^2$ .)
3. Projection to the line  $x = y$ . That is,  $T$  sends  $v$  to the point on the line  $x = y$  that is closest to  $v$ .
4. The identity map.

**A5.** Do the same for each of the linear maps in problem A4, but now with respect to the basis  $(1, 0), (1, 1)$  on *both* copies of  $\mathbb{R}^2$ .

**A6.** Compute each of the following matrix products, or explain why they are not defined:

1.

$$\begin{pmatrix} 2 & 5 \\ 3 & 7 \\ 11 & 13 \end{pmatrix} \begin{pmatrix} 1 & -2 \\ -1 & 0 \end{pmatrix}$$

2.

$$\begin{pmatrix} 1 & -2 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} 2 & 5 \\ 3 & 7 \\ 11 & 13 \end{pmatrix}$$

3.

$$\begin{pmatrix} 1+i \\ 0 \\ i \end{pmatrix} \begin{pmatrix} -i & 0 & i \end{pmatrix}$$

4.

$$\begin{pmatrix} -i & 0 & i \end{pmatrix} \begin{pmatrix} 1+i \\ 0 \\ i \end{pmatrix}$$

**A7.** Let  $T_\theta: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be the linear map given by counterclockwise rotation by  $\theta$  about the origin. Let  $A$  be the matrix of  $T_\theta$  with respect to the standard bases. Compute  $A^2$  and  $A^3$ ; then interpret these products geometrically to deduce formulas for  $\cos(2\theta)$ ,  $\sin(2\theta)$ ,  $\cos(3\theta)$ , and  $\sin(3\theta)$ .

**A8.** Let  $W$  be the subset of  $\mathbb{F}^\infty$  given by

$$W = \{(x_1, x_2, \dots) : \text{there exists a number } N \text{ such that } x_i = x_j \text{ for all } i, j \geq N\}.$$

1. Prove  $W$  is a subspace.
2. Prove that  $\mathbb{F}^\infty/W$  is infinite-dimensional.

**A9.** Let  $\mathbb{F} = \mathbb{R}$  or  $\mathbb{C}$ . Let  $D: \mathbb{F}^n \times \dots \times \mathbb{F}^n \rightarrow \mathbb{F}$  be a function such that:

$$(P1) \quad D(v_1, \dots, \alpha v_k, \dots, v_n) = \alpha D(v_1, \dots, v_k, \dots, v_n) \text{ for all } v_i \in \mathbb{F}^n, \alpha \in \mathbb{F};$$

(P2)  $D(v_1, \dots, v_k + v'_k, \dots, v_n) = D(v_1, \dots, v_k, \dots, v_n) + D(v_1, \dots, v'_k, \dots, v_n)$   
for all  $v_i \in \mathbb{F}^n$ .

Show that  $D$  satisfies

(P3)  $D(v_1, \dots, v_j, \dots, v_k, \dots, v_n) = -D(v_1, \dots, v_k, \dots, v_j, \dots, v_n)$  for all  $v_i \in \mathbb{F}^n$

if and only if  $D$  satisfies

(P3')  $D(v_1, \dots, v_j + \alpha v_k, \dots, v_k, \dots, v_n) = D(v_1, \dots, v_j, \dots, v_k, \dots, v_n)$  for any  $v_i \in \mathbb{F}^n$  and  $\alpha \in \mathbb{F}$ .

**A10.** Apply the Gram Schmidt procedure to the linearly independent list

$$(1, 0, 0), (1, 1, 1), (1, 1, 2) \text{ in } \mathbb{R}^3.$$

**A11.** Apply the Gram Schmidt procedure to the linearly independent list

$$(1, 1 + i), (1, i) \in \mathbb{C}^2.$$

**A12.** Consider the map  $T_\theta \in \mathcal{L}(\mathbb{R}^2)$  that is counterclockwise rotation by angle  $\theta$ .

1. Verify that  $T_\theta^* = T_\theta^{-1}$ .
2. For which values of  $\theta \in [0, 2\pi)$  is  $T_\theta$  self-adjoint? for which values is it normal?

**A13.** Classify the isometries of  $\mathbb{R}^2$ , as follows. Let  $T \in \mathcal{L}(\mathbb{R}^2)$  be an isometry. Show that

- $T$  is a rotation, and  $\det \mathcal{M}(T) = 1$ , or
- $T$  is a reflection across a line through the origin, and  $\det \mathcal{M}(T) = -1$ ,

where the matrices are taken with respect to the standard basis of  $\mathbb{R}^2$ .