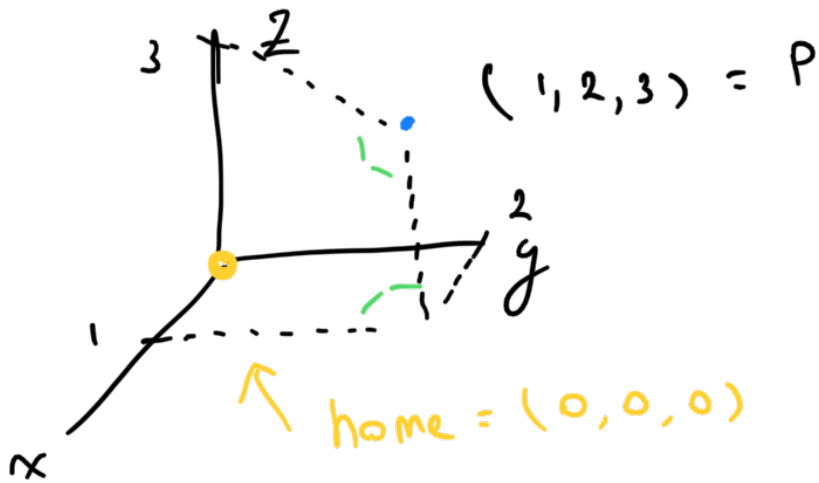


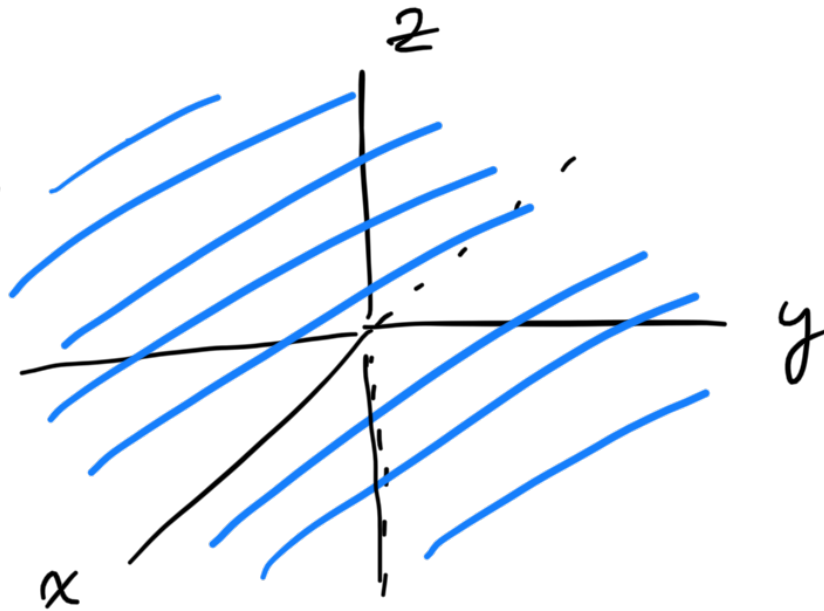
12.1 : 3D coordinates

describes all points in 3-space uniquely.

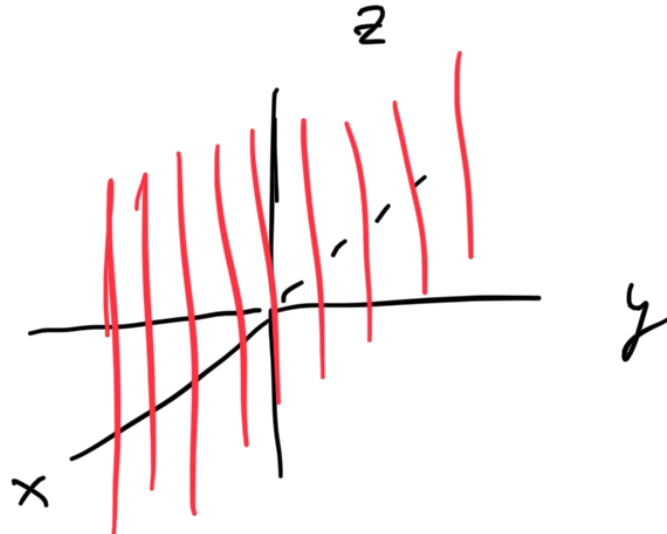


Coordinate planes:

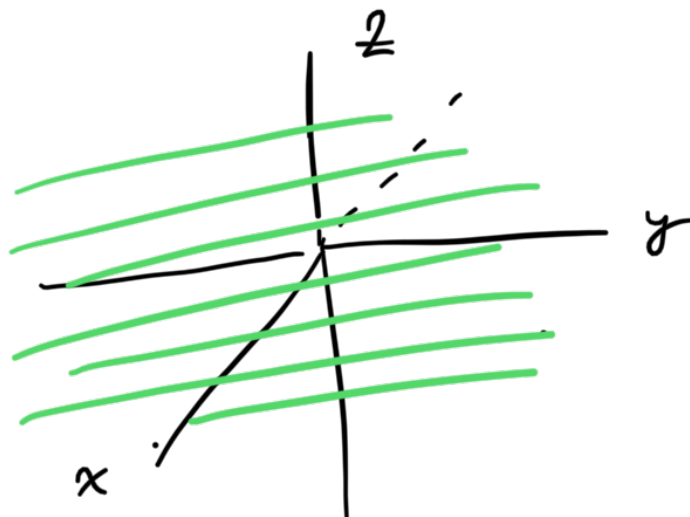
$x = 0$



$y = 0$

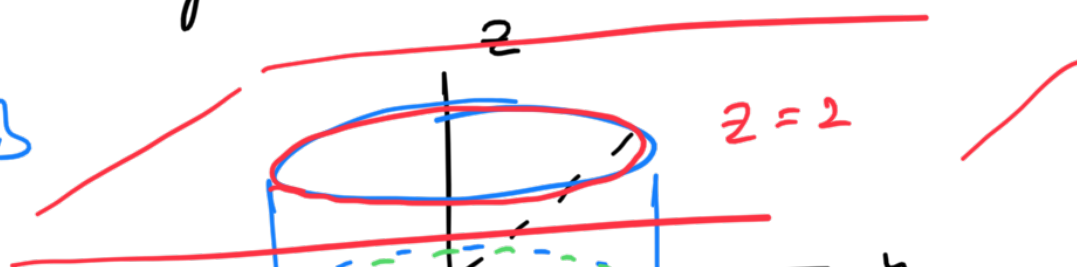


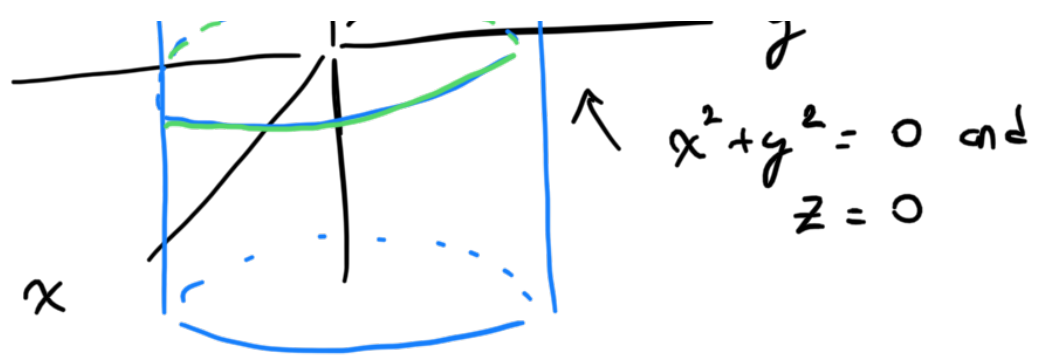
$z = 0$



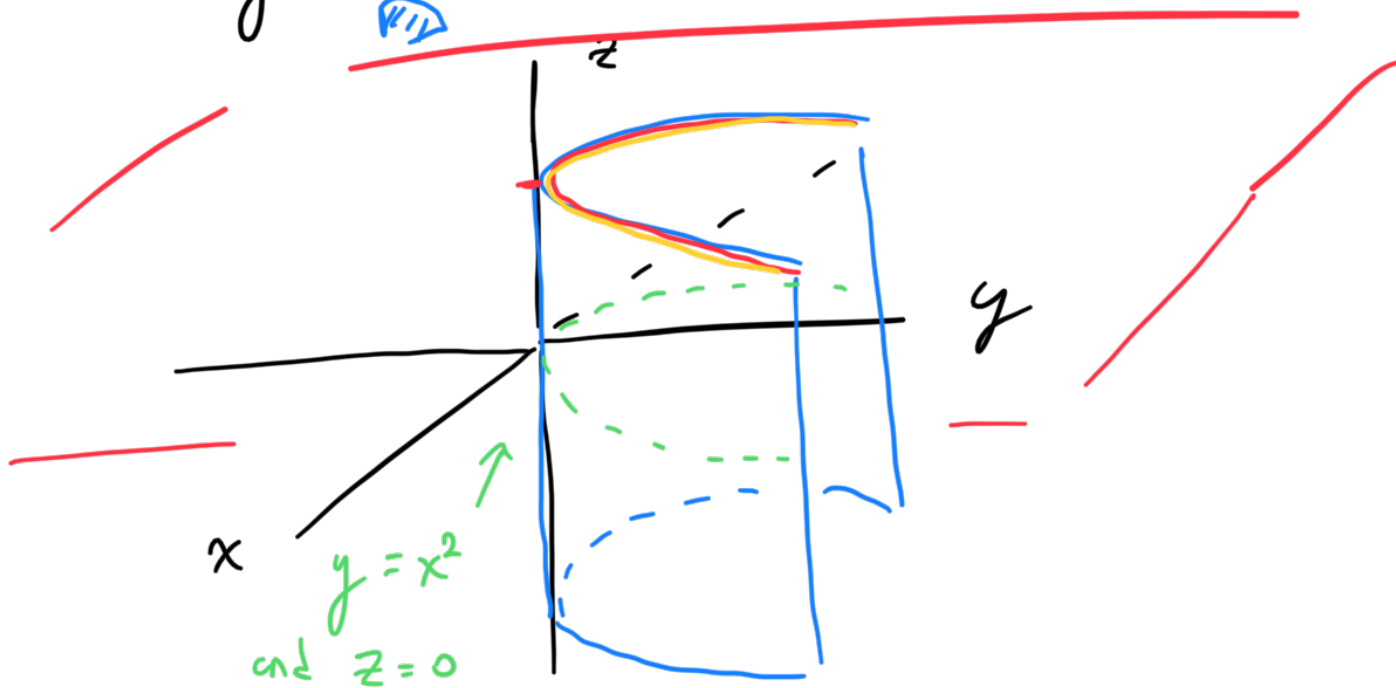
What about $x^2 + y^2 = 9$ and $z = 2$

$x^2 + y^2 = 9$

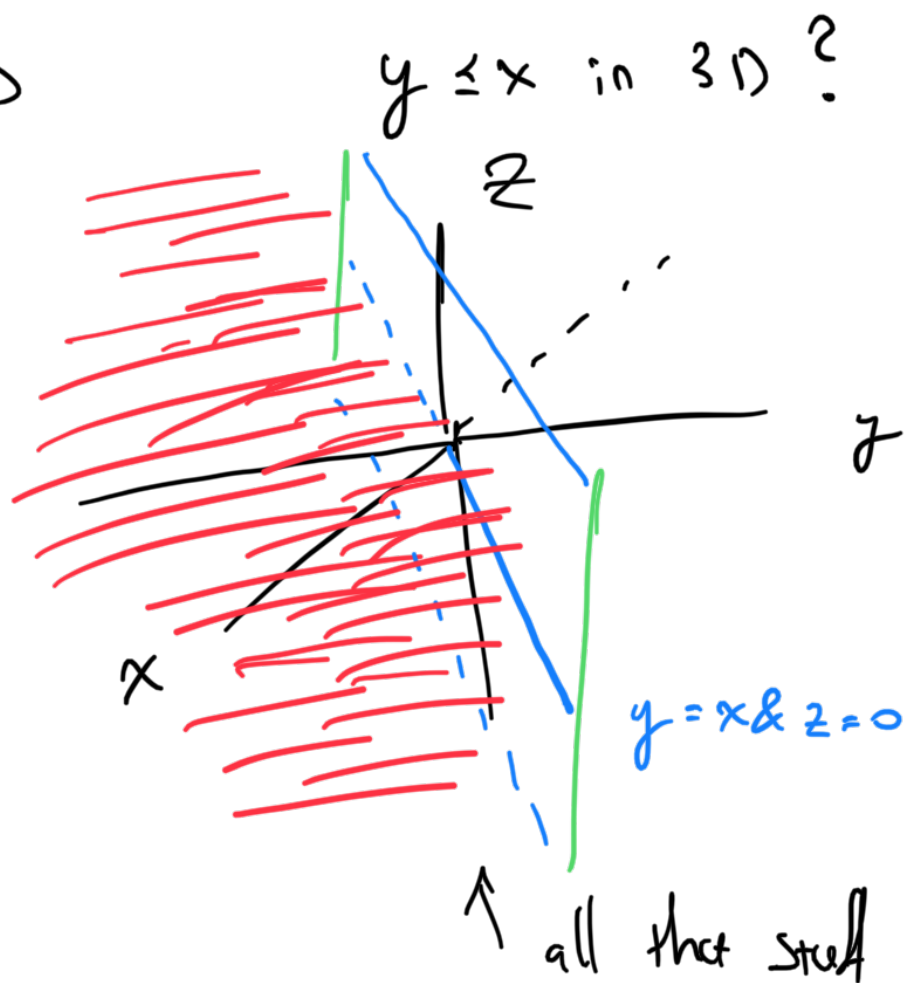
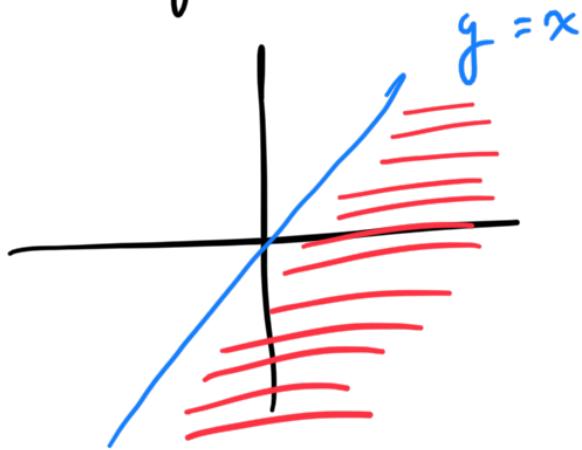




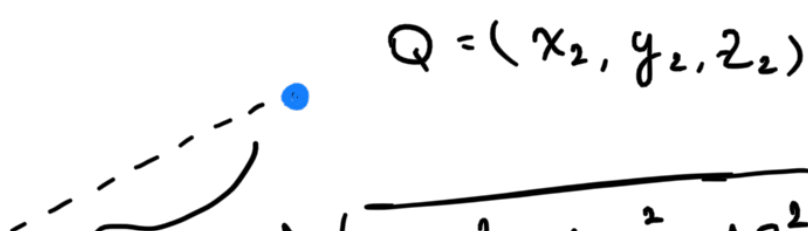
ex: $y = x^2$ and $z = 2$



ex: $y \leq x$ in 2D



Distance in 3 space?

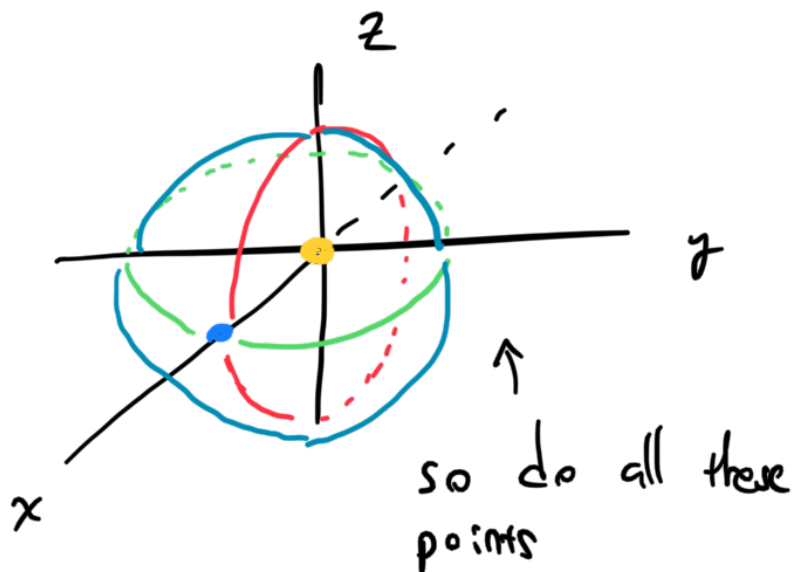
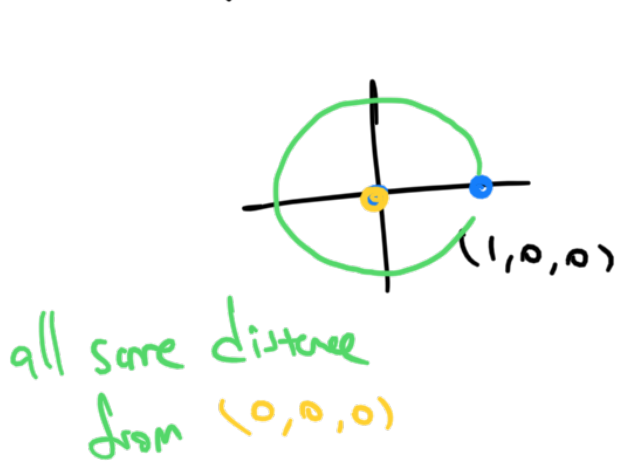


$$\Delta w = w_2 - w_1$$

 $d = \sqrt{\Delta x^2 + \Delta y^2 + \Delta z^2}$

$$p = (x_1, y_1, z_1)$$

ex: $d((0,0,0), (1,0,0)) = \sqrt{\Delta^2 + \Delta^2 + \Delta^2} = \sqrt{1} = 1$



Observation: The set of all points a fixed distance from a fixed point = Sphere!

algebraically $\therefore \sqrt{(x-x_0)^2 + (y-y_0)^2 + (z-z_0)^2} = r$

$$\underline{v} \quad (x-x_0)^2 + (y-y_0)^2 + (z-z_0)^2 = r^2$$

point (x_0, y_0, z_0) is center and r is the radius.

ex: Find the radius and center of

$$x^2 + y^2 + z^2 - 4z = 0$$

$$x^2 + y^2 + z^2 - 4z = 0$$

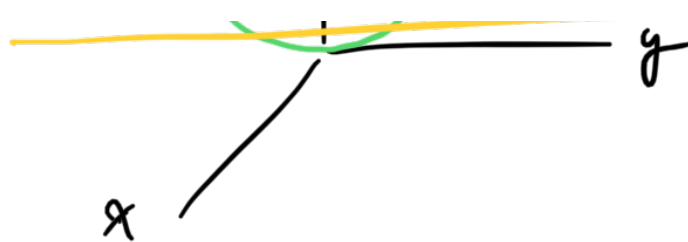
$$x^2 + y^2 + z^2 - 4z + \underline{4} = \underline{4}$$

$$x^2 + y^2 + (z - 2)^2 = 4$$

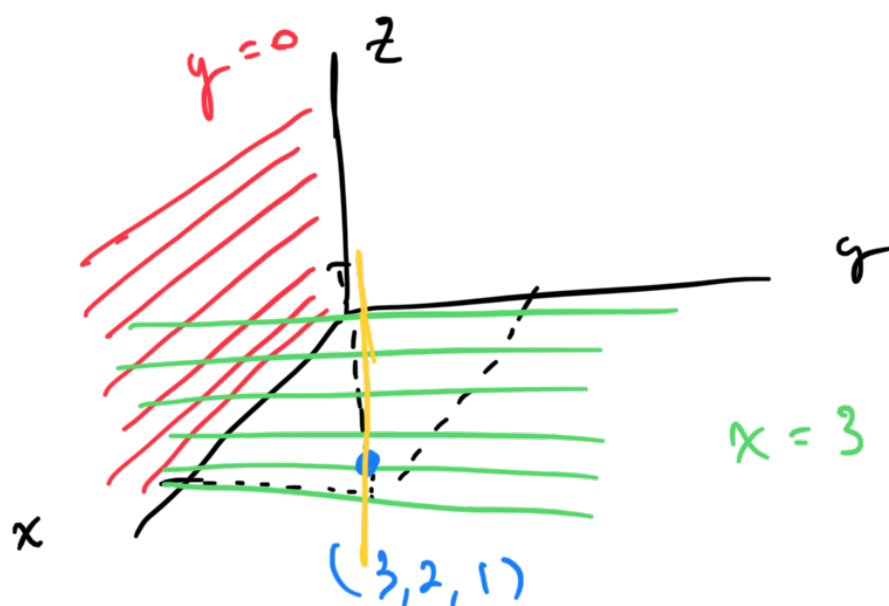
$$\frac{-4}{2} \rightarrow -2 \rightarrow 4$$

center = (0, 0, 2)
radius = 2





ex: Find plane through $(3, 2, 1)$
perpendicular to xz -plane.



