

January 2015  
MA 2110, Introduction to Manifolds  
First Assignment  
Due 2/5/15

January 30, 2015

1. Let  $G : U \rightarrow V$  and  $F : V \rightarrow W$  be maps between open subsets of Euclidean spaces, let  $p \in U$  be a point, and assume that the derivatives  $D_p G$  and  $D_{G(p)} F$  exist. Prove the coordinate-free Chain Rule: The derivative of  $F \circ G$  at the point  $p$  exists and is given by a composition of linear maps:

$$D_p(F \circ G) = D_{G(p)} F \circ D_p G.$$

2. Let  $M \subset \mathbb{R}^n$  be a smooth  $m$ -dimensional manifold in the sense of the first lecture, or the Supplement #2 (<http://www.math.brown.edu/~tomg/211notes.html>). Using the definition of the tangent space  $T_p M$  given there, use the Chain Rule to obtain two more descriptions of  $T_p M$ : First, if a neighborhood of  $p$  in  $M$  has a regular parametrization  $\phi : V \rightarrow \mathbb{R}^n$  with  $\phi(0) = p$ , then  $T_p M$  is the image of the linear map  $D_0 \phi : \mathbb{R}^m \rightarrow \mathbb{R}^n$ . Second, if a neighborhood of  $p$  in  $M$  is a regular level set  $\psi^{-1}(0)$  then  $T_p M$  is the kernel of the linear map  $D_p \psi : \mathbb{R}^n \rightarrow \mathbb{R}^{n-m}$ .

3. For which values of  $R$  can we say that the solution set of the pair of equations

$$x^2 + y^2 = 1$$

$$x^2 + z^2 = R^2$$

is a one-dimensional smooth manifold in  $\mathbb{R}^3$ ? Sketch the set for several illustrative values of  $R$ .