

# Evolution equations, II

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# The main equations

- the defocusing pure power NLS:  $u : \mathbb{R}^d \times [0, T] \rightarrow \mathbb{C}$ ,

$$i\partial_t u + \Delta u = u|u|^{2\sigma}, \quad u(0) = \phi.$$

- the KdV equation:  $u : \mathbb{R} \times [0, T] \rightarrow \mathbb{R}$ ,

$$\partial_t u + \partial_x^3 u = u\partial_x u, \quad u(0) = \phi.$$

# Local well-posedness: fixed-point argument

We rewrite the NLS in integral form (Duhamel formula)

$$u(t) = e^{it\Delta}\phi - i \int_0^t e^{i(t-s)\Delta} N(u(s)) ds,$$
$$N(u) = u|u|^{2\sigma}.$$

We would like to construct the solution by the recursive scheme

$$u^{(n+1)}(t) = e^{it\Delta}\phi - i \int_0^t e^{i(t-s)\Delta} \mathcal{N}(u^{(n)}(s)) ds,$$
$$u^{(0)}(t) = e^{it\Delta}\phi.$$

The procedure converges if

$$\left\| \int_0^t e^{i(t-s)\Delta} \mathcal{N}(f(s)) ds - \int_0^t e^{i(t-s)\Delta} \mathcal{N}(g(s)) ds \right\|_{L_T^\infty H^\rho} \ll \|f - g\|_{L_T^\infty H^\rho} \quad (1)$$

for any  $f, g \in C([0, T] : H^\rho)$  with  $\|f\|_{L_T^\infty H^\rho}, \|g\|_{L_T^\infty H^\rho} \leq 2R$ .

# Local well-posedness: fixed-point argument

If  $\rho > d/2$  then  $H^\rho$  is an algebra,  $\rho > d/2$ , therefore

$$\|\mathcal{N}(f) - \mathcal{N}(g)\|_{L_T^\infty H^\rho} \lesssim_\rho R \|f - g\|_{L_T^\infty H^\rho}$$

If  $\sigma \geq 1$  is an integer then

$$\|e^{i(t-s)\Delta} \{\mathcal{N}(f) - \mathcal{N}(g)\}\|_{H^\rho} \lesssim_{\rho,R} \|f - g\|_{L_T^\infty H^\rho}$$

for any  $s \leq t \in [0, T]$ . Thus, for any  $t \in [0, T]$

$$\left\| \int_0^t e^{i(t-s)\Delta} [\mathcal{N}(f(s)) - \mathcal{N}(g(s))] ds \right\|_{H^\rho} \lesssim_{\rho,R} T \|f - g\|_{L_T^\infty H^\rho},$$

which gives the desired bounds (1) if  $T \ll_{\rho,R} 1$ .

# Global well-posedness of the defocusing NLS

- Conservation laws: the quantities

$$\begin{aligned} M(t) &= \int_{\mathbb{R}^d} |u(x, t)|^2 dx, \\ E(t) &= \frac{1}{2} \int_{\mathbb{R}^d} |\nabla_x u(x, t)|^2 dx + \frac{1}{2\sigma + 2} \int_{\mathbb{R}^d} |u(x, t)|^{2\sigma+2} dx \end{aligned} \quad (2)$$

are conserved.

**Theorem:** Assume that

$$\sigma \in \left(0, \frac{2}{d-2}\right).$$

If  $\phi \in H^1(\mathbb{R}^d)$  then there is a unique global solution  $u \in S^1 \subseteq C([0, \infty) : H^1(\mathbb{R}^d))$  of the initial-value problem

$$i\partial_t u + \Delta u = u|u|^{2\sigma}, \quad u(0) = \phi.$$

Moreover, the mapping  $\phi \rightarrow u$  is continuous from  $H^1 \rightarrow S^1([0, T])$ , for any  $T > 0$ .

# Global well-posedness of the defocusing NLS

- To prove global well-posedness we need to be able to prove local well-posedness in  $H^1$ .
- The range  $\sigma \in (0, \frac{2}{d-2})$  is called the energy-subcritical range.
- We would still like to construct the solution by the basic recursive scheme

$$u^{(n+1)}(t) = e^{it\Delta}\phi - \int_0^t e^{i(t-s)\Delta}\mathcal{N}(u^{(n)}(s)) ds,$$
$$u^{(0)}(t) = e^{it\Delta}\phi.$$

in a suitable space  $S^1[0, \varepsilon]$ .