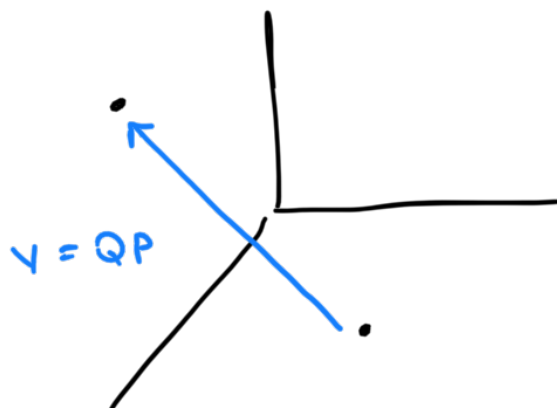
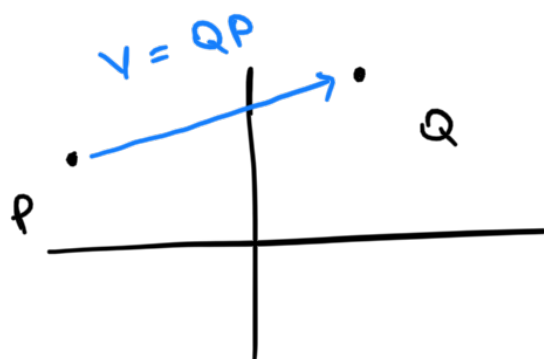
Line through $(3, 2, 1)$ parallel to z -axis?

$$x=3 \text{ \& } y=2$$

12.2 Vectors

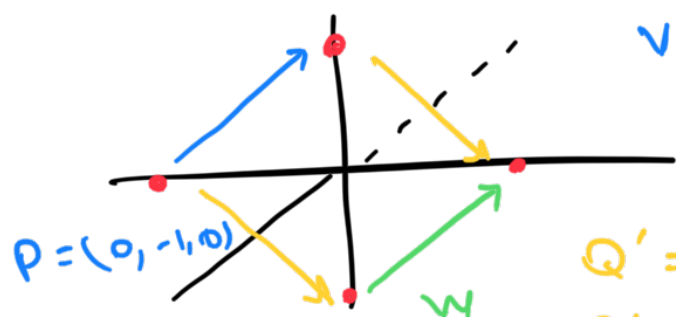
Vectors algebraically $v = (x, y) \in \mathbb{R}^2$ or $v = (x, y, z) \in \mathbb{R}^3$

Represent direction and magnitude



Book uses $\langle \rangle$, but I'm going to avoid that, just stylistic choice.

ex: $Q = (0, 0, 1)$



$$v = QP = (0, 0, 1) - (0, -1, 0) = (0, 1, 1)$$

$Q' = Q$ moved over $(0, 1, -1)$

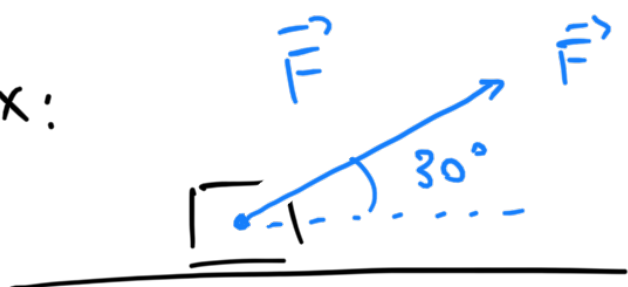
$P' = P$ moved over $(0, 1, -1)$

$$w = Q'P' = (0, 1, 0) - (0, 0, -1) = (0, 1, 1)$$

Every vector $v \in \mathbb{R}^3$ breaks up into components

$$v = (v_x, v_y, v_z)$$

ex:



$\vec{F}$ is 20 lb force then

$$\vec{F} = (20 \cos 30^\circ, 20 \sin 30^\circ)$$

$$= \left(20 \cdot \frac{\sqrt{3}}{2}, 20 \cdot \frac{1}{2} \right)$$

$$= (10\sqrt{3}, 10) \text{ lb}$$

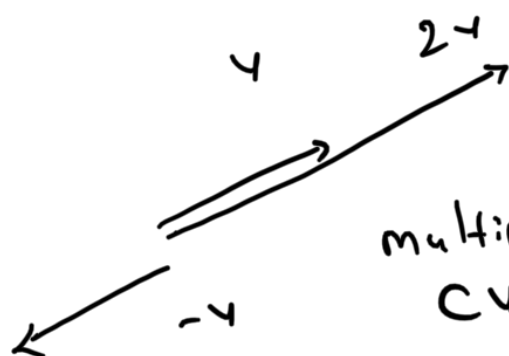
$$F_x = 10\sqrt{3} \quad F_y = 10 \text{ (lbs)}$$

Each vector has a direction and magnitude (except 0)

in previous example, $|F| = 20$, or $|v| = \sqrt{2}$

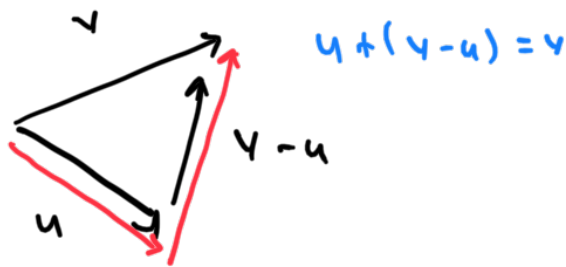
$$|v| = \sqrt{v_x^2 + v_y^2 + v_z^2} \leftarrow \text{magnitude}$$

Vector algebra:



multiply vectors
 cv

get all nine things



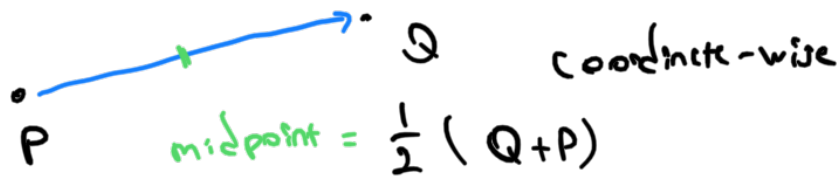
$$u + v = v + u \quad (u + v) + w = u + (v + w)$$

$$u + 0 = u \quad u + (-u) = 0$$

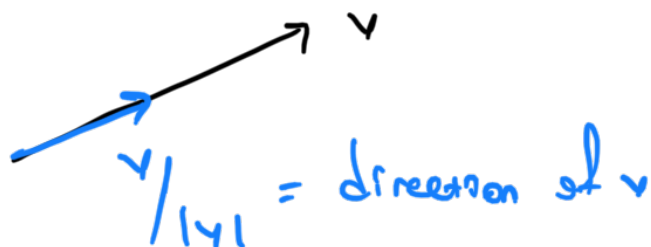
$$0u = 0 \quad 1u = u$$

$$a(bu) = (ab)u \quad a(u+v) = au + av$$

$$(a+b)u = au + bu$$



direction:



makes sense for all $v \neq 0$.

Mention some notation: $\vec{F} = (F_x, F_y, F_z)$
 $= F_x \hat{i} + F_y \hat{j} + F_z \hat{k}$

$$\hat{i} = (1, 0, 0)$$

$$\hat{j} = (0, 1, 0)$$

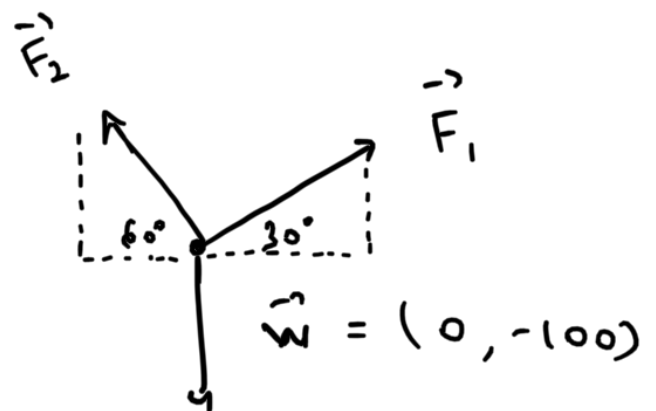
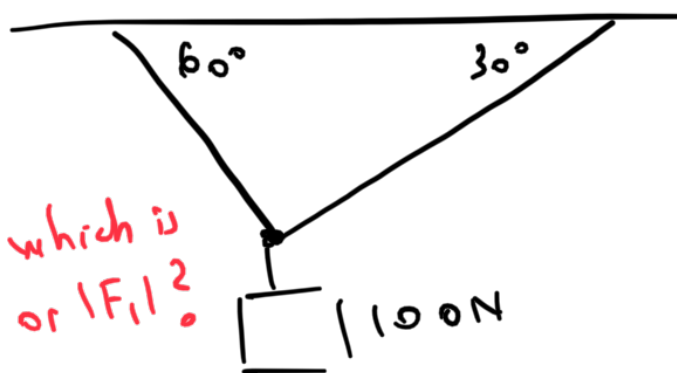
$$\hat{k} = (0, 0, 1)$$

ex:

9 pg. 729

Intuitively which is bigger $|F_2|$ or $|F_1|$?

Find magnitudes



$$(\star) \vec{F}_1 + \vec{F}_2 + \vec{W} = \vec{0}$$

$$(F_{1x}, F_{1y}) + (F_{2x}, F_{2y}) = (0, +100)$$

$$F_{1x} + F_{2x} = 0$$

$$F_{1x} = |F_1| \cos 30^\circ$$

$$F_{1y} + F_{2y} = +100$$

$$F_{1y} = |F_1| \sin 30^\circ$$

$$F_{2x} = -|F_2| \cos 60^\circ$$

$$F_{2y} = |F_2| \sin 60^\circ$$

$$|F_1| \left(\frac{\sqrt{3}}{2}\right) - |F_2| \left(\frac{1}{2}\right) = 0, \quad |F_1| = \frac{1}{\sqrt{3}} |F_2|$$

$$|F_1| \left(\frac{1}{2}\right) + |F_2| \left(\frac{\sqrt{3}}{2}\right) = 100 \quad \leftarrow$$

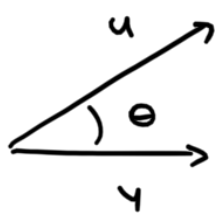
$$\left(\frac{1}{2\sqrt{3}} + \frac{\sqrt{3}}{2}\right) |F_2| = 100$$

$$|F_2| = 100 / \text{mess}$$

$$|F_1| = \frac{1}{\sqrt{3}} |F_2|$$

12.3: Dot Product

Given two vectors $u, v \in \mathbb{R}^3$, how to find $\angle(u, v)$?



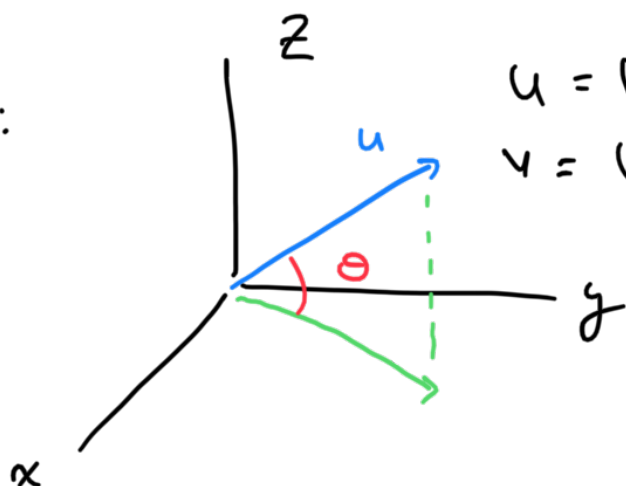
$$\theta \in [0, \pi]$$

$$\text{theorem: } \theta = \arccos \left(\frac{\overbrace{u \cdot v}^{u \cdot v}}{|u||v|} \right)$$

$$u \cdot v = u_1 v_1 + u_2 v_2 + u_3 v_3 \in \mathbb{R} \quad \underline{\text{not}} \text{ another vector.}$$

$$\text{Another way of saying this is } \cos \theta = \frac{u \cdot v}{|u||v|}$$

ex:



$$u = (1, 1, 1)$$

$$v = (1, 1, 0)$$

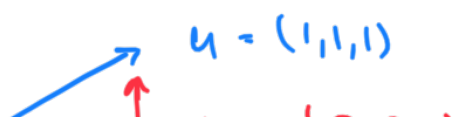
$$\cos \theta = \frac{u \cdot v}{|u||v|} = \frac{1+1+0}{\sqrt{3}\sqrt{2}}$$

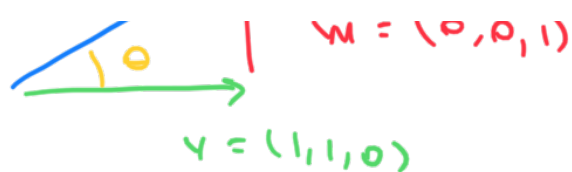
$$= \frac{\sqrt{2}}{\sqrt{3}}$$

$$\theta = \arccos\left(\frac{\sqrt{2}}{\sqrt{3}}\right) > 45^\circ \text{ or } < 45^\circ$$

$$\approx 35^\circ$$

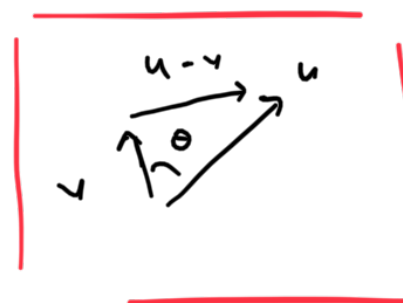
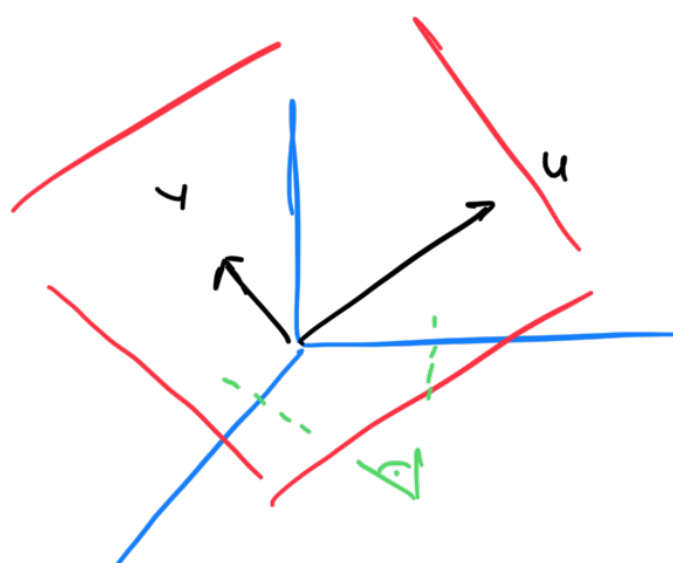
$$\text{or } = 45^\circ?$$





$$\Theta = \arctan\left(\frac{|w|}{|v|}\right) \text{ more } v \text{ than } w.$$

Why does $\cos \Theta = \frac{u \cdot v}{|u||v|}$? Use some trig on this picture.



law of cosines
 $|u - v|^2 = |u|^2 + |v|^2 - 2|u||v|\cos \Theta$

dot product gives us a nice way to see if two vectors are perpendicular (orthogonal).

$$\cos \Theta = \frac{u \cdot v}{|u||v|} = 0 \text{ iff } \underline{u \cdot v = 0}.$$

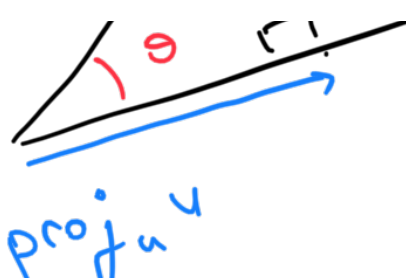
if want to see if $(1, 1)$ and $(1, -1) \perp$
 just check with dot product!

Nice algebra : $u \cdot v = v \cdot u$ $(cu) \cdot v = c(u \cdot v)$
 $u \cdot (v + w) = u \cdot v + u \cdot w$
 $u \cdot u = |u|^2$ $\vec{0} \cdot u = 0$

ex:



$\text{proj}_u v = \underbrace{(|v| \cos \Theta)}_{\in \mathbb{R}} \underbrace{(\text{direction } u)}_{\text{vector}}$

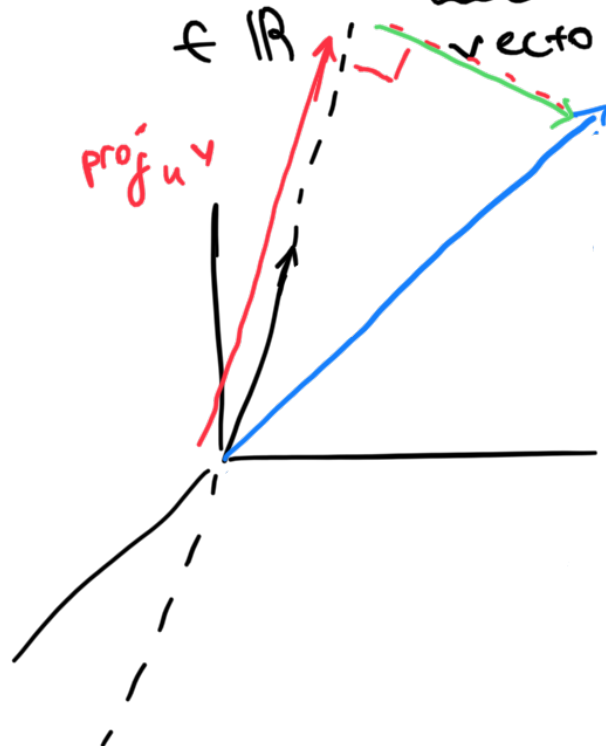


$$u = |u| \left(\frac{u \cdot v}{|u||v|} \right) \left(\frac{1}{|u|} \right)$$

$$= \left(\frac{u \cdot v}{|u|} \right) \left(\frac{u}{|u|} \right) = \left(\frac{u \cdot v}{|u|^2} \right) u$$

$\in \mathbb{R}$ vector

ex: $u = (1, 1, 2)$
 $v = (3, 3, 3)$



$$\text{proj}_u v = \left(\frac{u \cdot v}{|u|^2} \right) \frac{u}{|u|} = \frac{(3+3+6)}{\sqrt{6}} \left(\frac{(1, 1, 2)}{\sqrt{6}} \right)$$

$$= \frac{12}{6} = 2(1, 1, 2) = (2, 2, 4)$$

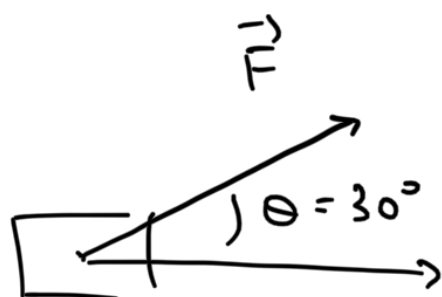
What orthogonal part, then $v - \text{proj}_u v = (3, 3, 3) - (2, 2, 4)$
 $= (1, 1, -1)$

Sanity check $(1, 1, -1) \perp u$?

$$1+1-2=0 \checkmark$$

Work: $W = \vec{F} \cdot \vec{D}$ where $\vec{F}$ force over displacement $\vec{D}$.

ex:



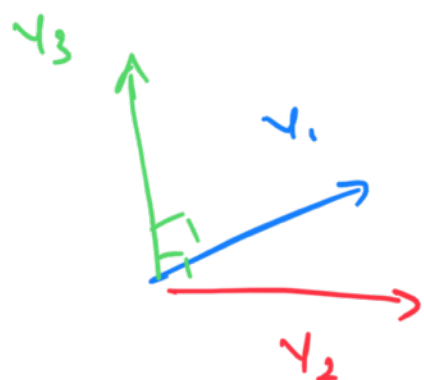
direction displacement

Say $|D| = \frac{4}{\sqrt{2}}$ m and $|\vec{F}| = 100$ N

$$\begin{aligned}
 \text{Then } \vec{F} \cdot \vec{D} &= |\vec{F}| |\vec{D}| \cos \theta = (100 \cdot \frac{4}{\sqrt{3}} \cdot (\frac{\sqrt{3}}{2})) \\
 &= 200 \text{ J Joules} = \text{N} \cdot \text{m}
 \end{aligned}$$

12.4: Cross-Products

Given two vectors $v_1, v_2 \in \mathbb{R}^3$, they span a plane (typically). Then up to scale, there's a natural choice of a complementary vector. Just take one $\perp$ to the plane. Here's a cartoon.



However, there's some ambiguity. There's a bunch of choices; let's agree on an orientation. Let's say that

3-ordered vectors are standardly oriented or right-hand rule oriented if you can rotate, scale, shear, etc to agree with $(\hat{i}, \hat{j}, \hat{k})$. So the set (v_1, v_2, v_3) defined above is not standardly oriented.

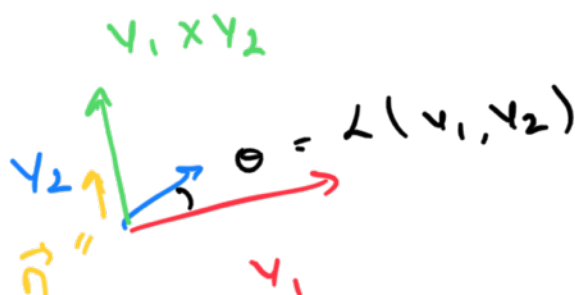
(Show them the hard thing)

We define the cross product of v_1, v_2 to be

$$v_1 \times v_2 = (|v_1||v_2|\sin\theta)\vec{n}$$
 where $\vec{n}$ is

a unit vector so that $(v_1, v_2, \vec{n})$ is standard orientation,
and $\theta = \angle(v_1, v_2)$.

Here's picture:



Here are some properties: (pg. 735)

$$(i). (ru) \times (sv) = (rs) u \times v$$

$$(ii). u \times (v + w) = u \times v + u \times w$$

$$(iii). v \times u = -(u \times v)$$

$$(iv). (v + w) \times u = v \times u + w \times u$$

$$(v). \vec{0} \times u = \vec{0}$$

$$(vi). u \times (v \times w) = (u \cdot w)v - (u \cdot v)w$$

$$(vii). u \times v = 0 \text{ for } u, v \neq 0 \text{ iff } u, v \text{ are parallel.}$$

Most fundamental ones to remember are

$$\hat{i} \times \hat{j} = \hat{k} \quad \hat{j} \times \hat{k} = \hat{i} \quad \hat{k} \times \hat{i} = \hat{j}$$

Easy to remember by picture



example: let $u, v \in \mathbb{R}^3$. Form parallelogram as pictured below. Then $|u \times v| = \text{Area}(u, v)$.



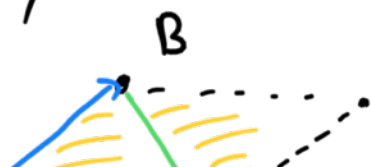
$$\text{Area} = |u \times v|$$

Just because



$$\begin{aligned} \text{Area} &= |\text{base}| |\text{height}| \\ &= |v| (|u| \sin \theta) \\ &= |u \times v| \quad \text{bc } |\mathbf{n}| = 1 \end{aligned}$$

Similarly if have 3-generic points in $\mathbb{R}^3$, then



form parallelogram take the area



or $\frac{1}{2}$ it to get area of triangle of $\triangle ABC$.

That is, $\text{Area } \triangle ABC = \frac{1}{2} |\vec{AB} \times \vec{AC}|$

How to actually calculate it? Before stating, let us recall determinant of a 2×2 -matrix.

$$\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = ad - bc = \begin{vmatrix} a & b \\ c & d \end{vmatrix}$$

(actually the signed area of parallelogram formed by $\begin{pmatrix} a \\ c \end{pmatrix}$ and $\begin{pmatrix} b \\ d \end{pmatrix}$ in $\mathbb{R}^2$)

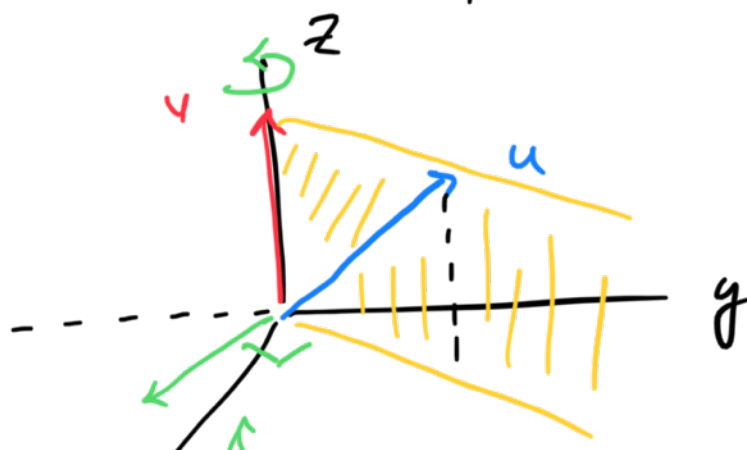
Okay, so $u = (u_1, u_2, u_3)$ and $v = (v_1, v_2, v_3)$

then $u \times v = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix}$

$$= \hat{i} \begin{vmatrix} u_2 & u_3 \\ v_2 & v_3 \end{vmatrix} - \hat{j} \begin{vmatrix} u_1 & u_3 \\ v_1 & v_3 \end{vmatrix} + \hat{k} \begin{vmatrix} u_1 & u_2 \\ v_1 & v_2 \end{vmatrix}$$

(Show then how to see this as minors of matrix)

ex: Find a unit vector perpendicular to the plane generated by $(1, 1, 1)$ and $(0, 0, 2)$



✓ this intuitively will do, say $w = (1, -1, 0)$
(kinda)

$$u \times v = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 1 & 1 \\ 0 & 0 & 2 \end{vmatrix} = \hat{i} \begin{vmatrix} 1 & 1 \\ 0 & 2 \end{vmatrix} - \hat{j} \begin{vmatrix} 1 & 1 \\ 0 & 2 \end{vmatrix} + \hat{k} \begin{vmatrix} 1 & 1 \\ 0 & 0 \end{vmatrix}$$

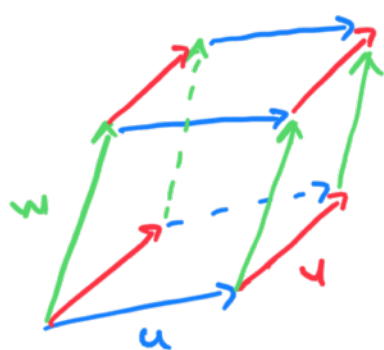
$$= (2, -2, 0)$$

then divide out by norm, $w = (2, -2, 0) / \sqrt{8}$

However, note, $w \parallel$ to our original choice $(1, -1, 0)$.

