

Tensor Transformations

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February 26, 2015

I found the material in §12.4 really hard to read. I re-wrote the material in a way which seems easier to get through. One thing about my notes is that I switch the roles of V and W , because we've all had years of experience thinking about linear transformations from V into W and not the reverse. (This is just a psychological preference, of course.)

1 Pulling Back a Tensor

Let V and W be vector spaces and let $M : V \rightarrow W$ be a linear transformation. The map M gives a linear transformation

$$M^* : T^r(W) \rightarrow T^r(V). \quad (1)$$

Note that V and W have switched. Let $T : W^r \rightarrow \mathbf{R}$ be a tensor of type r . We have the tensor $M^*T : V^r \rightarrow \mathbf{R}$ defined by the equation

$$M^*(T)(V_1, \dots, V_r) = T(M(V_1), \dots, M(V_r)). \quad (2)$$

In other words, we map V_1, \dots, V_r into W and then apply the tensor to them. Everything involved is linear, so M^* is a linear map. The goal of these notes is to explain the action of M^* .

Let $\{v_1, \dots, v_m\}$ is a basis for V and $\{w_1, \dots, w_n\}$ is a basis for W . We have the formula

$$M(v_i) = \sum_{k=1}^n M_{ik} w_k. \quad (3)$$

The goal is to express the map M^* in terms of these coefficients.

There are three cases, the first of which is just a warm-up: the linear functional case, the general case, and the alternating case.

2 Linear Functional Case

We are interested in $M^* : W^* \rightarrow V^*$. We have the dual bases $\{v_1^*, \dots, v_m^*\}$ and $\{w_1^*, \dots, w_n^*\}$. Here $v_i^*(v_j) = 1$ if $i = j$ and 0 otherwise. Same goes for w_i^* . The matrix for M^* is just the transpose of the matrix for M .

To figure out the matrix for M^* , we just have to see that $M^*(w_j^*)$ does to v_i . We compute

$$\begin{aligned} M^*(w_j^*)(v_i) &= \\ w_j^*(M(v_i)) &= \\ w_j^*\left(\sum_{k=1}^n (M_{ik}w_k)\right) &= \\ \sum_{k=1}^n w_j^*(M_{ik}w_k) &= \\ M_{ij}. \end{aligned}$$

In short,

$$M^*(w_j^*)(v_i) = M_{ij}. \quad (4)$$

But that means that

$$M^*(w_j^*) = \sum_{k=1}^m M_{kj} v_k^* \quad (5)$$

This is why the matrix for M^* is just the transpose of M_{ij} .

3 General Case

Let's introduce the multi-index notation. Let $I = (i_1, \dots, i_r)$ be an r -tuple of numbers. We write

$$v_I^* = v_{i_1}^* \otimes \dots \otimes v_{i_r}^*. \quad (6)$$

We write the same thing for w_I^* . Also, we write

$$v_I = (v_{i_1}, \dots, v_{i_r}).$$

This is just an r -tuple of vectors. We have $v_I^*(v_J) = 1$ if $I = J$ and 0 otherwise.

We want to figure out what $M^*(w_J^*)$ does to v_I . This gives the component M_{IJ}^* of the giant matrix representing M^* .

We compute

$$\begin{aligned}
M^*(w_J)(v_I) &= \\
w_J(M(v_I)) &= \\
w_J(M(v_{i_1}), \dots, M(v_{i_r})) &= \\
w_{j_1}^* \otimes \dots \otimes w_{j_r}^*(M(v_{i_1}), \dots, M(v_{i_r})) &= \\
w_{j_1}^*(M(v_{i_1})) \times \dots \times w_{j_r}^*(M(v_{i_r})) &= \\
M_{i_1 j_1} \dots M_{i_r j_r}. &
\end{aligned}$$

So, the bottom line is that

$$M_{IJ} = M_{i_1, j_1} \dots M_{i_r, j_r}. \quad (7)$$

4 Alternating Case

The basis elements for $\wedge^r(V^*)$ are given by

$$[v_I^*] = A(v_I^*) = v_{i_1} \wedge \dots \wedge v_{i_r}.$$

Similarly for $\wedge^r(W^*)$. The tensor $M^*([w_J]^*)$ is some linear combination of the various $[v_I]^*$. We want to find the coefficients. We have

$$[w_J^*] = \sum_{\sigma} \epsilon(\sigma) w_{\sigma J}^*. \quad (8)$$

Here σ is a permutation, and $\epsilon(\sigma)$ is the sign of σ , and σJ denotes the multi-index you get when you permute the entries of J according to the action of σ .

Now let's take I to be an increasing multi-index: $i_1 < \dots < i_r$. From the previous case, and linearity, we have

$$M^*([w_J^*])(v_I) = \sum_{\sigma} \epsilon(\sigma) M_{I, \sigma J} = \sum_{\sigma} \epsilon(\sigma) M_{i_1 \sigma(j_1), \dots, i_r, \sigma(j_r)}. \quad (9)$$

This last expression is just the determinant of the $r \times r$ matrix you get by taking I rows of M and the J columns.

5 Crucial Special Case

Suppose that $V = W$ and $r = n = \dim(V)$. Then the transformation law tells us that M^* is just multiplication by $\det(M)$. In particular, M^* is the identity map if $\det(M) = 1$.