# Global well-posedness of the defocusing NLS

We define the Strichartz space of functions on  $\mathbb{R}^d \times \mathbb{R}$  by

$$S^0 := L_t^\infty L_x^2 \cap L_t^q L_x^r,$$
$$\|f\|_{S^0} := \max \left\{ \|f\|_{L_t^\infty L_x^2}, \|f\|_{L_t^q L_x^r} \right\}$$

where  $(q, r)$  is an *admissible pair*

$$2/q + d/r = d/2, \quad (q, r) \in (2, \infty] \times [2, \infty]. \quad (3)$$

Here

$$\|f\|_{L_t^q L_x^r} := \left[ \int_{\mathbb{R}} \left[ \int_{\mathbb{R}^d} |f(x, t)|^r dx \right]^{q/r} dt \right]^{1/q}.$$

**Theorem:** (Strichartz estimates) (a) If  $(q, r)$  is admissible then

$$\|e^{it\Delta} \phi\|_{L_t^q L_x^r} \lesssim_q \|\phi\|_{L^2}.$$

(b) If  $(q, r)$  is an admissible pair then

$$\left\| \int_{-\infty}^t e^{i(t-s)\Delta} N(s) ds \right\|_{L_t^\infty L_x^2 \cap L_t^q L_x^r} \lesssim_q \|N\|_{L_t^1 L_x^2 + L_t^{q'} L_x^{r'}}.$$

# Global well-posedness of the defocusing NLS

- By definition,

$$\|N\|_{X+Y} := \inf_{N=N_1+N_2} \|N_1\|_X + \|N_2\|_Y.$$

- Dispersive estimates. The kernel of the operator  $e^{it\Delta}$  is

$$K(x, t) := C \int_{\mathbb{R}^d} e^{ix \cdot \xi} e^{-it|\xi|^2} d\xi = Ct^{-d/2} e^{i|x|^2/(4t)}.$$

$$\|e^{it\Delta}\|_{L^2(\mathbb{R}^d) \rightarrow L^2(\mathbb{R}^d)} \lesssim 1,$$

$$\|e^{it\Delta}\|_{L^1(\mathbb{R}^d) \rightarrow L^\infty(\mathbb{R}^d)} \lesssim |t|^{-d/2}.$$

By interpolation

$$\|e^{it\Delta}\|_{L^{r'}(\mathbb{R}^d) \rightarrow L^r(\mathbb{R}^d)} \lesssim |t|^{-d(1/2-1/r)}.$$



# Global well-posedness of the defocusing NLS

- The  $TT^*$  argument: we want

$$\|e^{it\Delta}\phi\|_{L_t^q L_x^r} \lesssim_q \|\phi\|_{L^2}.$$

This is equivalent to

$$\left| \int_{\mathbb{R}^d \times \mathbb{R}} (e^{it\Delta}\phi)(x)g(x, t) dxdt \right| \lesssim_q \|\phi\|_{L^2} \|g\|_{L_t^{q'} L_x^{r'}}.$$

This is equivalent to

$$\left\| \int_{\mathbb{R}^d \times \mathbb{R}} e^{-it|\xi|^2} e^{ix \cdot \xi} g(x, t) dxdt \right\|_{L_\xi^2} \lesssim_q \|g\|_{L_t^{q'} L_x^{r'}}.$$

This is equivalent to

$$\left| \int_{\mathbb{R}^d \times \mathbb{R}} \int_{\mathbb{R}^d \times \mathbb{R}} g(x, t) \bar{g}(y, s) K(x-y, t-s) dxdt dyds \right| \lesssim_q \|g\|_{L_t^{q'} L_x^{r'}}^2. \quad (4)$$