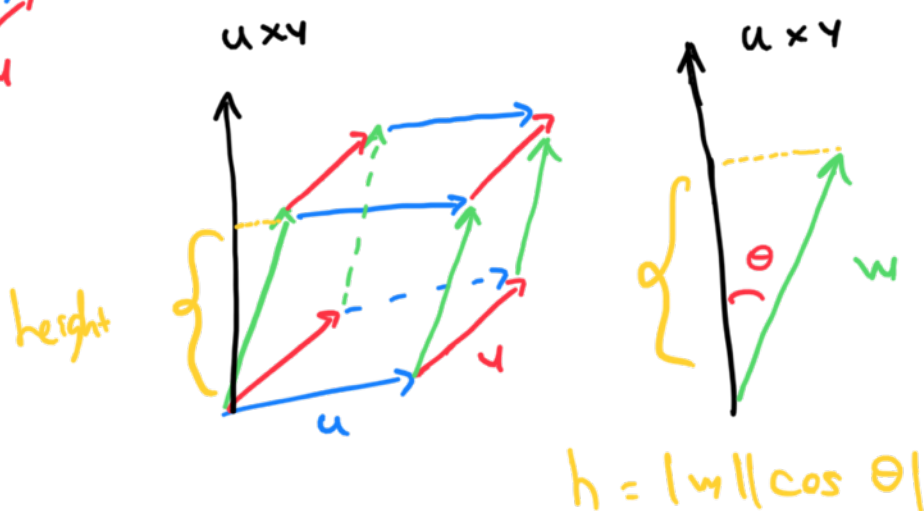
Also note right hand rule.

- Note
- 1 vector defines a line segment
 - 2 vectors determine a parallelogram (typically)
 - 3 vectors determine a ... parallelepiped



What the volume of this.

Recall Volume = area $\cdot$ height



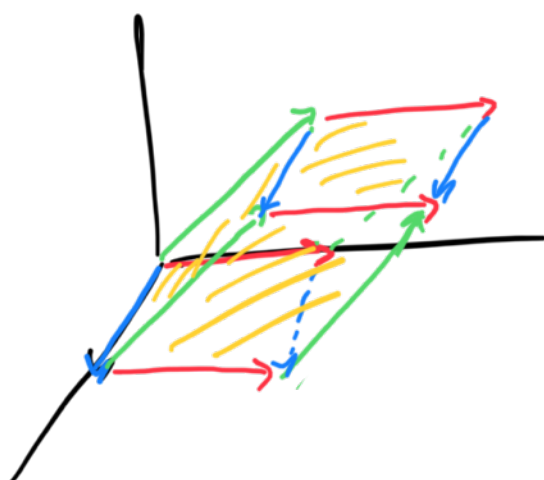
thus Volume = (Area of parallelogram (u, v)) (height)

$$= |u \times v| |w| \cos \theta = |(u \times v) \cdot w|$$

if you work it out...

$$= \begin{vmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix}$$

ex: $u = (1, 0, 0)$ $v = (0, 1, 0)$ $w = (0, 1, 1)$



Volume = 1 (why?)

Verify:

$$V = \begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \end{vmatrix}$$

$$= 1 \begin{vmatrix} 1 & 0 \\ 1 & 1 \end{vmatrix} - 0 + 0$$

$$= 1$$

Torque: Vector quantity that expresses turning (kinda)

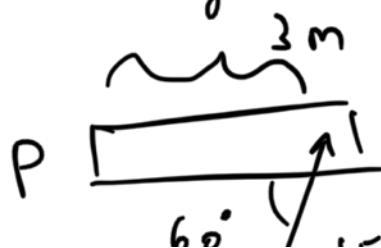
Just think of opening door.



if push is it easier to open at point A or B?

$$\vec{\tau} = \vec{r} \times \vec{F}$$

Calculate magnitude of torque exerted by $\vec{F}$ at pivot in figure (example 5 pg. 738)



$$\begin{aligned} \text{So } |\tau| &= |\vec{r}| |\vec{F}| \sin \theta \\ &= 3(2) \sin 60^\circ \end{aligned}$$

$$/ |F| = 20 \text{ N}$$

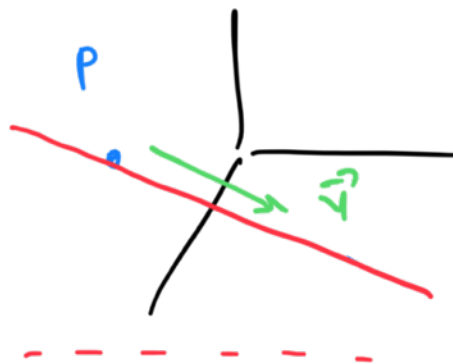
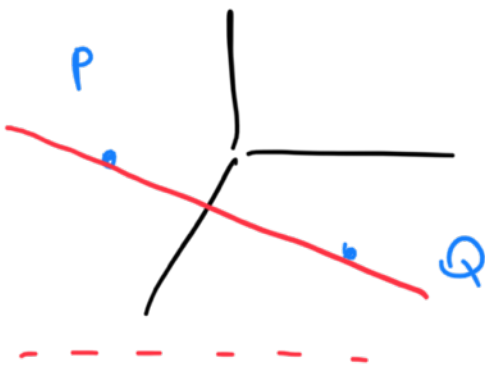
$$= 60 \cdot \frac{\sqrt{3}}{2} \text{ Nm}$$

$$= 30\sqrt{3} \text{ Nm.}$$

12.5: Lines and Planes

A line is uniquely determined by either

- 2 distinct points
- 1 point and a non-zero vector.



Parametric equation for a line. Let v and P be as above. The line determined by P and v is algebraically given by $\vec{r}(x) = P + x v$ for $x \in \mathbb{R}$.

the idea being x is time along the line. $x=0$ is starting point, namely P .

Another way of writing this is

$$x = x_0 + x v_1$$

$$y = y_0 + x v_2$$

$$z = z_0 + x v_3$$

$$\sim \vec{r}(x) = P + x v$$

$$\text{with } P = (x_0, y_0, z_0)$$

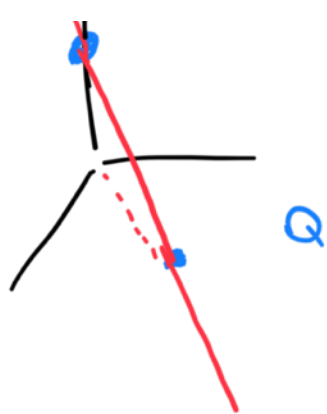
$$v = (v_1, v_2, v_3).$$

ex: Parametrize line joining $P = (0, 0, 1)$

$$Q = (1, 1, 0)$$

$\vec{v}$

in such a way that



located at the midpoint of P and Q.

$$\text{midpoint } (P, Q) = \frac{1}{2} P + \frac{1}{2} Q = \left(\frac{1}{2}, \frac{1}{2}, \frac{1}{2}\right).$$

$$\text{Vector defined by } P, Q = \vec{PQ} = (1, 1, 0) - (0, 0, 1)$$

$$= (1, 1, -1)$$

$$\text{equation: } \vec{r}(x) = \left(\frac{1}{2}, \frac{1}{2}, \frac{1}{2}\right) + x(1, 1, -1).$$

unit speed meaning $r(x) = P + x\vec{v}$ with $|\vec{v}| = 1$.

$$\vec{r}(x) = \left(\frac{1}{2}, \frac{1}{2}, \frac{1}{2}\right) + x \left(\frac{(1, 1, -1)}{\sqrt{3}} \right)$$

↑ unit vector

Planes: Planes are defined by

- 1 point, 2 vectors
- (typically) - 3 points
- 2 points, 1 vector
- 1 point, 1 vector ← (less obvious)
- etc

Algebraically they are described by the set of all $(x, y, z) \in \mathbb{R}^3$

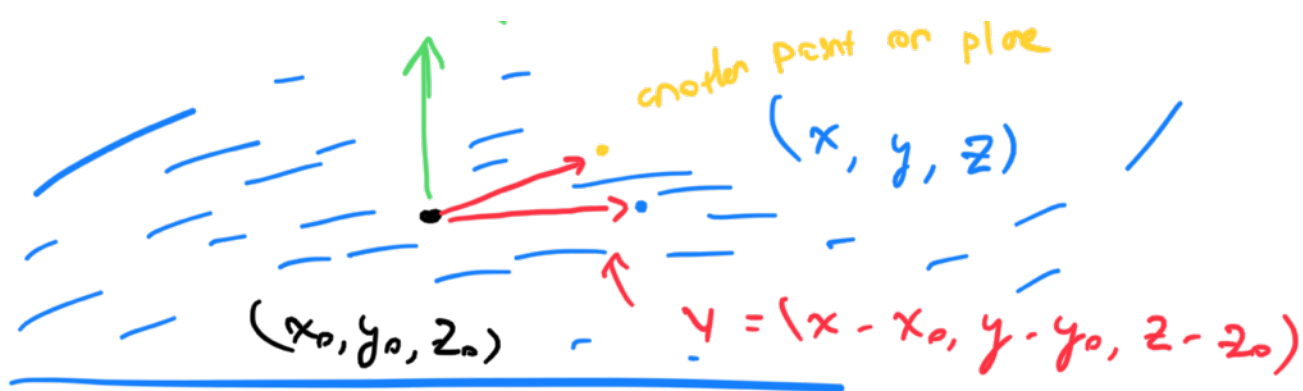
$$A(x - x_0) + B(y - y_0) + C(z - z_0) = 0$$

for fixed $A, B, C \in \mathbb{R}$ and a point $P = (x_0, y_0, z_0)$.

Normal equation is $\approx$ to

$$(A, B, C) \cdot (x - x_0, y - y_0, z - z_0) = 0$$

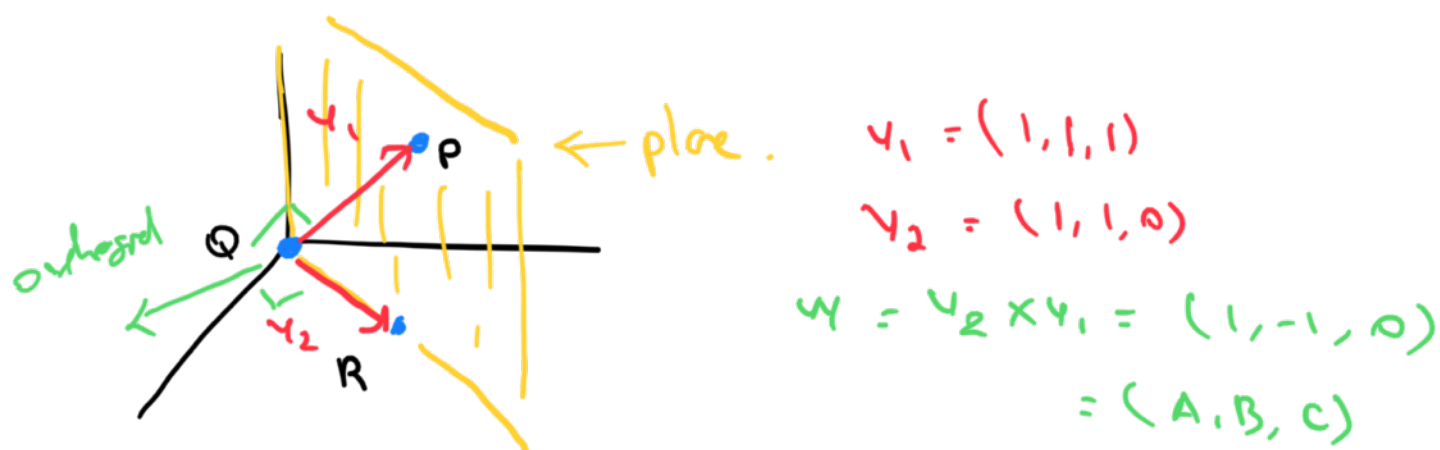
$$(A, B, C)$$



note vector $(A, B, C) \perp$ plane

ex: Find equation of plane containing points

$$P = (1, 1, 1) \quad Q = (0, 0, 0) \quad R = (1, 1, 0)$$



Equation: $A(x - x_0) + B(y - y_0) + C(z - z_0) = 0$

here choose point $(1)(x - 1) + (-1)(y - 1) + 0(z - 0) = 0$

R, does it matter though?

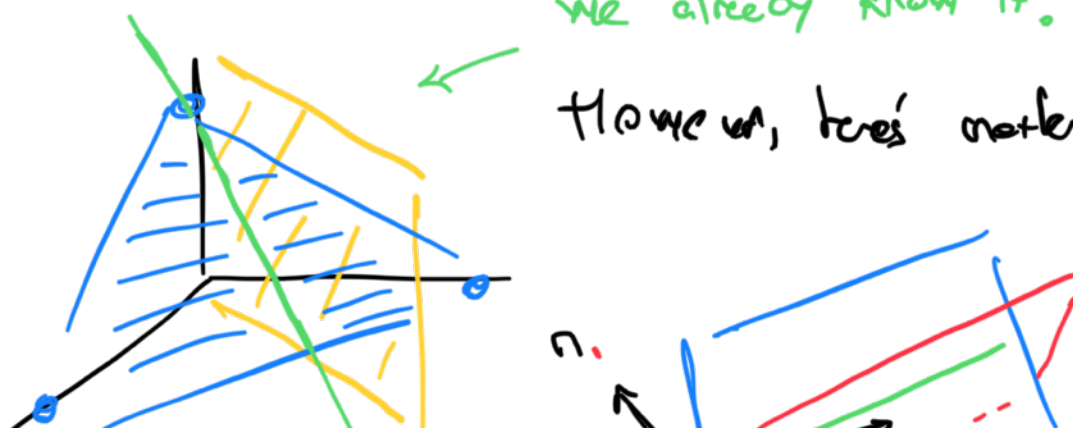
$$(x - 1) - y + 1 = 0, \quad \underline{\underline{x - y = 0}}$$

ex: let plane 1 be defined by $P_1: x - y = 0$
plane 2 be defined by $P_2: x + y + z = 1$

determine the equation of the line intersecting these two planes.

we already know it!

However, here's another way.



$$n_1 = (1, -1, 0)$$

$$n_2 = (1, 1, 1)$$

$$n_1 \times n_2 = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & -1 & 0 \\ 1 & 1 & 1 \end{vmatrix}$$

$$v = \hat{i}(-1) - \hat{j}(1) + \hat{k}(2) = (-1, -1, 2) \sim (1, 1, -2)$$

Quick sanity: $n_1 \cdot v = 0$ and $n_2 \cdot v = 0$

all need is a point on both P_1 & P_2 .

$$\begin{aligned} x - y &= 0 \\ x + y + z &= 1 \end{aligned}$$

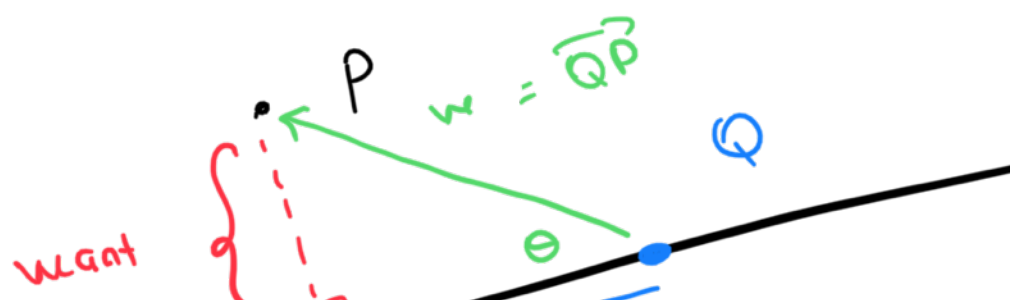
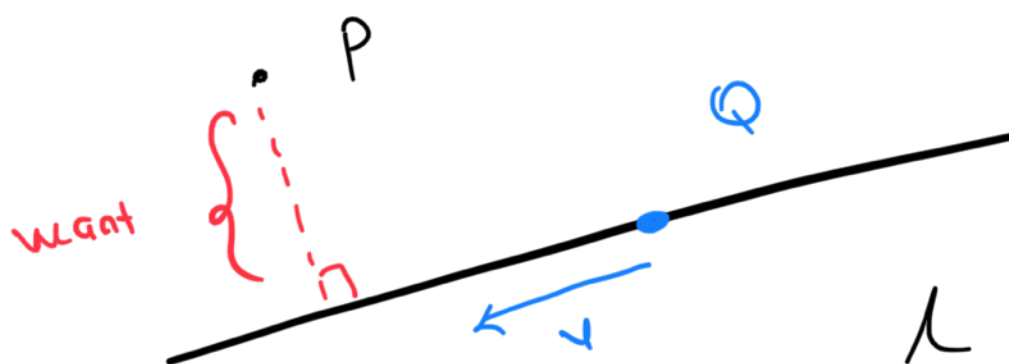
$P = (0, 0, 1)$ is good.

$l: (0, 0, 1) + t(1, 1, -2)$. Good way to check?

Ensure $l \subseteq P_1$ and $l \subseteq P_2$!

Distances:

ex: Point and a line



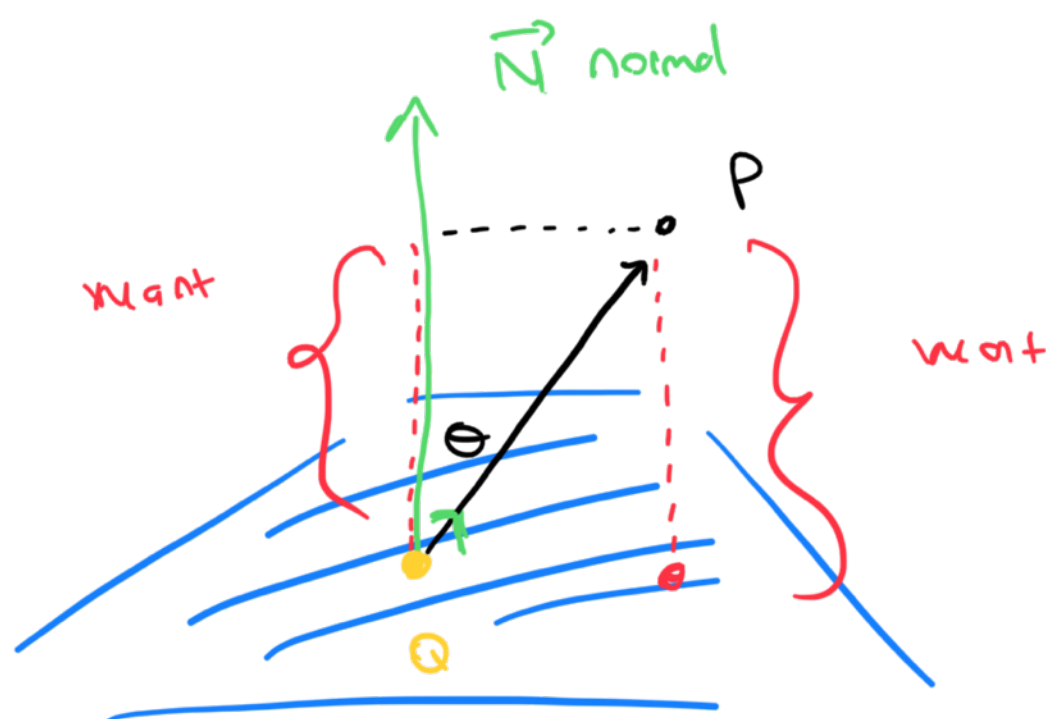
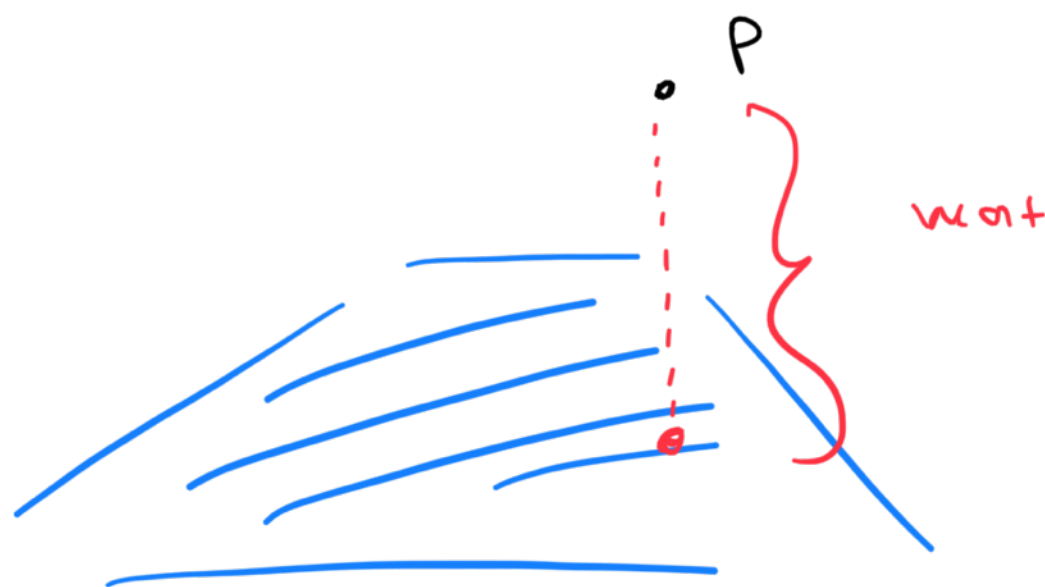


$$\text{want } |\vec{QP}| |\sin \theta| = \frac{|\vec{QP}| |\vec{v}| |\sin \theta|}{|\vec{v}|}$$

$$\underline{\underline{\text{dist}(P, l) = |\vec{QP} \times \vec{v}| / |\vec{v}|}}$$

$\vec{v}$ parallel to l
and Q any
point on it

ex: Distance between point and a plane?



$$\begin{aligned} \text{distance is equal to } & |\vec{QP}| |\cos \theta| \\ & = \frac{|\vec{QP}| |\vec{N}| |\cos \theta|}{|\vec{N}|} \end{aligned}$$

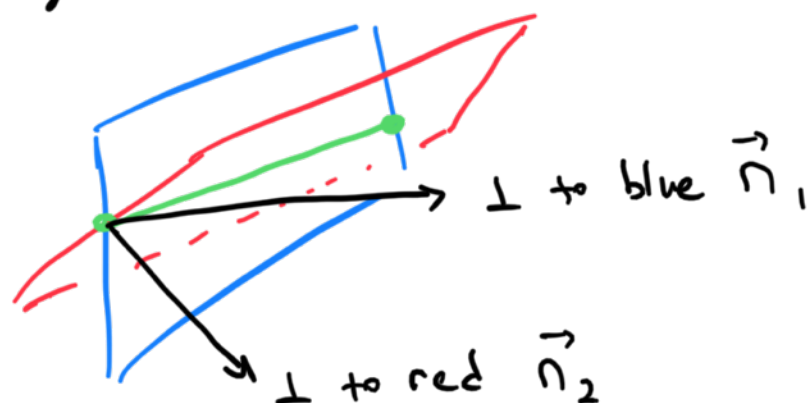
→ → . .

$$\text{dist}(P, \text{plane}) = |QP \cdot N| / |\vec{N}|$$

$\vec{N}$ normal to plane

Q any point on it

ex: Angle between two planes



$$\cos(\theta(\text{plane}_1, \text{plane}_2)) = \frac{n_1 \cdot n_2}{|n_1| |n_2|} \quad \text{where } n_1, n_2 \text{ normal to plane 1, plane 2 respectively}$$

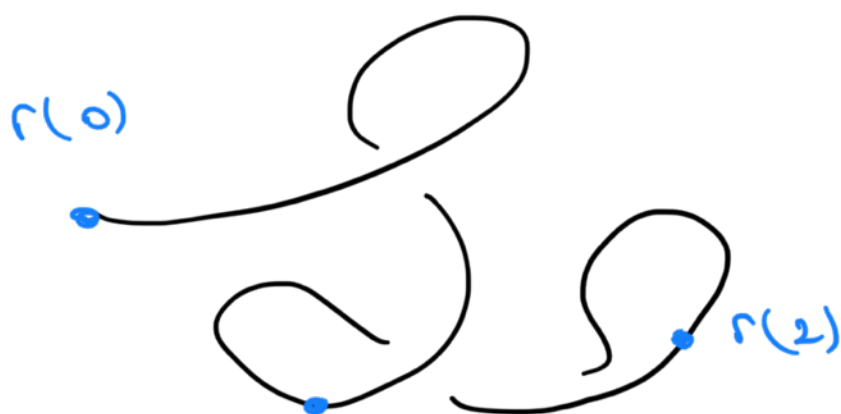
13.1: Curves in space and tangents

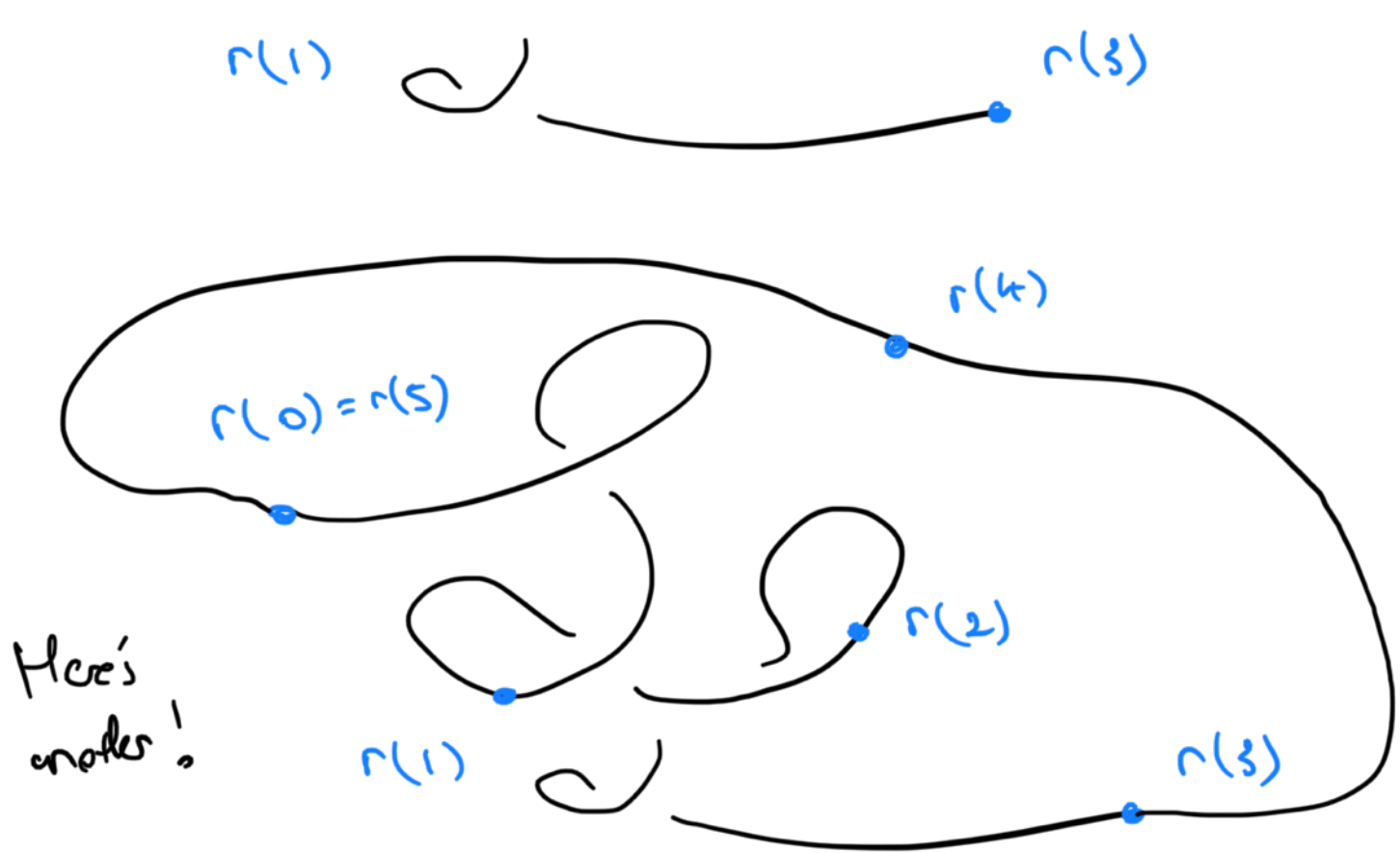
A curve in space is a map

$$\vec{r}: \mathbb{R} \longrightarrow \mathbb{R}^3 \text{ typically written as}$$

$$\vec{r}'(t) = (x(t), y(t), z(t)). \text{ You imagine}$$

the t -parameter is time. Here's a curve.





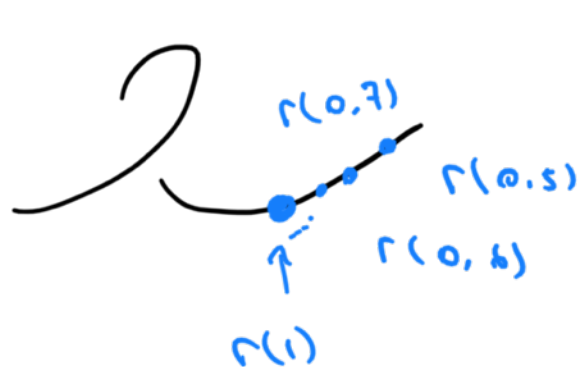
typically we want our curves to be smooth meaning differentiable. Want to avoid stuff like



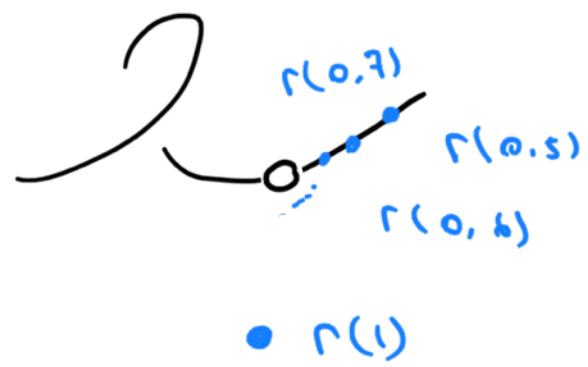
but it happens.

Just like in 2-dimensional calculus we have limits and derivatives.

ex:



$\lim_{t \rightarrow 1} r(t)$ exists



$\lim_{t \rightarrow 1} r(t)$ exists
but not

equal to $r(1)$.
Continuous iff for each
point $t \in \text{domain}$ $\lim_{s \rightarrow t} r(s) = r(t)$.

Above or right not cont.

theorem: if $r(t) = (x(t), y(t), z(t))$
then $r(t)$ continuous at s iff
each $x(t), y(t), z(t)$ continuous
at s .

ex: $r(t) = (t, t^2, t^3)$ good (also
interesting curve)

ex: $r(t) = (1/t, \sin(t), t^2)$ not cont
at $t=0$, however, good
everywhere else.

Derivatives: let $\vec{r}(t)$ be curve in $\mathbb{R}^3$.
We say $\vec{r}(t)$ is differentiable at t if
$$\lim_{\Delta t \rightarrow 0} \frac{\vec{r}(t + \Delta t) - \vec{r}(t)}{\Delta t} \text{ exists.}$$

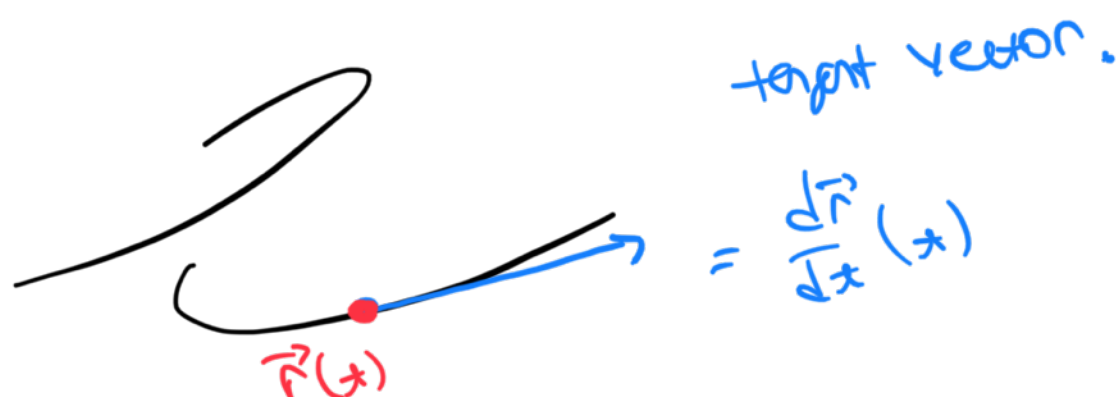
In this case we denote the limit by
 $\vec{r}'(t)$ or $\frac{d\vec{r}}{dt}(t)$.

then: $\vec{r}(x)$ is differentiable at x if
each $x(x)$, $y(x)$, $z(x)$ is too.

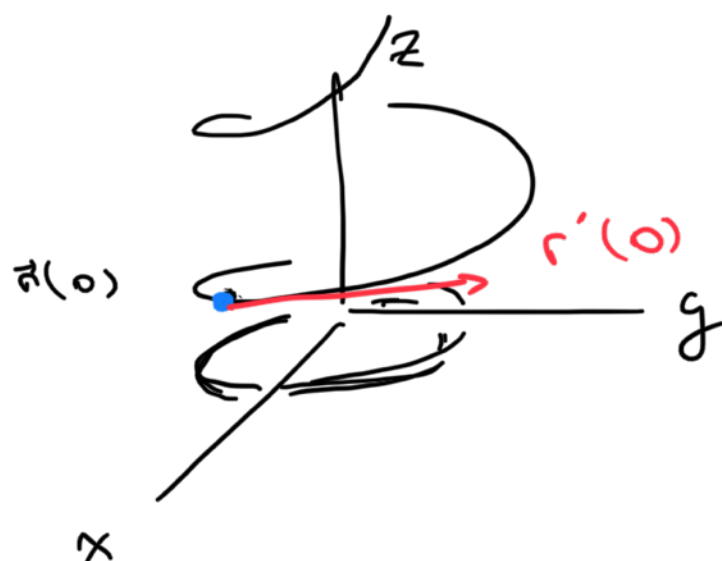
if so then $\vec{r}'(x) = (x'(x), y'(x), z'(x))$

upshot: Just look at components.

Here's a picture:



ex: $\vec{r}(x) = (\cos x, \sin x, e^x)$



$$\vec{r}'(x) = (-\sin x, \cos x, e^x)$$

$$\vec{r}'(0) = (0, 1, 1)$$

Calculate the tangent line at $x=0$.

Tangent line should just be what it was in 2D,
but now in 3D.

$$\vec{r}(x) - \vec{r}(a) \approx \frac{d\vec{r}}{dx}(a) (x-a) \quad \text{now with vectors.}$$

$$\text{ends} \rightarrow L(x) = \vec{r}(a) + \frac{d\vec{r}}{dx}(a) (x-a)$$

for linear.

$$\begin{aligned} L(x) &= \vec{r}(0) + (0, 1, 1)(x-0) \\ &= (1, 0, 1) + x(0, 1, 1) \end{aligned}$$

Acceleration: $\frac{d^2 \vec{r}}{dx^2}(x) = \frac{d}{dx} (-\sin x, \cos x, e^x)$
 $= (-\cos x, -\sin x, e^x)$

Here some helpful rules on pg. 765

(i). $\frac{d}{dx} \vec{C} = \vec{0}$ where $\vec{C}$ constant

(ii). $\frac{d}{dx} (c \vec{u}(x)) = c \vec{u}'(x)$ c constant scalar

(iii). $\frac{d}{dx} (f(x) \vec{u}(x)) = f'(x) \vec{u}(x) + f(x) \vec{u}'(x)$
 $f(x)$ scalar function

(iv). $\frac{d}{dx} (\vec{u}(x) + \vec{v}(x)) = \vec{u}'(x) + \vec{v}'(x)$

(v). $\frac{d}{dx} (\vec{u}(x) - \vec{v}(x)) = \vec{u}'(x) - \vec{v}'(x)$

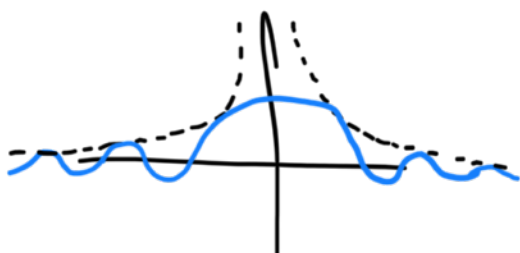
(vi). $\frac{d}{dx} (\vec{u}(x) \cdot \vec{v}(x)) = \vec{u}'(x) \cdot \vec{v}(x) + \vec{u}(x) \cdot \vec{v}'(x)$

(vii). $\frac{d}{dx} (\vec{u}(x) \times \vec{v}(x)) = \vec{u}'(x) \times \vec{v}(x) + \vec{u}(x) \times \vec{v}'(x)$

(viii). $\frac{d}{dx} (\vec{u}(f(x))) = \vec{u}'(f(x)) f'(x)$

ex: $\vec{r}(x) = \left(x, \frac{\sin x}{x}, 1 \right)$

Want $\lim_{x \rightarrow 0} \vec{r}(x)$ and $\lim_{x \rightarrow 0} \vec{r}'(x)$

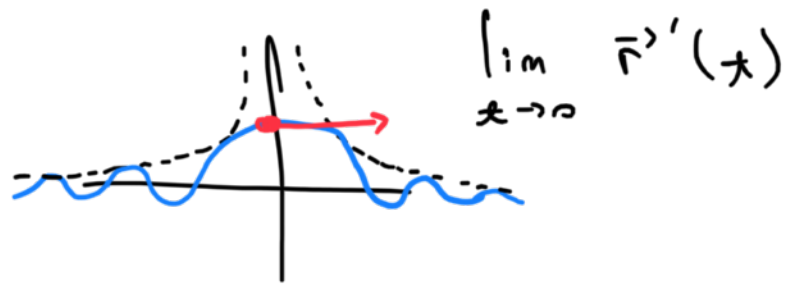


1. $\vec{r}(x) = (x, \frac{\sin x}{x}, 1)$ $\vec{r}'(x) = (1, \frac{x \cos x - \sin x}{x^2}, 0)$

$$\lim_{t \rightarrow 0} \vec{r}(t) = (0, 1, 1)$$

$$\vec{r}'(t) = \left(1, \frac{\cos t - \sin t}{t}, 0 \right)$$

$$\lim_{t \rightarrow 0} \vec{r}'(t) = (1, 0, 0)$$



13.2 : Integrals and projectile motion

Just like functions of a single variable, we say $\vec{r}'(x)$ has an anti-derivative $\vec{R}(x)$ if

$$\frac{d\vec{R}}{dx}(x) = \vec{r}'(x). \quad \text{Or in integral notation,}$$

$$\vec{R}(x) = \int \vec{r}'(x) dx.$$

Note just like 1-variable, there's ambiguity.

$$\vec{S}(x) = \vec{R}(x) + \vec{C} \quad \text{where } \vec{C} \text{ constant}$$

is perfectly valid too. (oops forgot
 $\int_a^b \frac{d\vec{F}}{dx}(x) dx = \vec{F}(b) - \vec{F}(a)$
be sure to mention)

Motivated by physical quantities.

e.g.: $\vec{v}(x) = (-\sin x, \cos x, 1)$, velocity of particle. Want to find a particle's path

where velocity is $\vec{v}(x)$. Set up an integral.

$$\begin{aligned} \int \vec{v}(x) dx &= \int -\sin x dx \hat{i} + \int \cos x dx \hat{j} \\ &\quad + \int dx \hat{k} = (\cos x, \sin x, x) \\ &\quad + \vec{C}. \end{aligned}$$

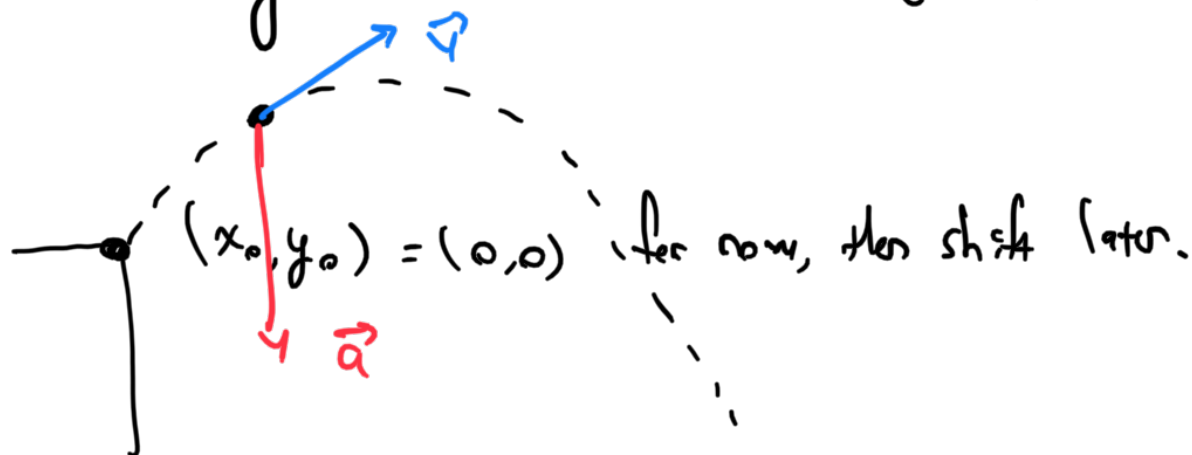
If our particle starts at point $(1, 0, 1)$ then solution is unique.

$$\vec{r}(x) = (\cos x, \sin x, x) + (C_1, C_2, C_3)$$

$$\vec{r}(0) = (1, 0, 1) = (1, 0, 0) + (0, 0, 1)$$

$$\text{so } \vec{r}(t) = (\cos t, \sin t, t+1)$$

ex: Say a ball thrown with initial velocity $\vec{v} = (v_x, v_y)$ at position $(x_0, y_0) = \vec{r}_0$. Calculate its trajectory assuming no forces other than gravity.



$$\frac{d^2 \vec{r}}{dt^2}(t) = \vec{a} = (0, -g) \quad g = \text{gravitational constant} \approx 10 \text{ m/s}^2$$

$$\int_0^s \frac{d^2 \vec{r}}{dt^2}(t) dt = \int_0^s 0 dt \hat{i} + \int_0^s -g dt \hat{j}$$

$$\vec{v}(s) - \vec{v}(0) = (0, -gs) \quad (\text{replace with } t)$$

$$\vec{v}(t) = \vec{v}(0) + (0, -gt) = (v_x, v_y - gt)$$

$$\int_0^s \vec{v}(t) dt = \int_0^s \frac{d\vec{r}}{dt}(t) dt = \vec{r}(s) - \vec{r}(0)$$

$$= \int_0^s v_x dt \hat{i} + \int_0^s (v_y - gt) dt \hat{j}$$

$$= (v_x s, v_y s - \frac{1}{2} g s^2)$$

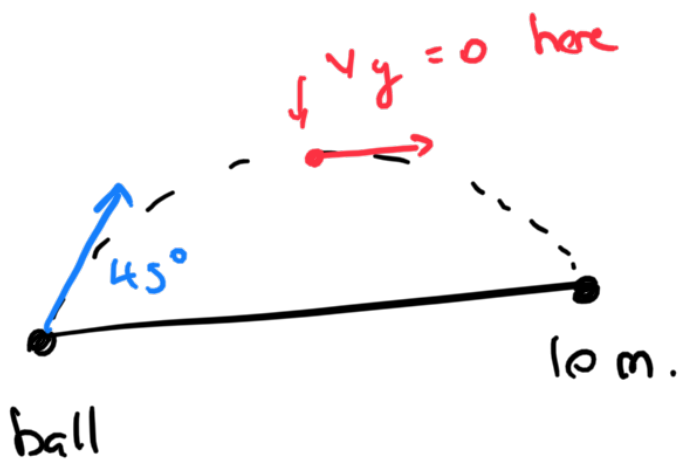
So $\vec{r}(t) = (x_0 + v_x t, y_0 + v_y t - \frac{1}{2} g t^2)$ (•)

ex 13.2.27: Hit ball at $\theta = 45^\circ$ and it lands level 10 m away.

(i). What was ball's initial speed?

(ii). Find 2 angles that make range 6m. ^{why?}

Speed is $|\vec{v}(t)|$. We want $|\vec{v}_0|$.