# Global well-posedness of the defocusing NLS

However, using the dispersive estimate,

$$\left| \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} g(x, t) h(y, s) K(x-y, t-s) dx dy \right| \lesssim G(t) G(s) |t-s|^{-d(1/2-1/r)}$$

where

$$G(t) = \left[ \int_{\mathbb{R}^d} |g(x, t)|^{r'} dx \right]^{1/r'}.$$

The desired bound follows from fractional integration:

$$\|f * |y|^{-\gamma}\|_{L^q(\mathbb{R})} \leq C_{p,q} \|f\|_{L^p(\mathbb{R})}$$

if

$$0 < \gamma < 1, \quad 1 < p < q < \infty, \quad 1 - \gamma = \frac{1}{p} - \frac{1}{q}.$$

# Global well-posedness of the defocusing NLS

We return now to the proof of the global well-posedness theorem. Assume, for simplicity, that  $d = 3$  and we study the cubic NLS, corresponding to  $\sigma = 1$ . This is consistent with the subcritical condition

$$\sigma \in (0, 2/(d - 2)).$$

We define the Strichartz space  $S^1[0, T]$  as the set functions on  $\mathbb{R}^d \times [0, T]$  defined by the norm

$$\|f\|_{S^1[0, T]} := \max \left\{ \|\langle \nabla \rangle f\|_{L_t^\infty L_x^2}, \|\langle \nabla \rangle f\|_{L_t^4 L_x^3} \right\}.$$

with  $(q, r) = (4, 3)$ .

# Global well-posedness of the defocusing NLS

The Strichartz estimate shows that

$$\|e^{it\Delta}\phi\|_{S^1[0,T]} \lesssim \|\phi\|_{H^1}$$

To close the fixed-point argument we need to show that

$$\|f \cdot g \cdot \partial h\|_{L_t^{4/3} L_x^{3/2}[0,T]} \ll \|f\|_{S^1[0,T]} \|g\|_{S^1[0,T]} \|h\|_{S^1[0,T]} \quad (5)$$

if  $T$  is small enough. However, using Sobolev embedding in the  $x$  variable

$$\begin{aligned} \|f\|_{L_t^4 L_x^{12}[0,T]} &\lesssim \|f\|_{S^1[0,T]}, & \|g\|_{L_t^4 L_x^{12}[0,T]} &\lesssim \|g\|_{S^1[0,T]}, \\ \|\partial h\|_{L_t^\infty L_x^2[0,T]} &\lesssim \|h\|_{S^1[0,T]}. \end{aligned}$$

Therefore

$$\|f \cdot g \cdot \partial h\|_{L_t^2 L_x^{3/2}[0,T]} \lesssim \|f\|_{S^1[0,T]} \|g\|_{S^1[0,T]} \|h\|_{S^1[0,T]}$$

and the desired conclusion (5) follows by taking  $T$  small.

# Global well-posedness of the KdV equation

We consider now the Korteweg-de Vries equation:

$$u : \mathbb{R} \times [0, T] \rightarrow \mathbb{R},$$

$$\partial_t u + \partial_x^3 u = u \partial_x u, \quad u(0) = \phi.$$

The equation has infinitely many conservation laws, including the conservation of mass

$$M(t) = \int_{\mathbb{R}^d} |u(x, t)|^2 dx.$$

**Theorem:** If  $\phi \in H^0(\mathbb{R})$  is real-valued then there is a unique global solution  $u \in F^0 \subseteq C([0, \infty) : H^0(\mathbb{R}))$  of the KdV initial-value problem. Moreover, the mapping  $\phi \rightarrow u$  is continuous from  $H^0 \rightarrow F^0([0, T])$ , for any  $T > 0$ .

# Global well-posedness of the KdV equation

- The energy argument gives local well-posedness in  $H^{3/2+}$ .
- By scaling  $u_\lambda(x, t) = \lambda^2 u(\lambda x, \lambda^3 t)$ ,  $\lambda > 0$ , we may assume that the initial data is small in  $H^0$ ,  $\|\phi\|_{H^0} \leq \varepsilon \ll 1$ , which will be propagated by the flow.
- We would still like to construct the solution by the basic recursive scheme (coming from the Duhamel formula)

$$u^{(n+1)}(t) = e^{-t\partial_x^3} \phi + \int_0^t e^{-(t-s)\partial_x^3} \mathcal{N}(u^{(n)}(s)) ds,$$
$$u^{(0)}(t) = e^{it\Delta} \phi.$$