We can solve for half time by

$$v_y = 0$$

$$\vec{r}(t) = (v_x t, v_y t - \frac{1}{2} g t^2)$$

$$\vec{v}(t) = (v_x, v_y - g t)$$

So $v_y - g t = 0$ thus

$$t^* = v_y / g.$$

this means total flight time is $2t^*$, thus range

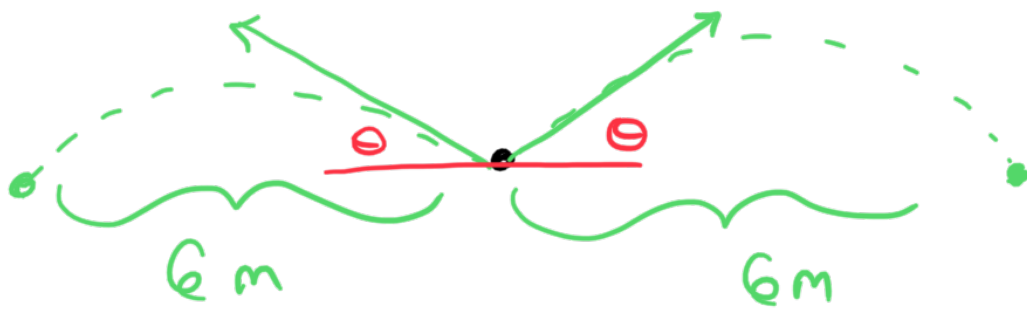
$$R = v_x (2t^*) = 2 v_x v_y / g \quad (-)$$

$$= 2 v_0^2 \cos \theta \sin \theta / g = \frac{1}{g} v_0^2 \sin 2\theta$$

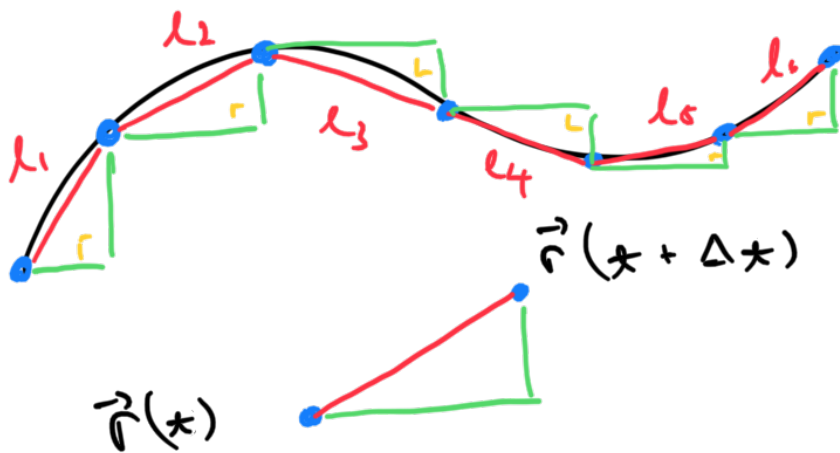
$$10 \text{ m} = \frac{1}{g} v_0^2 \sin(2 \cdot 45^\circ) \text{ so } |v_0| = \sqrt{10g} \text{ m/s}$$

If however want range to be 6m at initial speed of $\sqrt{20} \text{ m/s}$, then

$$6m = \frac{1}{2} v_0^2 \sin(2\theta) \quad \frac{v}{v_0} = \sin(2\theta)$$



13.3 : Arc length



$$|\vec{r}(x + \Delta) - \vec{r}(x)| \approx \text{red length}$$

$$\approx \left| \frac{d\vec{r}}{dx}(x) \right| |\Delta x| = |\vec{v}(x)| |\Delta x|$$

So we define arc-length of a curve $\vec{r}(x)$ from $[a, b]$ to be

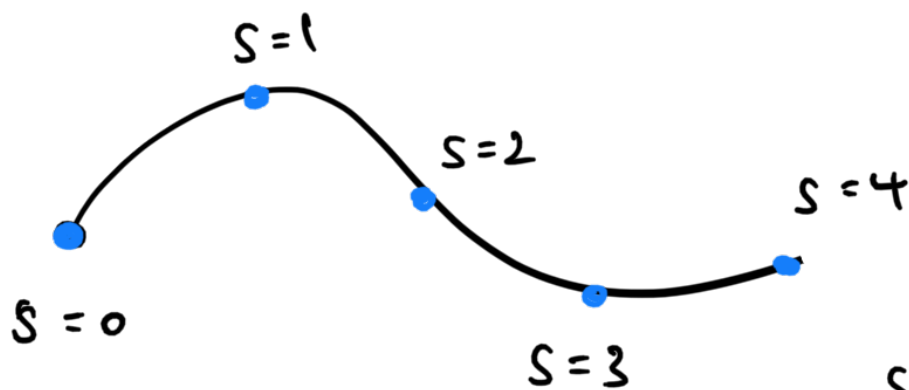
$$L = \int_a^b |\vec{v}(x)| dx = \int_a^b \sqrt{\left(\frac{dx}{dx}\right)^2 + \left(\frac{dy}{dx}\right)^2 + \left(\frac{dz}{dx}\right)^2} dx$$

ex: $\vec{r}'(x) = (\sin x, 2\sin x, \sin x)$

What length of curve from $t = 0$ to $t = \pi/2$

$$\begin{aligned} L &= \int_0^{\pi/2} \sqrt{(x')^2 + (y')^2 + (z')^2} dt \\ &= \int_0^{\pi/2} \sqrt{\cos^2 t + 4\cos^2 t + \cos^2 t} dt \\ &= \int_0^{\pi/2} \sqrt{6} |\cos t| dt = \sqrt{6} \end{aligned}$$

Weird way of parametrizing, but okay. A 'natural' way to parametrize a smooth curve is by arclength itself!



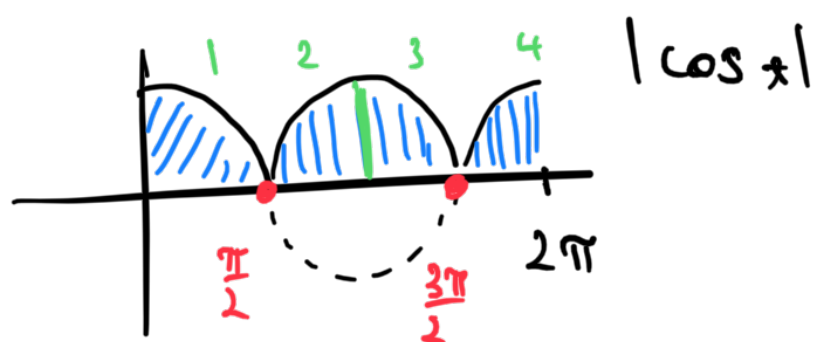
where $s(t) = \int_0^t |v(\tau)| d\tau$

s is a measure of how far you've gone.

ex: $\vec{r}(t) = (\sin t, 2\sin t, \sin t)$ then after t -seconds we've traveled

$$\begin{aligned} s(t) &= \int_0^t \sqrt{\cos^2 \tau + 4\cos^2 \tau + \cos^2 \tau} d\tau \\ &= \sqrt{6} \int_0^t |\cos \tau| d\tau \end{aligned}$$

So for example after 2π , it's gone



So $s(2\pi) = \sqrt{6} \cdot 4$ and note that $\vec{r}(2\pi) = \vec{r}(0)$.

Unit tangent vectors: let $\vec{r}(t)$ be some path. Unit tangent vector records direction of velocity vector (so long as $\vec{v}(t) \neq 0$).

denoted
$$\vec{T}(t) = \frac{\vec{v}(t)}{|\vec{v}(t)|}.$$

One property is that $\vec{T}(s) = \frac{d\vec{r}}{ds}(s)$
(good exercise).

ex: $\vec{r}(t) = (C \cos t, C \sin t, 1) \quad C \text{ constant} > 0$

$$\vec{v}(t) = (-C \sin t, C \cos t, 0)$$

$$|\vec{v}(t)| = |C| = C$$

so $T(t) = (-\sin t, \cos t, 0)$ indeed

Unit norm.

Also note, $s(x) = \int_0^x |v(t)| dt = Cx$ for $x \geq 0$.
 $s = Cx$ so

$$\text{so } \vec{r}(s) = (C \cos(s/c), C \sin(s/c), 1)^T / C.$$

$$\begin{aligned} \frac{d\vec{r}}{ds}(s) &= (-\sin(s/c), \cos(s/c), 0) \\ &= \vec{T}(s)! \end{aligned}$$

14.1: Functions of several variables

Before: $x \in \mathbb{R} \mapsto (x(x), y(x), z(x)) \in \mathbb{R}^3$

Now: $(x, y, z) \in \mathbb{R}^3$
or $(x, y) \in \mathbb{R}^2 \mapsto f(x, y, z) \in \mathbb{R}$ or
 $f(x, y) \in \mathbb{R}$

Real-valued functions. Can think of them as measurements of some variables, e.g. temperature along a plate of food or elevation as a function of position.

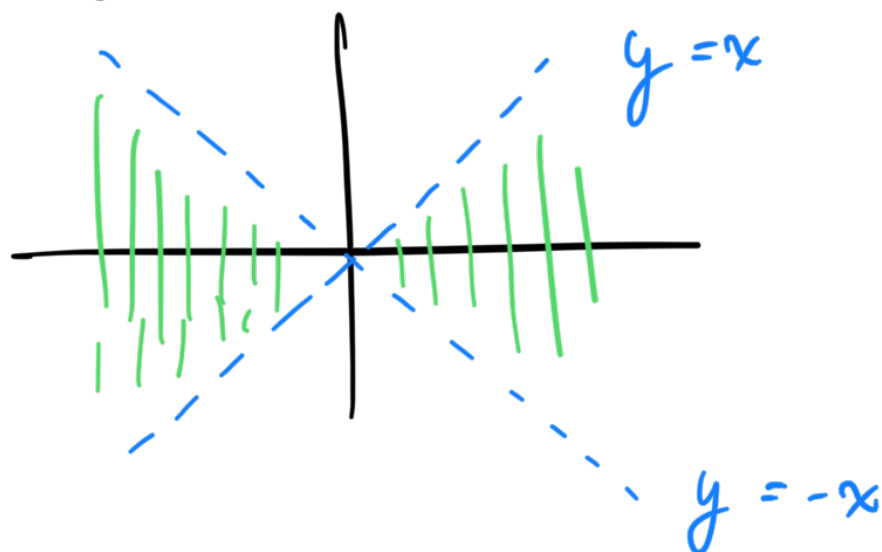
When you have a multivariable function typically

denoted by $f(x, y, z)$ or $f(x, y)$. The set of all points (x, y, z) for which f makes sense is called the domain.

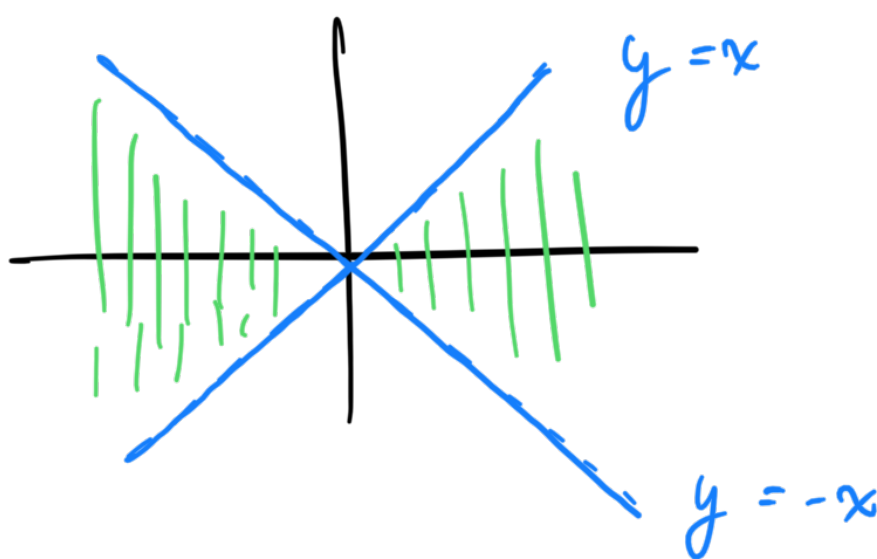
ex: Describe the domain of map

$$f(x, y) = \log(x^2 - y^2)$$

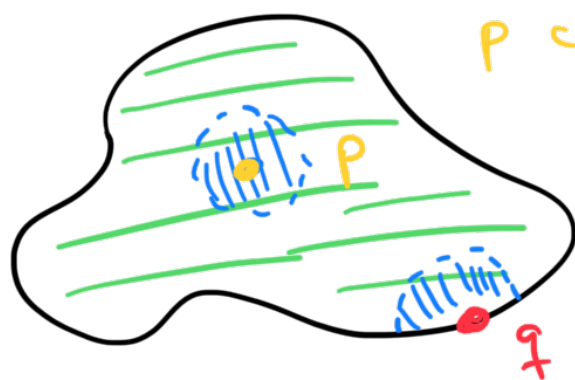
Need $x^2 - y^2 > 0$ (not equal)



What if $f(x, y) = \sqrt{x^2 - y^2}$? then



domain:

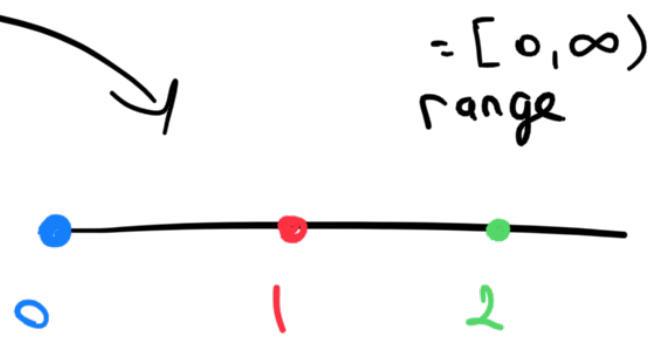
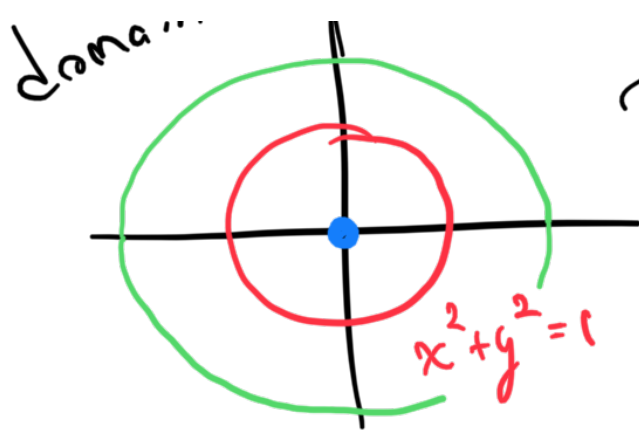


P called an interior point

Q called a boundary point

ex: $f(x, y) = x^2 + y^2$.

f



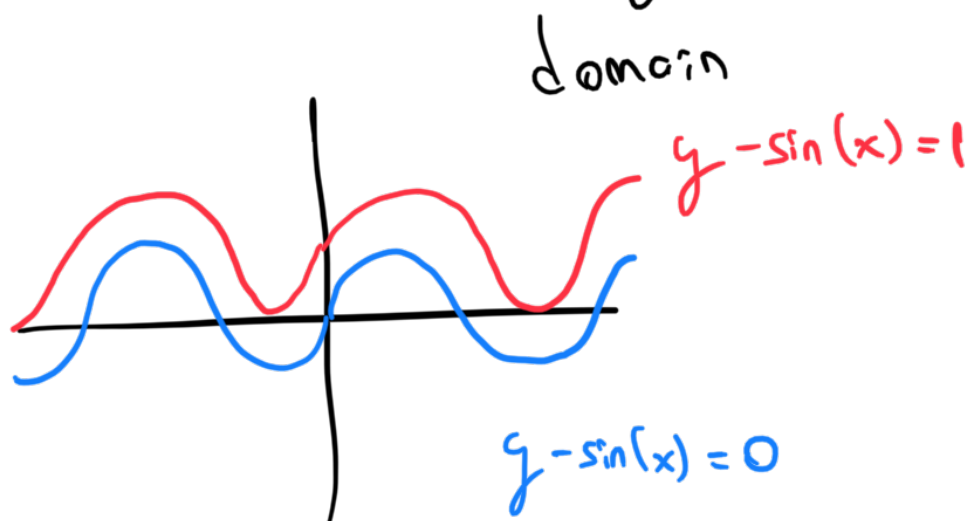
green/red/blue in domain are called

'level curves'. These are

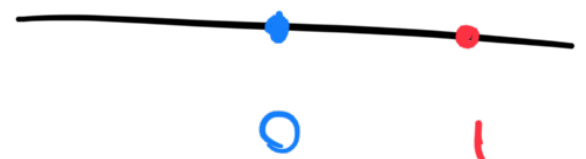
curves where the function has a constant value.

Can define same notion of a 'level-surface'.

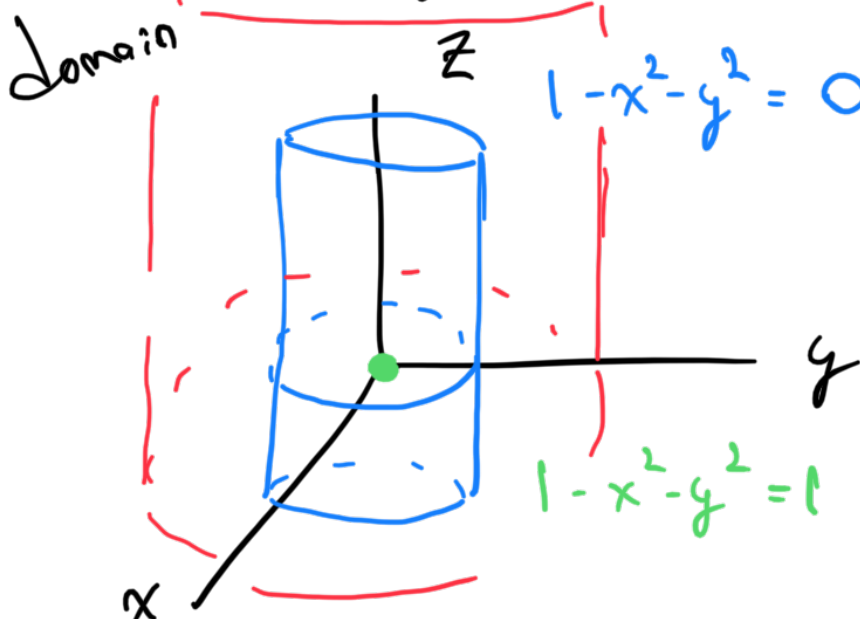
ex: $f(x, y) = y - \sin(x)$



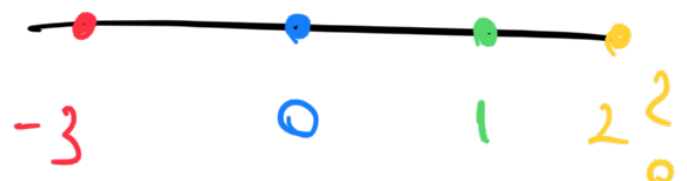
range
 $= (-\infty, \infty)$



ex: $f(x, y, z) = 1 - x^2 - y^2$



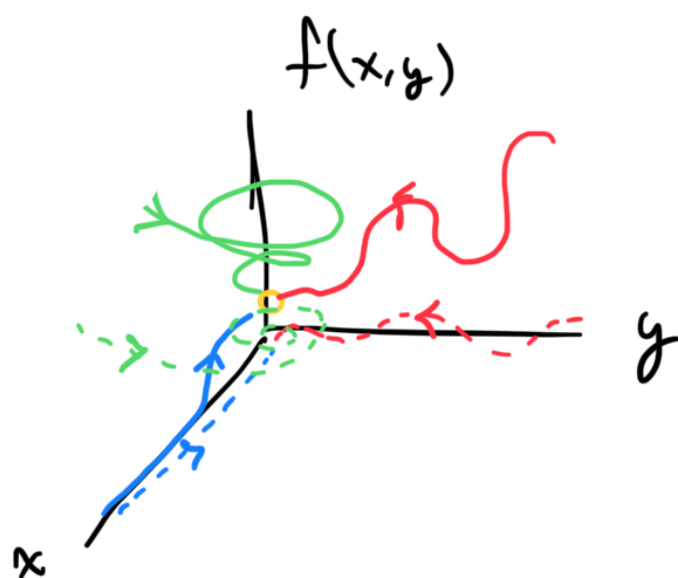
range
 $= (-\infty, 1]$



$$1 - x^2 - y^2 = -3$$

14.2: Limits and Continuity

Limits in 2-variable are much more complicated than usual. Reason why is because you have a bunch of directions to approach now.



Let's not formally define limits, but instead use rules to figure out what limits are equal to.

Hawker has a piece of intuition.

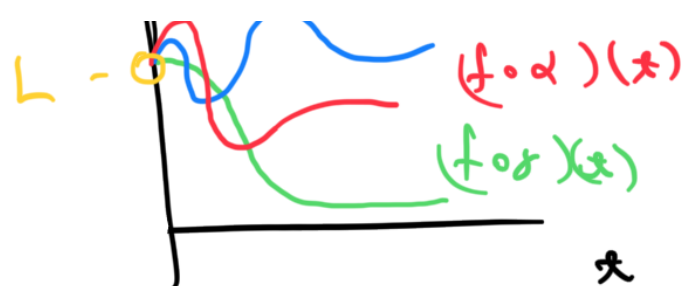
Let $f(x, y)$ be a function. Consider a point (a, b) . We say $\lim_{(x, y) \rightarrow (a, b)} f(x, y) = L$ if

for every smooth path $\gamma(t)$ in $\mathbb{R}^2$ with $\gamma(0) = (a, b)$

we have $\lim_{t \rightarrow 0} (f \circ \gamma)(t) = L$.

$\downarrow \gamma(t)$

$\parallel (f \circ \gamma)(t)$



Note in particular if we find two paths that disagree, then limit does not exist! that is if find α and β so that

$$\lim_{x \rightarrow 0} (f \circ \alpha)(x) \neq \lim_{x \rightarrow 0} (f \circ \beta)(x) \text{ then limit}$$

does not exist!

Bunch of rules on pg. 812 look exactly like one you familiar with but now in 2-variables.

$$\text{e.g. if } \lim_{(x,y) \rightarrow (a,b)} f(x,y) = L \text{ \& } \lim_{(x,y) \rightarrow (a,b)} g(x,y) = M$$

$$\text{then } \lim_{(x,y) \rightarrow (a,b)} f(x,y) + g(x,y) = L + M$$

$$\lim_{(x,y) \rightarrow (a,b)} f(x,y) \cdot g(x,y) = L \cdot M \text{ etc.}$$

We say a function is continuous if for every point (a,b) in the domain we have

$$\lim_{(x,y) \rightarrow (a,b)} f(x,y) = f(a,b).$$

$$\text{ex: } \lim_{(x,y) \rightarrow (1,1)} \frac{x^2 - y^2}{x^2 + y^2} = \lim_{(x,y) \rightarrow (1,1)} \frac{(x-y)(x+y)}{(x^2 + y^2)}$$

$$= \lim_{(x,y) \rightarrow (1,1)} \frac{1-1}{1+1} = 0$$

ex: 14.2.19

$$\text{define } f(x,y) = \frac{\sqrt{2x-y} - 2}{2x-y-4} \text{ for } 2x-y-4 \neq 0$$

$$= 7 \text{ if } 2x-y-4 = 0$$

is $f(x,y)$ continuous at $(2,0)$?

$$\lim_{(x,y) \rightarrow (2,0)} \frac{\sqrt{2x-y} - 2}{2x-y-4}$$

$$= \lim_{(x,y) \rightarrow (2,0)} \frac{(\sqrt{2x-y} - 2)}{(\sqrt{2x-y} - 2)(\sqrt{2x-y} + 2)} = \lim_{(x,y) \rightarrow (2,0)} \frac{1}{\sqrt{2x-y} + 2}$$

$$= \frac{1}{2+2} = 1/4 \neq 7 \text{ so no, function not continuous at } (2,0)$$

ex: Just because a function has a limit along every line, doesn't mean it has a limit!

$$f(x,y) = \frac{2x^2y}{x^4 + y^2} \text{ pg. 815}$$

note along y -axis $\alpha(t) = (0, t)$ for $t \neq 0$

$$(f \circ \alpha)(t) = \frac{0}{t^2} = 0 \text{ for } t \neq 0$$

$$\rightarrow 0$$

However for $\beta(t) = (t, mt)$

$$(f \circ B)(x) = \frac{2(x^2)(mx)}{x^4 + (mx)^2} = \frac{2mx^3}{m^2x^2 + x^4}$$

$$= \frac{2mx}{m^2 + x^2} \text{ for } x \neq 0$$

so $\lim_{x \rightarrow 0} (f \circ B)(x) = 0$ true for any m .

However limit is different for $C(x) = (x, kx^2)$
check is good exercise.

ex: $\lim_{(x,y) \rightarrow (0,0)} \frac{\sin(x+y)}{x+y}, \quad u = x+y$

$$\lim_{u \rightarrow 0} \frac{\sin(u)}{u} = 1 \quad \left\{ \begin{array}{l} \text{can do replacement} \\ \text{if function is a} \end{array} \right.$$

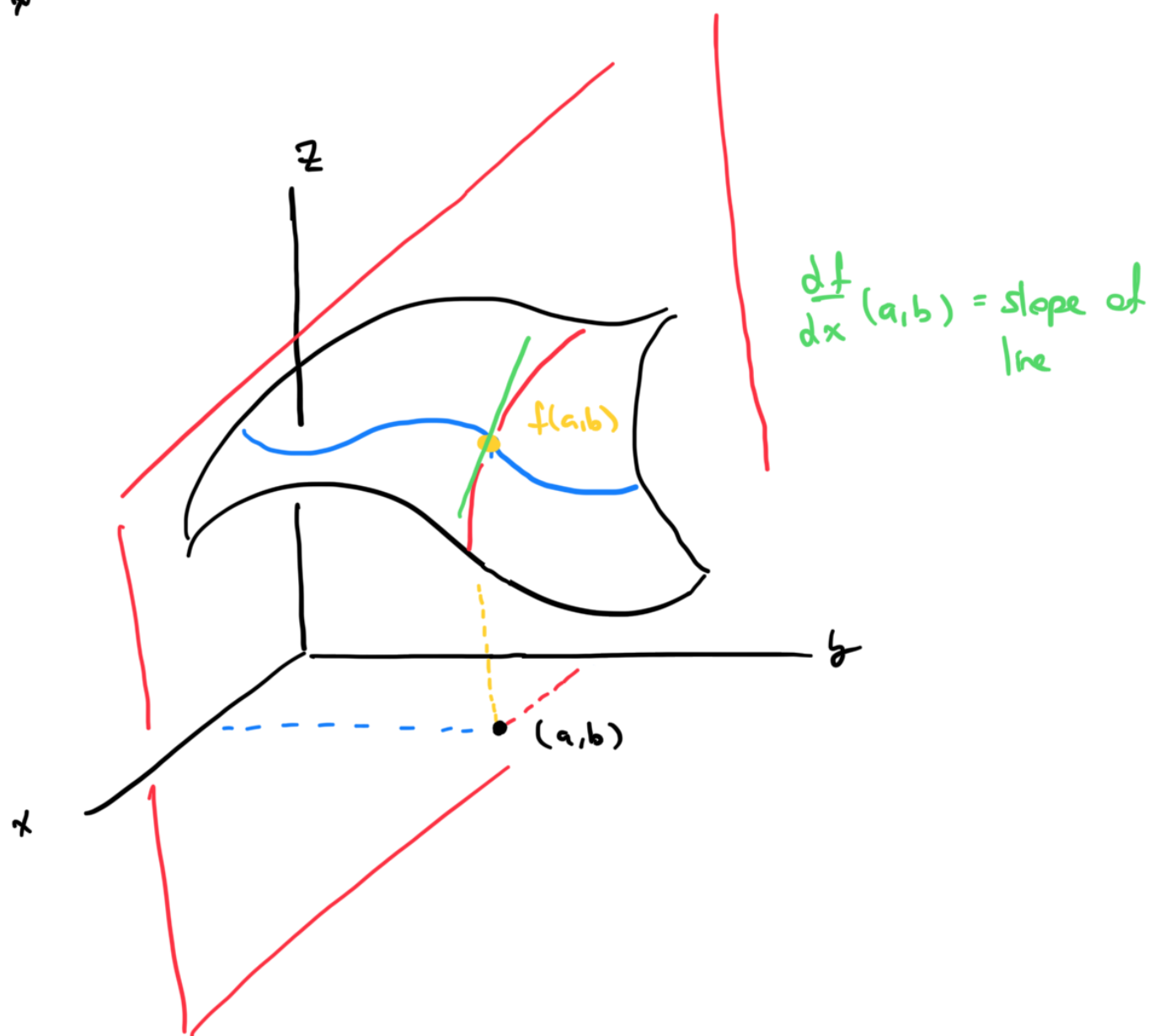
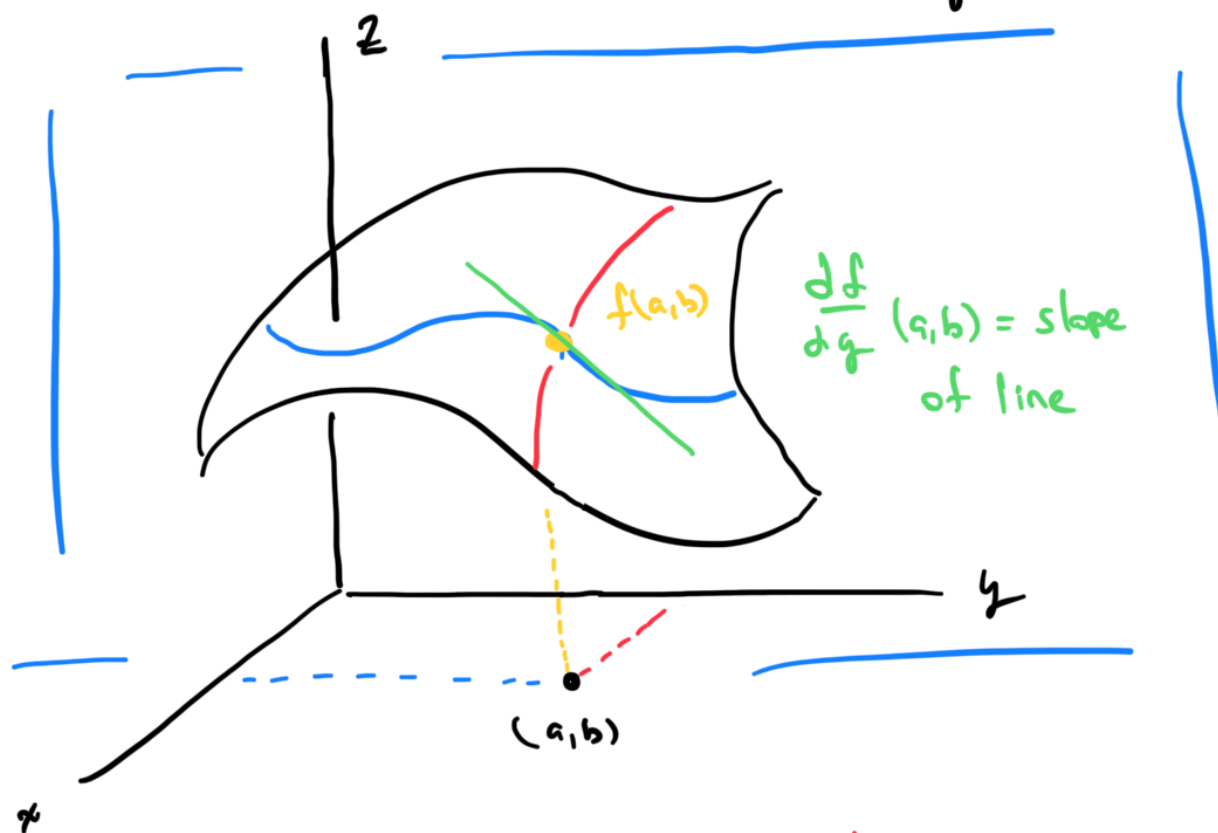
composition $(f \circ g)(x,y)$ where $f(u)$ continuous
at $\lim_{(x,y) \rightarrow L} g(x,y) \rightarrow L$

14.3: Partial derivatives

$z = f(x,y)$ then we can define partial derivatives
which measure how a function changes as one variable
changes and the other stays fixed.

$$\frac{\partial f}{\partial x}(a,b) := \lim_{\Delta x \rightarrow 0} \frac{f(a + \Delta x, b) - f(a, b)}{\Delta x}$$

$$\frac{\partial f}{\partial y}(a,b) = \lim_{\Delta y \rightarrow 0} \frac{f(a, b + \Delta y) - f(a,b)}{\Delta y}$$



ex: $f(x,y) = x \cos(xy)$

$$\frac{\partial f}{\partial x} = x \frac{\partial}{\partial x} \cos(xy) = x (-\sin(xy) \frac{\partial}{\partial x} (xy))$$

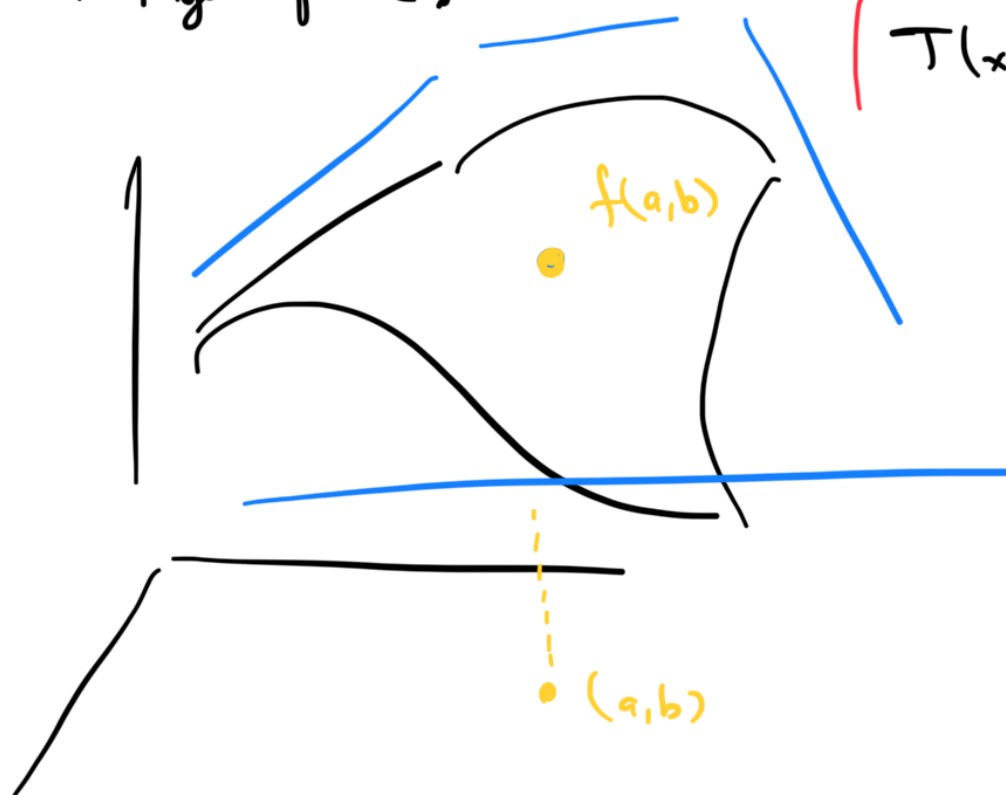
$$\frac{\partial f}{\partial y} = -x \sin(xy) \left(\frac{\partial}{\partial x} x \right) = -x^2 \sin(xy)$$

$$\frac{df}{dx} = \frac{d}{dx} (x \cos(xy)) = \left(\frac{d}{dx} x \right) \cos(xy) + x \frac{d}{dx} (\cos(xy))$$

$$= 1 \cos(xy) + x (-\sin(xy) \frac{d}{dx} (xy))$$

$$= \cos(xy) - x \sin(xy) (y) = \cos(xy) - xy \sin(xy)$$

Tangent plane:



$$\begin{aligned} T(x, y) &= f(a, b) \\ &+ (x - a) \frac{\partial f}{\partial x}(a, b) \\ &+ (y - b) \frac{\partial f}{\partial y}(a, b) \end{aligned}$$

ex: $f(x, y) = x \cdot e^{x \sin(y)}$

Calculate tangent plane to $f(x, y)$ at point
 $(x, y) = (0, \pi)$

$$\frac{df}{dx} = \left(\frac{d}{dx} x \right) e^{x \sin(y)} + x \frac{d}{dx} (e^{x \sin(y)})$$

$$= e^{x \sin(y)} + x e^{x \sin(y)} \frac{d}{dx} (x \sin(y))$$

$$= e^{x \sin(y)} + x e^{x \sin(y)} \sin(y)$$

$$\begin{aligned}
 \frac{d}{dy} &= \frac{d}{dy} (x e^{x \sin(y)}) = x \frac{d}{dy} (e^{x \sin(y)}) \\
 &= x e^{x \sin(y)} \frac{d}{dy} (x \sin(y)) \\
 &= x e^{x \sin(y)} x \cos(y) = x^2 e^{x \sin(y)} \cos(y)
 \end{aligned}$$

$$\frac{df}{dx}(0, \pi) = e^0 + 0 = 1 \quad \frac{df}{dy}(0, \pi) = 0$$

So tangent plane is and $f(0, \pi) = 0$

$$\begin{aligned}
 T(x, y) &= f(0, \pi) + \frac{df}{dx}(0, \pi)(x - 0) + \frac{df}{dy}(0, \pi)(y - 0) \\
 &= 0 + x + 0 = x
 \end{aligned}$$

ex: Is there a function $f(x, y)$ for which

$$\frac{\partial^2 f}{\partial x^2}(x, y) = x^2 y \quad \text{and} \quad \frac{\partial^2 f}{\partial y^2}(x, y) = x y^2 \quad ?$$

Mixed partials (typically) agree.

$$\frac{\partial^2 f}{\partial y \partial x} = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right) = \frac{\partial}{\partial y} (x^2 y) = x^2 \quad \text{and}$$

$$\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \right) = \frac{\partial}{\partial x} (x y^2) = y^2$$

So no!

What if $\frac{\partial f}{\partial x} = 2xy + y^2 + x^2$ and $\frac{\partial f}{\partial y} = x^2 + 2xy$

$$\text{then quick check } \frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x}$$

$$\text{also notationally } f''_{xy} = f''_{yx}$$

How to find u ?

$$\frac{\partial f}{\partial y} = x^2 + 2xy \text{ so } f(x, y) = x^2 \int dy + 2x \int y dy \\ = x^2 y + xy^2 + \underline{\underline{h(x)}}$$

$$\frac{\partial f}{\partial x} = 2xy + y^2 + h'(x) = 2xy + y^2 + x^2$$

$$\text{get } h'(x) = x^2 \text{ so } h(x) = \frac{1}{3}x^3 + C$$

$$\text{and } f(x, y) = x^2 y + xy^2 + \frac{1}{3}x^3 + C$$

14.4: Chain rule

Easiest explained by examples. However for now

let $z = f(x, y)$ and x be a function of t
 y be a function of t

$$\text{then } \frac{dz}{dt} = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt}$$

$$\text{ex: } z = x^2 - y^2 \text{ and } x(t) = \cos(t) \\ y(t) = \sin(t)$$

$$\text{then } \frac{dz}{dt} = \frac{\partial z}{\partial x} \frac{dx}{dt} + \frac{\partial z}{\partial y} \frac{dy}{dt}$$

$$\frac{\partial z}{\partial x} = 2x \quad \frac{\partial z}{\partial y} = -2y \quad \frac{dx}{dt} = -\sin t \quad \frac{dy}{dt} = \cos t \\ = 2 \cos t \quad = -2 \sin t \quad \text{so}$$

$$\frac{dz}{dt} = (2 \cos t)(-\sin t) + (-2 \sin t)(\cos t)$$

$$= -2 \sin(2x)$$

In fact, $z(x) = \cos^2 x - \sin^2 x = \cos(2x)$

$$\text{So } \frac{dz}{dx} = -\sin(2x)(2)$$

ex: $f(x, y, z) = \sin x \cos y \tan z$ and want

$$\frac{df}{dx}(0) \text{ where } x(x) = x \quad y(x) = -x \text{ and}$$

$$z(x) = \tan^{-1}(x)$$

$$\frac{df}{dx} = \frac{\partial f}{\partial x} \frac{dx}{dx} + \frac{\partial f}{\partial y} \frac{dy}{dx} + \frac{\partial f}{\partial z} \frac{dz}{dx}$$

$$\frac{df}{dx} = \cos x \cos y \tan z = (\cos^2 x) \tan(\tan^{-1}(x)) = x \cos^2 x$$

$$\frac{df}{dy} = -\sin x \sin y \tan z = -(\sin^2 x) x$$

$$\begin{aligned} \frac{df}{dz} &= \sin x \cos y \sec^2 z = \sin x \cos y (1 + \tan^2 z) \\ &= \sin x \cos x (1 + \tan^2 x) \end{aligned}$$

$$\frac{dx}{dx} = \cos x \quad \frac{dy}{dx} = -\sin x \quad \frac{dz}{dx} = \frac{1}{1+x^2}$$

$$\text{So } \frac{df}{dx}(0) = (0)(1) + (0)(0) + (0)(1) = 0$$

Can see this simply by

$$f(x) = (\sin x \cos x) x = \frac{1}{2} \sin(2x) x$$

$$\frac{df}{dx} = \left(\frac{1}{2} \cos(2x) \cdot 2 \right) \cdot x + \left(\frac{1}{2} \sin(2x) \right) \cdot 1$$

$$\frac{df}{dx}(0) = 0$$

What if have more than one variable, i.e. a surface?

ex: $w = f(x, y, z)$ where $x(u, v), y(u, v), z(u, v)$?

Pretty much the same thing.

$$\frac{\partial w}{\partial u} = \frac{\partial w}{\partial x} \frac{\partial x}{\partial u} + \frac{\partial w}{\partial y} \frac{\partial y}{\partial u} + \frac{\partial w}{\partial z} \frac{\partial z}{\partial u} \quad \text{and}$$

$$\frac{\partial w}{\partial v} = \frac{\partial w}{\partial x} \frac{\partial x}{\partial v} + \frac{\partial w}{\partial y} \frac{\partial y}{\partial v} + \frac{\partial w}{\partial z} \frac{\partial z}{\partial v}$$

ex: $w = x^2 + y^2 + z^2$ $x = \sin u \cos v$

What $\frac{\partial w}{\partial u}$.

$$y = \sin u \sin v$$

$$z = \cos u$$

$$\frac{\partial w}{\partial x} = 2x \quad \frac{\partial w}{\partial y} = 2y \quad \frac{\partial w}{\partial z} = 2z$$

$$w_x = 2 \sin u \cos v \quad w_y = 2 \sin u \sin v \quad w_z = 2 \cos u$$

$$\frac{\partial x}{\partial u} = \cos u \cos v \quad \frac{\partial y}{\partial u} = \cos u \sin v \quad \frac{\partial z}{\partial u} = -\sin u$$

$$w_u = (2 \sin u \cos v)(\cos u \cos v)$$

$$+ (2 \sin u \sin v)(\cos u \sin v)$$

$$+ (2 \cos u)(-\sin u)$$

$$= (2 \sin u \cos u) \cos^2 v + (2 \sin u \cos u) \sin^2 v$$

$$- 2 \cos u \sin u = 0$$

let's try w_v . We already have some terms. Just

need $\frac{\partial x}{\partial v}, \frac{\partial y}{\partial v}, \frac{\partial z}{\partial v}$

$$\frac{dx}{dy} = -\sin u \sin v \quad \frac{dy}{dy} = \sin u \cos v \quad \frac{dz}{dy} = 0$$

$$\text{So } \frac{dw}{dy} = (2\sin u \cos v)(-\sin u \sin v) + (2\sin u \sin v)(\sin u \cos v) + 0 = 0$$

$$\text{So } w_y = 0$$

$$\text{In fact... } w(u, v) = (\sin u \cos v)^2 + (\sin u \sin v)^2 + (\cos u)^2$$

$$= (\sin^2 u)(\cos^2 v + \sin^2 v) + (\cos^2 u)$$

$$= 1$$

$$\text{So } \frac{dw}{du} = 0 \text{ and } \frac{dw}{dv} = 0!$$

implicit differentiation:

Say have z implicitly defined in terms of

$$x, y, \text{ e.g. } x^2 + y^2 - z^2 = 13$$

Want to calculate $\frac{dz}{dx}$ at a point, e.g. $(2, 0, 1)$

You do so by differentiating.

$$\frac{d}{dx}(x^2 + y^2 - z^2) = \frac{d}{dx}(13)$$

$$2x + 0 - 2z \frac{dz}{dx} = 0 \quad \text{so}$$

$$\frac{dz}{dx} = \frac{x}{z} \quad \text{thus } \frac{dz}{dx}(2, 0) = \frac{2}{1} = 2$$

ex: $\sin(xy^2) + e^z = 1$ calculate $\frac{dy}{dx}$ and $\frac{dy}{dz}$
at $(\pi, 1, 0)$.

$$\frac{d}{dx} (\sin(xy^2) + e^z) = \frac{d}{dx} (1)$$

$$\cos(xy^2) \frac{d}{dx} (xy^2) + 0 = 0$$

$$\cos(xy^2) (1 + x \cdot 2y \frac{dy}{dx}) = 0 \quad \text{plug in } (\pi, 1, 0)$$

$$\cos(\pi) (1 + 2\pi \frac{dy}{dx}) = 0 \quad \text{so } \frac{dy}{dx}(\pi, 0) = -1/2\pi$$

$$\frac{d}{dz} (\sin(xy^2) + e^z) = \frac{d}{dz} (1)$$

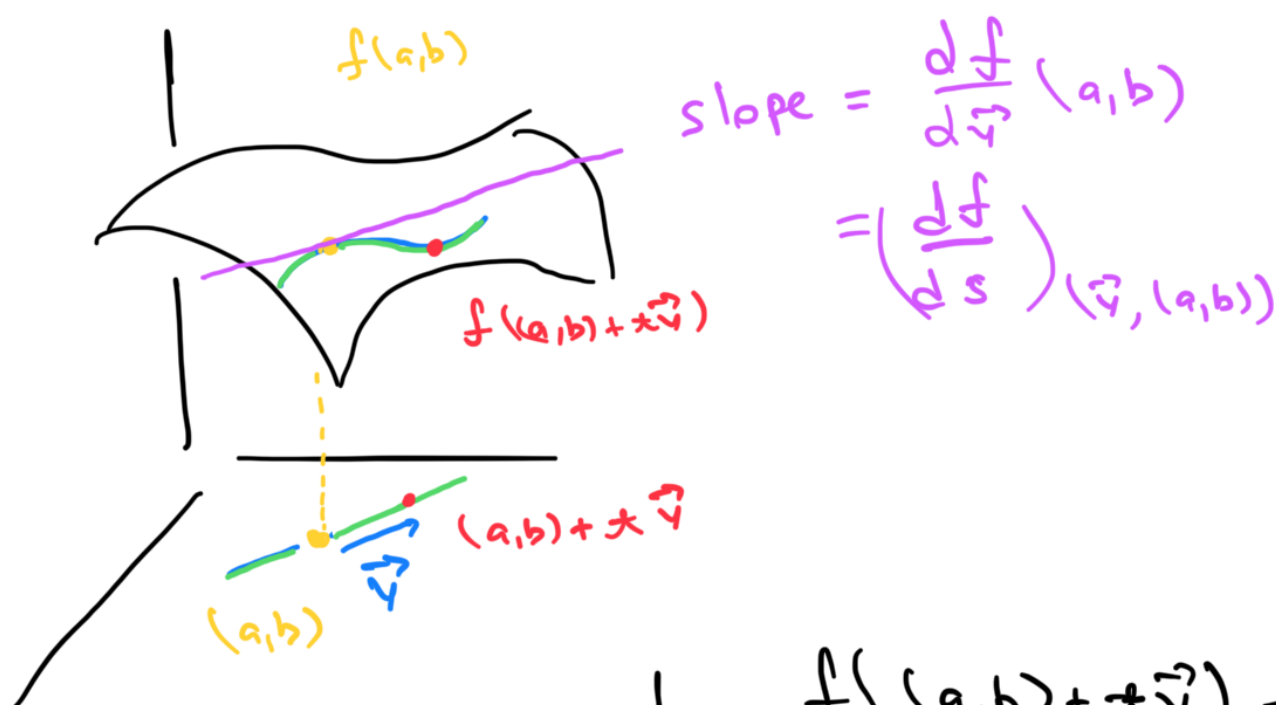
$$\cos(xy^2) \frac{d}{dz} (xy^2) + e^z = 0$$

$$\cos(xy^2) x (2y \frac{dy}{dz}) + e^z = 0 \quad \text{at } (\pi, 1, 0),$$

$$\cos(\pi)(\pi \cdot 2) \frac{dy}{dz}(\pi, 0) + 1 = 0 \quad \text{so}$$

$$\frac{dy}{dz}(\pi, 0) = +1/2\pi$$

14.5: Directional derivatives and gradient



$$\text{slope} = \lim_{t \rightarrow 0} \frac{f((a, b) + t\vec{v}) - f(a, b)}{t}$$

= scalar quantity measure how fast f is changing along the vector $\vec{v}$.