in a suitable space  $F^0[0, 1]$ . In our case the nonlinearity is

$$N(u) = u\partial_x u.$$

# Global well-posedness of the KdV equation

The key idea is to use a new class of spaces, called the  $X^{s,b}$  spaces introduced by Bourgain, Kenig-Ponce-Vega, and Klainerman-Machedon. They are defined by the norms

$$\|f\|_{X^{s,b}} := \|\widehat{f}(\xi, \tau) \langle \tau - \omega(\xi) \rangle^b \langle \xi \rangle^s\|_{L^2} \quad (6)$$

where  $\langle r \rangle := (1 + r^2)^{1/2}$  and  $\omega(\xi) := \xi^3$  is the KdV dispersion relation. Here  $f : \mathbb{R} \times \mathbb{R}$  and  $\widehat{f}$  denotes its Fourier transform in both variables.

For functions  $f : \mathbb{R} \times [a, b]$  we define

$$\|f\|_{X^{s,b}[a,b]} := \inf_{Ef=f \text{ on } \mathbb{R} \times [a,b]} \|Ef\|_{X^{s,b}},$$

where the infimum is taken over all the extension  $Ef$  of  $f$ .

# Global well-posedness of the KdV equation

- Notice that

$$X^{s,b} \hookrightarrow C(\mathbb{R} : H^s) \quad \text{if } b > 1/2.$$

- To close the fixed point argument we need to prove the linear estimates

$$\|e^{-t\partial_x^3} \phi\|_{X^{s,b}[0,1]} \lesssim \|\phi\|_{H^s}, \quad (7)$$

$$\left\| \int_0^t e^{-(t-s)\partial_x^3} N(s) ds \right\|_{X^{s,b}[0,1]} \lesssim \|N\|_{X^{s,b-1}[0,1]}, \quad (8)$$

and the bilinear estimates ( $b = 1/2+$ ),

$$\|\partial_x(fg)\|_{X^{0,b-1}} \lesssim \|f\|_{X^{0,b}} \|g\|_{X^{0,b}}. \quad (9)$$



# Global well-posedness of the KdV equation

The linear estimates are easy, for example

$$\begin{aligned}\|e^{-t\partial_x^3}\phi\|_{X^{s,b}[0,1]} &\leq \|\eta(t)e^{-t\partial_x^3}\phi\|_{X^{s,b}} \\ &\lesssim \|\widehat{\phi}(\xi)\widehat{\eta}(\tau - \xi^3)\langle \tau - \omega(\xi) \rangle^b \langle \xi \rangle^s\|_{L^2_{\xi,\tau}} \\ &\lesssim \|\phi\|_{H^s}.\end{aligned}$$

In view of the definitions, the bilinear estimates are equivalent to

$$\begin{aligned}\int_{\mathbb{R}^4} \frac{|\xi + \eta|H(\xi + \eta, \tau + \mu)F(\xi, \tau)G(\eta, \mu)}{\langle \tau + \mu - \omega(\xi + \eta) \rangle^{1-b} \langle \tau - \omega(\xi) \rangle^b \langle \mu - \omega(\eta) \rangle^b} d\xi d\eta d\tau d\mu \\ \lesssim \|F\|_{L^2} \|G\|_{L^2} \|H\|_{L^2}\end{aligned}\tag{10}$$

where

$$\begin{aligned}F(\xi, \tau) &:= \widehat{f}(\xi, \tau)\langle \tau - \omega(\xi) \rangle^b, \\ G(\xi, \tau) &:= \widehat{g}(\xi, \tau)\langle \tau - \omega(\xi) \rangle^b.\end{aligned}$$

# Global well-posedness of the KdV equation

The point is that the denominator cannot be small, since

$$\omega(\xi + \eta) - \omega(\xi) - \omega(\eta) = (\xi + \eta)^3 - \xi^3 - \eta^3 = 3\xi\eta(\xi + \eta).$$

The bounds (10) follow by dyadic decompositions in the variables  $\xi, \eta, \tau - \omega(\xi), \mu - \omega(\eta)$ . An important case is when

$$\xi \approx N \gg 1, |\eta| \lesssim 1/N^2, |\tau - \omega(\xi)| \lesssim 1, |\mu - \omega(\eta)| \lesssim 1.$$