Warning: Book only defines this for unit vectors.

This is absurd, I have no idea why. //

So when they ask something like

"find the derivative of the function f at (a, b) in the direction of $\vec{v}$ " they mean make $\vec{v}$ a unit vector first!

ex: find the derivative of $f(x, y) = xy^2$ at the point $(1, 1)$ along the vector $\vec{v} = (3, 4)$.
(then do the same for the direction).

1. $f((1, 1) + t(3, 4)) - f(1, 1)$

$$\begin{aligned}
 & \lim_{t \rightarrow 0} \frac{\text{大}}{\text{大}} \\
 &= \lim_{t \rightarrow 0} \frac{f(1+3t, 1+4t) - f(1,1)}{t} = \lim_{t \rightarrow 0} \frac{(1+3t)(1+4t)^2 - 1}{t} \\
 &= \lim_{t \rightarrow 0} \frac{(1+3t)(1+8t+16t^2) - 1}{t} \\
 &= \lim_{t \rightarrow 0} \frac{11t + 40t^2 + 48t^3}{t} = \lim_{t \rightarrow 0} \frac{11t}{t} + \text{stuff} \cdot t = 11
 \end{aligned}$$

if the book asks for direction, $u = \left(\frac{3}{5}, \frac{4}{5}\right)$

$$\begin{aligned}
 \lim_{t \rightarrow 0} \frac{f\left((1,1) + t\left(\frac{3}{5}, \frac{4}{5}\right)\right) - f(1,1)}{t} &= \frac{11}{5} \text{ why?} \\
 &= (D_u f)(1,1)
 \end{aligned}$$

In general note for a vector $\vec{v}$,

$$(D_{\vec{v}} f)(a,b) = \frac{df}{d\vec{v}}(a,b) = \lim_{t \rightarrow 0} \frac{f((a,b) + t(v_x, v_y)) - f(a,b)}{t}$$

$f(t) = (a,b) + t(v_x, v_y)$ then

$$(D_{\vec{v}} f)(a,b) = \frac{d}{dt} \Big|_{t=0} (f \circ f)(t) \text{ which we may use chain-rule,}$$

$$= \frac{df}{dx}(f(0)) \frac{dx}{dt}(0) + \frac{df}{dy}(f(0)) \frac{dy}{dt}(0)$$

$$= \left(\frac{df}{dx}(a,b), \frac{df}{dy}(a,b) \right) \cdot (v_x, v_y)$$

$$\text{so } (D_{\vec{v}} f)(a,b) = \left(\frac{df}{dx}(a,b), \frac{df}{dy}(a,b) \right) \cdot \vec{v}$$

we have $(\nabla f)(a,b) = \uparrow$ called

the gradient of f //

ex: Find the directional derivative of

$f(x, y) = x \sin(y)$ at $(1, \pi)$ along the vector $\vec{v} = (1, 2)$.

$$\vec{u} = \left(\frac{1}{\sqrt{5}}, \frac{2}{\sqrt{5}} \right)$$

$$(D_{\vec{u}} f)(1, \pi) = \nabla f(1, \pi) \cdot \vec{u}$$

$$\begin{aligned} \nabla f(1, \pi) &= (\sin(y), x \cos(y)) \Big|_{(1, \pi)} \\ &= (0, -1) \end{aligned}$$

$$\text{so } (D_{\vec{u}} f)(1, \pi) = (0, -1) \cdot \left(\frac{1}{\sqrt{5}}, \frac{2}{\sqrt{5}} \right) = \frac{-2}{\sqrt{5}} < 0$$

The formula $(D_{\vec{v}} f)(a, b) = \nabla f(a, b) \cdot \vec{v}$ is very telling insofar as it gives us that

$$(D_{\vec{v}} f)(a, b) = \nabla f(a, b) \cdot \vec{v} = |\nabla f(a, b)| |\vec{v}| \cos \theta$$

$$\text{so } -|\nabla f(a, b)| |\vec{v}| \leq (D_{\vec{v}} f)(a, b) \leq |\nabla f(a, b)| |\vec{v}|$$

bc $-1 \leq \cos \theta \leq 1$. This quantity is maximized if $\cos \theta = 1$, i.e. $\theta = 0$, so $\vec{v}$ and $\nabla f(a, b)$ point same direction.

$\cos \theta = -1$ i.e. $\theta = \pi$, so $\vec{v}$ and $\nabla f(a, b)$ point opposite direction.

thus f increases most in direction of ∇f
 and f decreases most in direction of $-\nabla f$.

Similarly, $(D_{\vec{v}} f)(a,b) = \nabla f(a,b) \cdot \vec{v} = 0$

iff $\vec{v} \perp \nabla f(a,b)$, thus f is

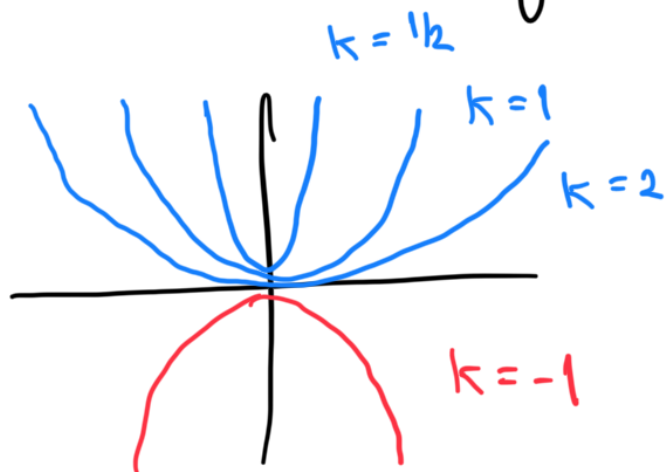
not changing if $\vec{v} \perp \nabla f(a,b)$!

so f is constant along direction $\perp$ to ∇f !

ex: $f(x,y) = \frac{x^2}{y}$ on domain $y \neq 0$.

Draw level curves, $\frac{x^2}{y} = k$ for constant k

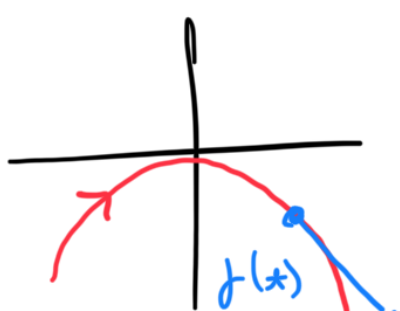
means that $y = k^{-1}x^2$



Okay, let's calculate
 the gradient at a point
 (a,b) .

$$\begin{aligned} (\nabla f)(a,b) &= \left(\frac{df}{dx}(a,b), \frac{df}{dy}(a,b) \right) \\ &= \left(\frac{2x}{y}, -\frac{x^2}{y^2} \right) \Big|_{(a,b)} = \left(\frac{2a}{b}, -\frac{a^2}{b^2} \right) \end{aligned}$$

let's choose a level curve. Say $k = -1$.



$\frac{x^2}{y} = -1$. Note you can parametrize
 by $f(x) = (x, -x^2)$
 so $f'(x) = (1, -2x)$

$$(x, -x^2) \quad f'(x) = (1, -2x). \quad \text{So } \vec{u}(x) = \frac{(1, -2x)}{\sqrt{1+4x^2}}$$

So now if take $(D_{\vec{u}} f)(\gamma(x))$

$$\begin{aligned} &= (\nabla f)(\gamma(x)) \cdot \vec{u}(x) \\ &= \left(2 \frac{x}{-x^2}, -\frac{x^2}{x^4} \right) \cdot (1, -2x) / \sqrt{1+4x^2} \\ &= \left(-\frac{2}{x}, -\frac{1}{x^2} \right) \cdot \frac{(1, -2x)}{\sqrt{1+4x^2}} = \frac{-\frac{2}{x} + \frac{2}{x}}{\sqrt{1+4x^2}} = 0 \quad \text{for } x \neq 0 \end{aligned}$$

that means f not changing in the direction of

$\gamma'(x)$! (But this is not surprising at all,

it's because $\gamma(x)$ is a level curve!)

this principle holds in general.

— the gradient is orthogonal to level curves!

Some properties:

$$\nabla(f \pm g) = \nabla f \pm \nabla g$$

$$\nabla(cf) = c \nabla f \quad c \text{ constant}$$

$$\nabla(fg) = (\nabla f)g + f(\nabla g)$$

$$\nabla\left(\frac{f}{g}\right) = \frac{g \nabla f - (\nabla g)f}{g^2}$$

ex: $f(x, y, z) = x^2 + y^2 - z^2.$

at the point $(1, 2, 3)$ find the direction
for which f is increasing the most.

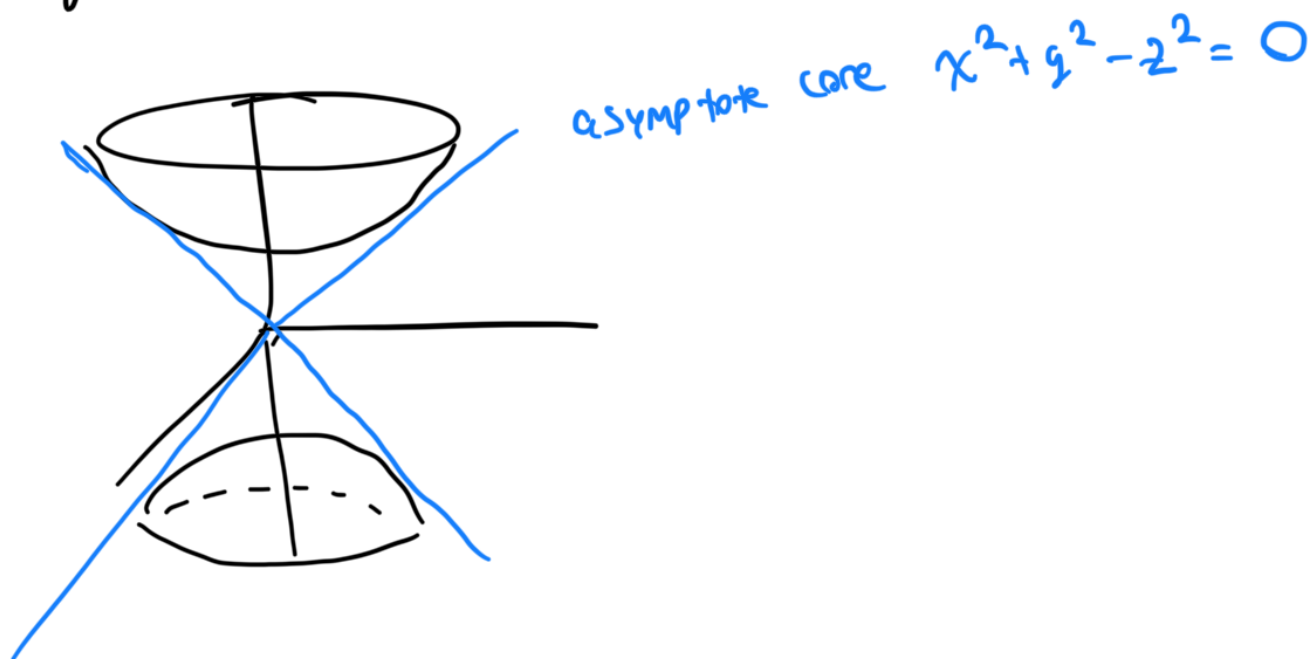
$$\nabla f = (2x, 2y, -2z) \text{ so}$$

$$(\nabla f)(1, 2, 3) = (2, 4, -6), \text{ direction of greatest increase}$$

$$\text{is } \frac{(2, 4, -6)}{|(2, 4, -6)|} = \frac{(1, 2, -3)}{\sqrt{14}}$$

Calculate a vector normal to the surface

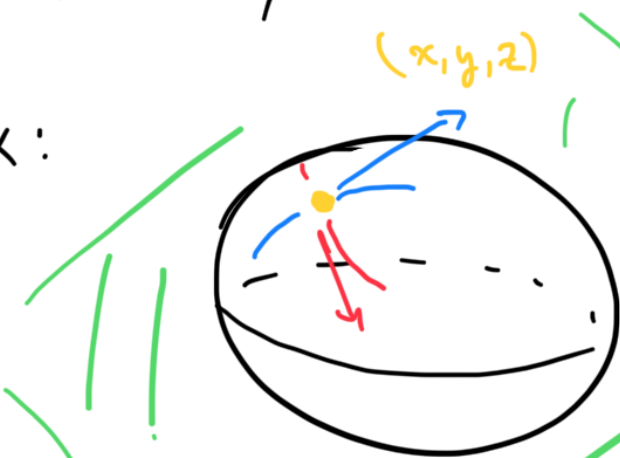
$$x^2 + y^2 - z^2 = -1. \quad \nabla f(x, y, z) = (2x, 2y, -2z)$$



14.6: Tangent planes and differentials

intuitively have an idea of this

ex:



consider all paths through
point (x, y, z) on your
surface S and take

all possible tangent lines.

This is your tangent plane.

As we know a plane is also specified by a point and normal vector. So we have the following.

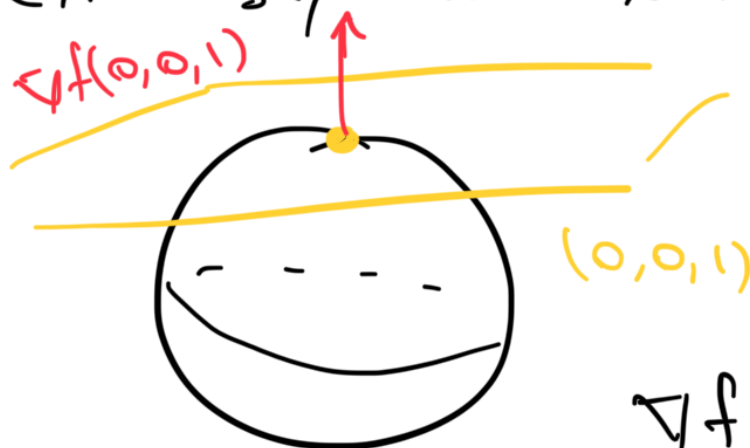
Let S be surface defined by $f(x, y, z) = C$.

Let (a, b, c) be a point on S . The tangent plane is going to be all lines through (a, b, c) that are $\perp$ to $\nabla f(a, b, c)$ because $\nabla f(a, b, c)$ is $\perp$ to level curves. So get equation

$$\nabla f(a, b, c) \cdot (x - a, y - b, z - c) = 0 \quad (\rightarrow)$$

ex: Say have $x^2 + y^2 + z^2 = 1$

$\nabla f(0, 0, 1)$



so intuitively plane is $z = 1$.

Check. $f(x, y, z) = x^2 + y^2 + z^2$

$$\nabla f = (2x, 2y, 2z)$$

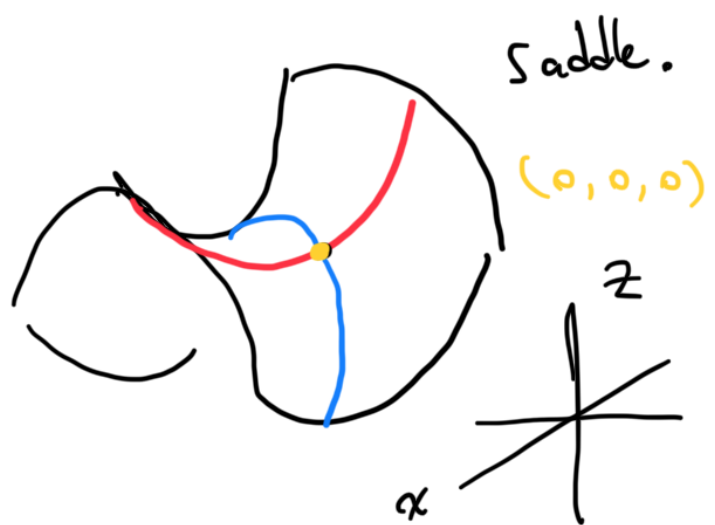
So $\nabla f(0, 0, 1) = (0, 0, 2)$ tangent plane is

$$(\nabla f)(0, 0, 1) \cdot (x - 0, y - 0, z - 1) = 0$$

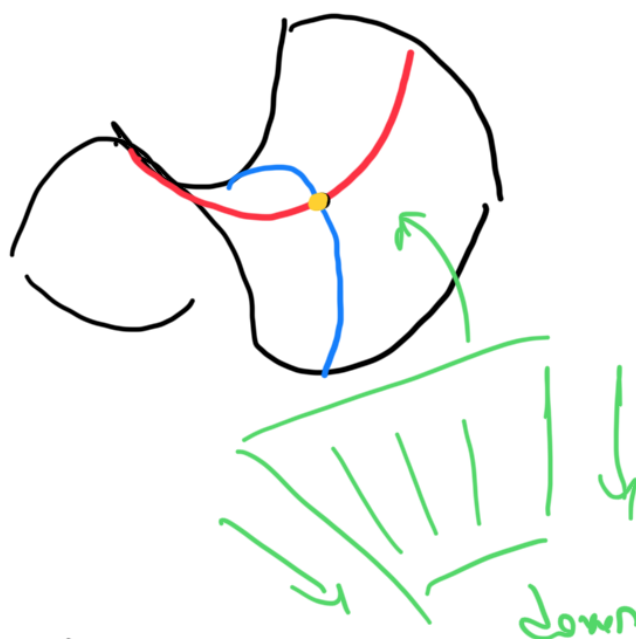
$$(0, 0, 2) \cdot (x, y, z - 1) = 0$$

$$2(z - 1) = 0 \sim z = 1 \quad !$$

ex: $f(x, y) = x^2 - y^2 = z$



Want tangent plane at $(0,1,-1)$



$$g(x,y,z) = f(x,y) - z \\ = (x^2 - y^2) - z$$

$$\nabla g(x,y,z) = (2x, -2y, -1) \text{ just proceed}$$

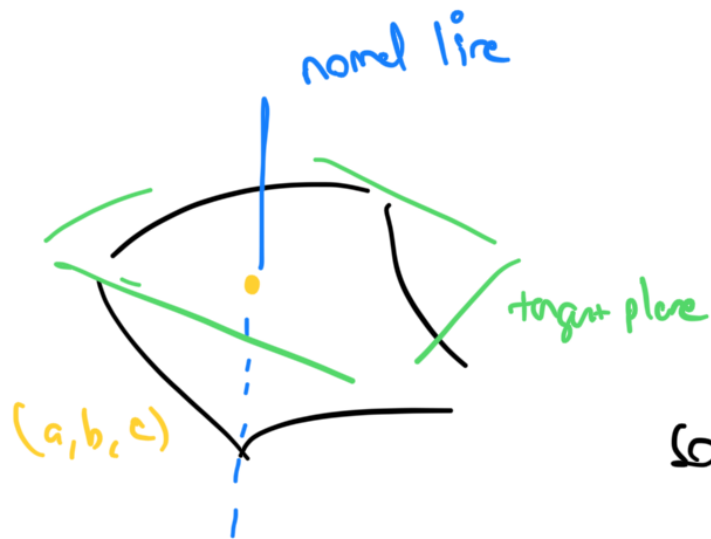
as normal.

$$\nabla g(0,1,-1) = (0, -2, -1) = \vec{n}$$

$$\text{So } \vec{n} \cdot (x-0, y-1, z-(-1)) = 0$$

$$-2(y-1) - 1(z+1) = 1 - z - 2y = 0$$

Want normal line through a point a on surface?



if surface is $f(x,y,z) = c$

then $\nabla f(a,b,c)$ will be $\perp$ to level curve c at (a,b,c) .

so normal line is

$$L(t) = (a,b,c) + t \nabla f(a,b,c)$$

ex: Calculate normal line at point $(0,1,-1)$ as above.

$$g(x,y,z) = x^2 - y^2 - z \quad \text{so } \nabla g = (2x, -2y, -1)$$

0

$$\text{thus } L(x) = (0, 1, -1) + x(0, -2, -1) \\ = (0, 1-2x, -1-x)$$

Why care about linearizing? Use it to approximate.

$$\text{Recall that } \frac{df}{d\vec{v}}(a, b) = \nabla f(a, b) \cdot \vec{v}$$

so we should have that $df(a, b)$ is related to $\nabla f(a, b) \cdot \vec{v}$ and $d\vec{v}$

Choose a small $x \approx 0$. Then we have,

$$f((a, b) + x\vec{v}) \approx f(a, b) + x \nabla f(a, b) \cdot \vec{v} \quad (*)$$

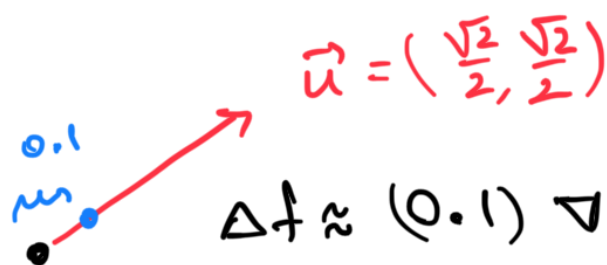
first order Taylor approximation.

$$\text{so that is to say } \Delta f(\vec{v}) \approx x \nabla f(a, b) \cdot \vec{v}$$

(text uses df)

ex: $f(x, y) = x^2 \cos(y)$ at $(1, \pi/2)$. Want to estimate the change of f if change the point $(1, \pi/2)$

0.1 units in the direction of $(\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2})$.



$$\Delta f \approx (0.1) \nabla f(1, \pi/2) \cdot (\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2})$$

$$(0, \pi/2) \quad \nabla f(x, y) = (2x \cos y, -x^2 \sin(y))$$

$$\nabla f(1, \pi/2) = (0, -1) \quad \text{so } \Delta f \approx (0.1)(0, -1) \cdot (\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2})$$

$$\Delta f \approx -\frac{\sqrt{2}}{20} \approx -0.0707 \dots \quad \text{so the answer}$$

0.1 units in the direction of $(\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2})$

$f(\text{point}) - f(0,0) \approx -0.01$ and in fact,

$$f\left(1, \frac{\sqrt{2}}{2} + (0.1)\vec{u}\right) \approx -0.08 \text{ and } f(0,0) = 0$$

So good estimate.

Another way is the tangent plane, though it's secretly the same method pretty much.

Recall

$$L(x,y) = f(a,b) + \frac{\partial f}{\partial x}(a,b)(x-a) + \frac{\partial f}{\partial y}(a,b)(y-b)$$

ex:

Say you're measuring height of some mountain

and at coordinate $(a,b) = (10\text{m}, 20\text{m})$ you estimate

the elevation is changing -2 in the x -direction and $+3$ in the y -direction. (m/m?)

if at point $(10\text{m}, 20\text{m})$ you measure the height

to be 100m , approximate the height at $(10.1\text{m}, 20.3\text{m})$

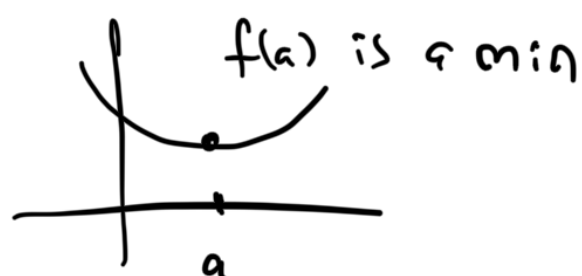
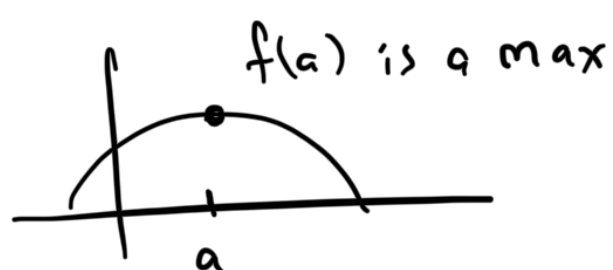
$$L(x,y) = f(10,20) + \frac{\partial f}{\partial x}(10,20)(x-10) + \frac{\partial f}{\partial y}(10,20)(y-20)$$

$$\begin{aligned} \text{So } L(x,y) &= 100 + (-2)(0.1) + (+3)(0.3) \\ &= 100 - 0.2 + 0.9 = 100.7\text{m} \end{aligned}$$

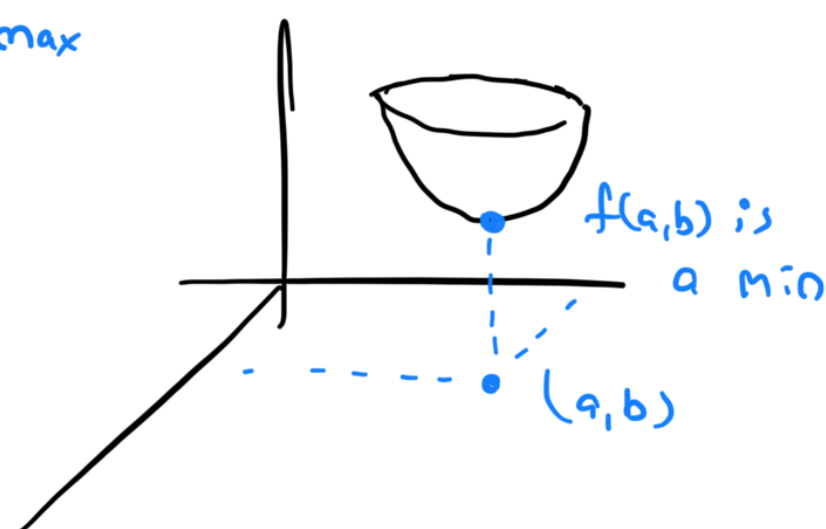
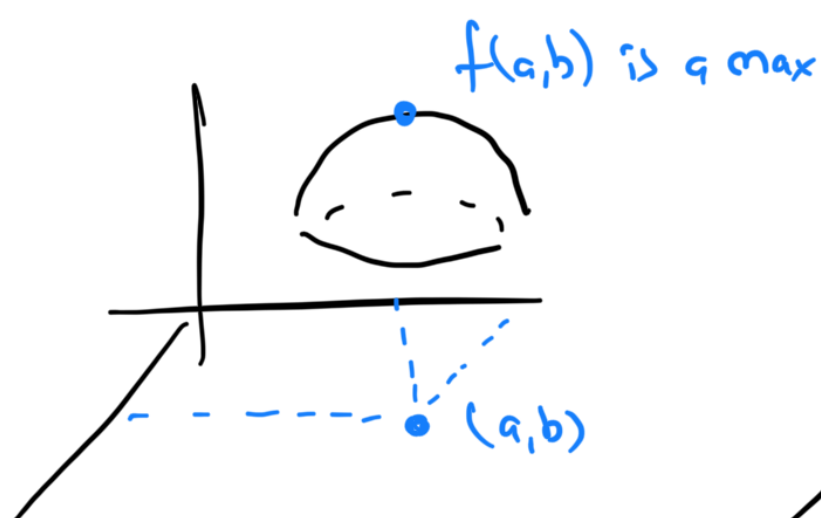
So we estimate height to be 100.7m at $(10.1\text{m}, 20.3\text{m})$

14.7: Extreme-values and Saddle points

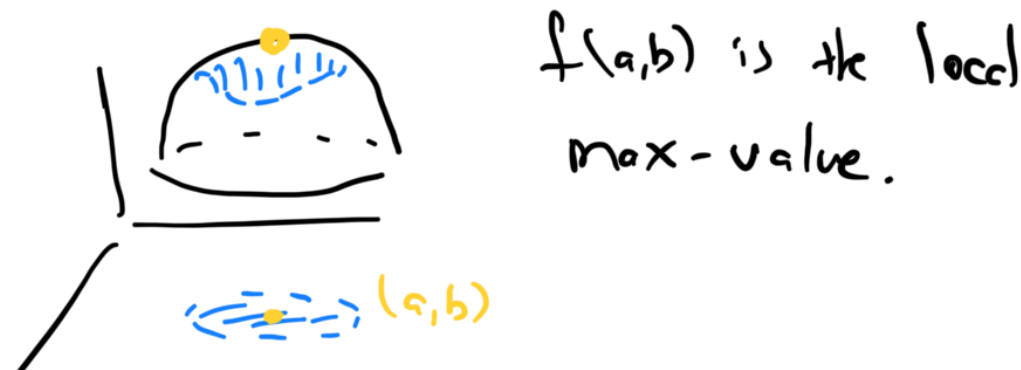
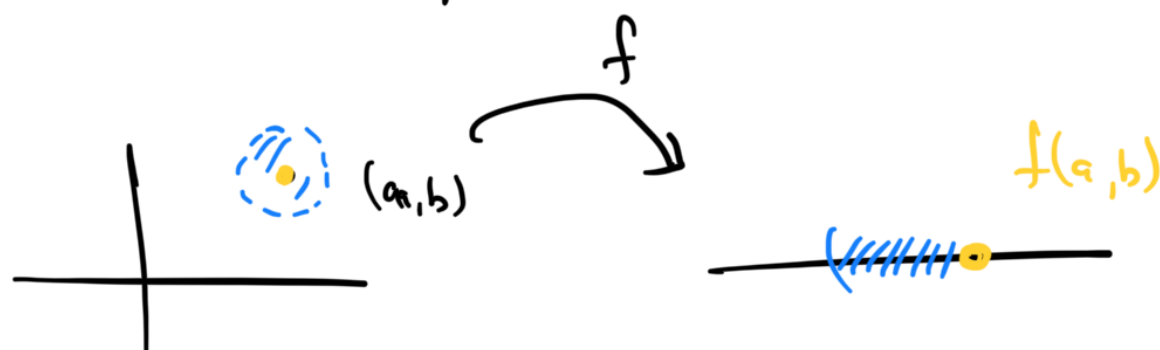
intuitively we have an idea from 1D-calc.



in 2D things are similar, but more subtle.

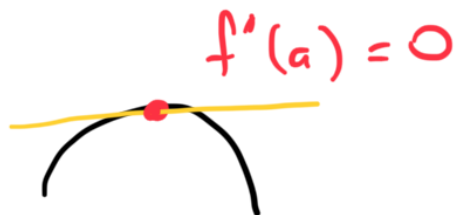


def: A point (a,b) is a local maximum if
find a small ball about (a,b) so that
for all points (x,y) in the ball, $f(x,y) \leq f(a,b)$.



local min - similar picture / definition. (pg 860)

Recall from Calc 1 if $x=a$ is a max/min
then $f'(a) = 0$



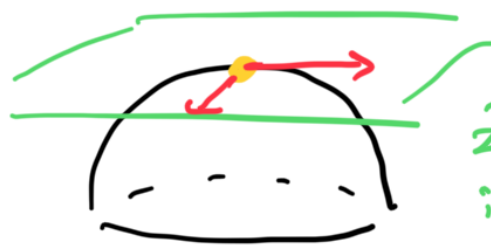
Similar statement holds in 2D.

Theorem: if (a,b) is a local max/min,

at an interior point of domain, then

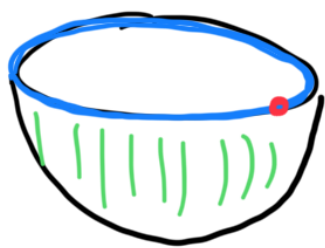
$$\frac{\partial f}{\partial x}(a,b) = \frac{\partial f}{\partial y}(a,b) = 0$$

picture to have in mind is



$z = f(a,b)$
is tangent plane.

interior point stuff is because



$f(a,b)$ also local max

e.g.: $f(x,y) = x^2 + y^2$ on disk
 $x^2 + y^2 \leq 1$.



(a,b)

boundary is local maxes, however

$\frac{\partial f}{\partial x}(a,b), \frac{\partial f}{\partial y}(a,b)$ not necessarily zero.

However at point $(a,b) = (0,0)$, it is true that

$\frac{\partial f}{\partial x} = 0, \frac{\partial f}{\partial y} = 0$ at $(0,0)$

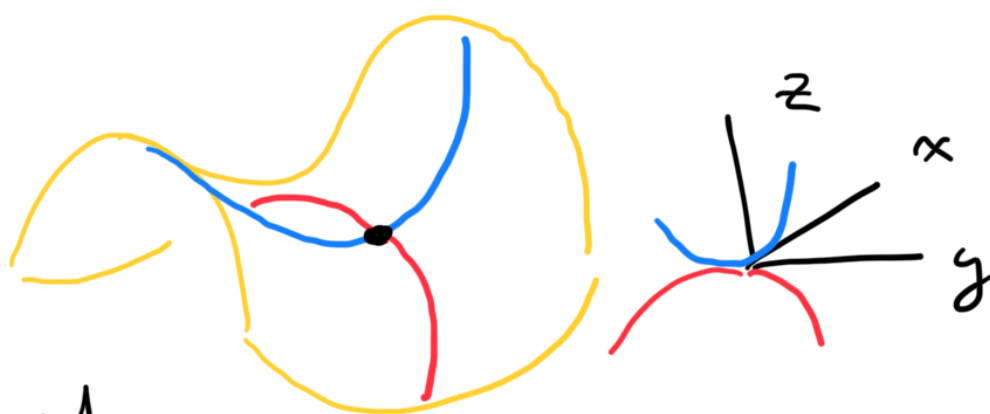
$$\frac{\partial f}{\partial x}(0,0) = \frac{\partial f}{\partial y}(0,0) = 0. \quad \text{Also}$$

local min.

Warning! Just like in 1D, $\frac{\partial f}{\partial x}(a,b) = \frac{\partial f}{\partial y}(a,b) = 0$
does not mean (a,b) is local min/max!

eg: $f(x,y) = x^2 - y^2$. Certainly $f_x(0,0) = f_y(0,0) = 0$

However,



So there are points where

$f(x,y) > f(0,0)$ and points where $f(x,y) < f(0,0)$.

def: A critical point for a function $f(x,y)$ is a point (a,b) in the interior of the domain of $f(x,y)$ where either

(i). $f_x(a,b) = f_y(a,b) = 0$ or

(ii). either $f_x(a,b)$ or $f_y(a,b)$ does not exist.

Can think of these as 'potential' max/min.

def: A critical point (a,b) is called a saddle point if there are points in every ball about (a,b) that evaluate to values both

bigger and less than $f(a, b)$.

How to tell if a critical point is a local max or local min?

Theorem: 2nd derivative test for $f(x, y)$.

Let (a, b) be a point where f_x and f_y are continuous around it. Assume also that $f_x(a, b) = f_y(a, b) = 0$ so (a, b) is a critical point.

(i). if $f_{xx} < 0$ and $f_{xx}f_{yy} - f_{xy}^2 > 0$

(at (a, b)), then (a, b) is a local max

(ii). if $f_{xx} > 0$ and $f_{xx}f_{yy} - f_{xy}^2 > 0$

then (a, b) is a local min

(iii). if $f_{xx}f_{yy} - f_{xy}^2 < 0$ then (a, b) is

a saddle point

(iv). if $f_{xx}f_{yy} - f_{xy}^2 = 0$ then test is

inconclusive.

The quantity $\begin{vmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{vmatrix}$ is called the Hessian or discriminant of f at (a, b) .

$= f_{xx}f_{yy} - f_{xy}^2$

ex: $f(x, y) = x^2 + y^2$

$$f(x,y) = x + xy - y$$

$$f_x(x,y) = 2x + y \quad f_y(x,y) = x - 2y$$

$$\begin{aligned} 2x + y &= 0 \\ x - 2y &= 0 \end{aligned} \Rightarrow y = 0 \text{ and } x = 0 \text{ so } (a,b) = (0,0).$$

$$f_{xx}(x,y) = 2 \quad f_{xy}(x,y) = 1 \quad f_{yy}(x,y) = -2$$

$$\text{so } f_{xx}f_{yy} - f_{xy}^2 = -4 - 1 = -5 < 0$$

so $(0,0)$ is a saddle point.

$$\text{ex: } f(x,y) = 3x^3 + 2xy + y^2$$

$$f_x = 9x^2 + 2y \quad f_y = 2x + 2y$$

so setting both to zero, get $x = -y$

$$\text{and then } 9(-y)^2 + 2y = 0 = y(9y + 2) = 0$$

$$\text{so } y = 0 \text{ or } y = -2/9$$

$$\text{so } (a,b) = (0,0) \text{ or } (a,b) = (2/9, -2/9).$$

$$\text{Now } f_{xx} = 18x \quad f_{xy} = 2 \quad f_{yy} = 2$$

$$\text{so } f_{xx}f_{yy} - f_{xy}^2 = 36x - 4 = 4(9x - 1)$$

$H(0,0) = -4 < 0$ so $(0,0)$ is saddle

$H(2/9, -2/9) = 4(2-1) > 0$ so either max/min.

$$\text{note } f_{xx}(2/9, -2/9) = 18(2/9) > 0$$

so local min

ex: $f(x,y) = 3x^2y - y^3$ Classify all critical points.

$$f_x(x,y) = 6xy \quad f_y(x,y) = 3x^2 - 3y^2$$

So critical points mean $6xy = 0$ and $3x^2 - 3y^2 = 0$

So either $x = 0$ & $-3y^2 = 0 \Rightarrow x = y = 0$

or $y = 0$ & $3x^2 = 0 \Rightarrow x = y = 0$

So only one option $x = y = 0$. $(a,b) = (0,0)$

Note $f_{xx}(x,y) = 6y$, $f_{yy}(x,y) = -6y$ and
 $f_{xy}(x,y) = 6x$. Thus

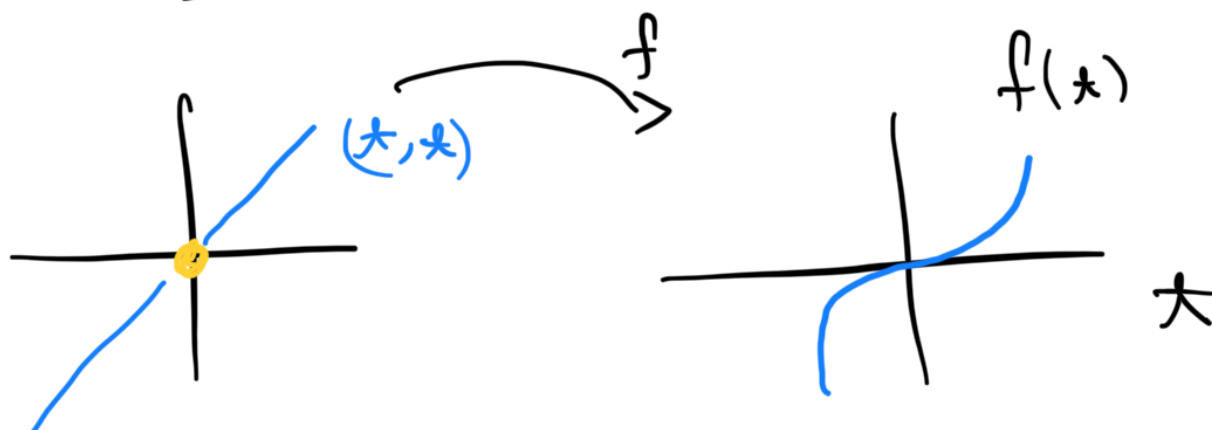
$H(0,0) = 0$, inconclusive. However, note

$$\text{that } f(x,x) = 3x^3 - x^3 = 2x^3.$$

So along $\gamma(t) = (t,t)$, there are points

so that $f(0,0) = 0 < f(t,t)$ if $t > 0$

and $f(0,0) = 0 > f(t,t)$ if $t < 0$.



So $(0,0)$ is a saddle.

One last example is boundary problems.

ex: let $f(x,y) = x^2 - y^2$ on unit disk $x^2 + y^2 \leq 1$.

Calculate local max/min and saddles.

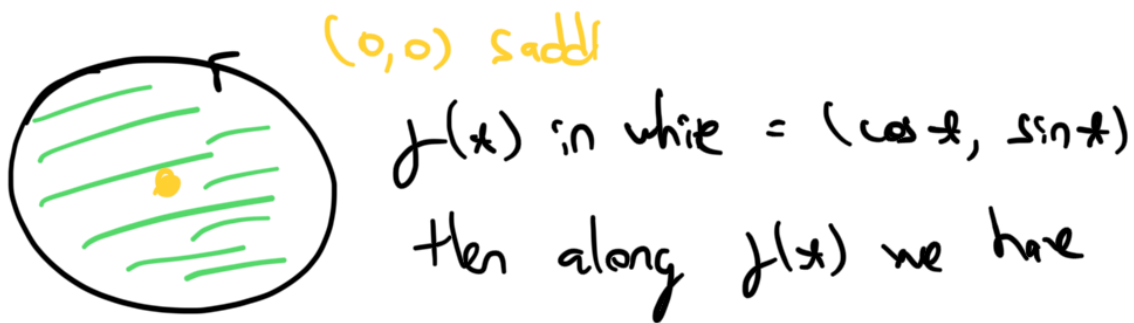
$$f_x = 2x, f_y = -2y = 0 \text{ if } x=y=0.$$

$$f_{xx} = 2 \quad f_{yy} = -2 \quad f_{xy} = 0 \text{ so}$$

$$H(x,y) = -4 < 0 \text{ so } (0,0) \text{ is a saddle.}$$

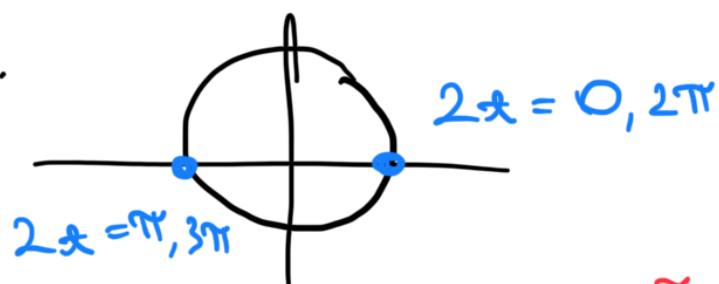
What about boundary? Parametrize by

$$j(t) = (\cos t, \sin t). \text{ Then}$$



$$(f \circ j)(t) = \cos^2 t - \sin^2 t. \text{ Reduce problem to 1-dimension.}$$
$$= \cos(2t). \text{ Minimize/maximize by}$$

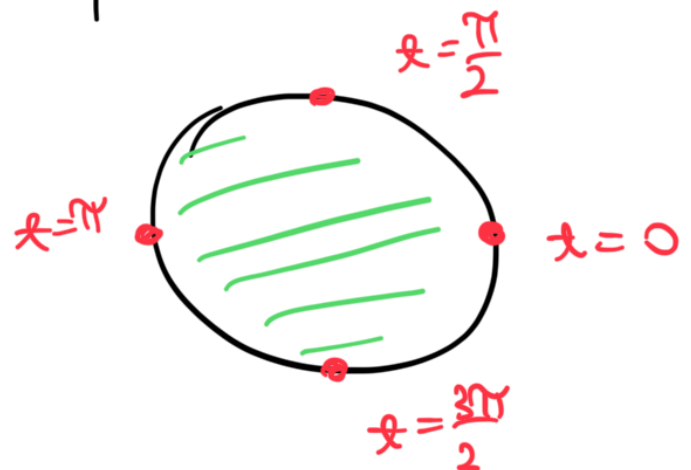
derivative or picture.



$$(f \circ j)'(t) = -2 \sin(2t)$$

$$\text{so } 2t = 0, \pi, 2\pi, 3\pi \text{ so}$$

$$t = 0, \frac{\pi}{2}, \pi, \frac{3\pi}{2}$$



Now just check

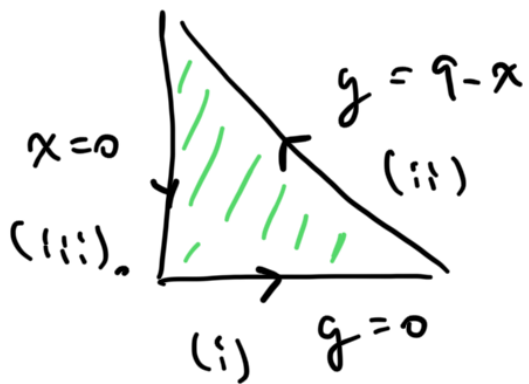
$$f(j(0)) = f(1,0) = 1^2 - 0^2 = 1$$

$$\begin{aligned}
 f(f(\pi/2)) &= f(0,1) = 0^2 - 1^2 = -1 \\
 f(f(\pi)) &= f(-1,0) = 1^2 - 0^2 = 1 \\
 f(f(\frac{3\pi}{2})) &= f(0,-1) = 0^2 - 1^2 = -1
 \end{aligned}$$

$\therefore$ global max is +1
 and
 global min is -1

ex: Just going to loosely explain ex 6 on pg. 865.

$$f(x,y) = 2 + 2x + 4y - x^2 - y^2 \quad \text{on triangle}$$



(iii) you can do, just f_x, f_y , etc.

the other things let's explain.

(i). $y=0$. $\gamma(t) = (t, 0)$ from $t=0$ to $t=9$

$$\begin{aligned}
 \text{so } (f \circ \gamma)(t) &= 2 + 2t - t^2. & (f \circ \gamma)'(t) &= 2 - 2t = 0 \\
 & \text{iff } t=1 & \gamma(1) &= \underline{(1, 0)} \\
 & \text{add to list and } t=0 \\
 & t=1, \underline{(0, 0)}, \underline{(0, 9)}
 \end{aligned}$$

(ii). $y = 9 - x$ $\gamma(t) = (9 - t, t)$ from $t=0$ to $t=9$.

$$\begin{aligned}
 (f \circ \gamma)(t) &= 2 + 2(9 - t) + 4(t) - (9 - t)^2 - t^2 \\
 &= -61 + 20t - 2t^2
 \end{aligned}$$

$$(f \circ \gamma)'(t) = 20 - 4t \quad \text{so } t=5, \gamma(5) = \underline{(4, 5)}$$

and endpoints $\gamma(0) = (9, 0)$ and $\gamma(9) = \underline{(0, 9)}$

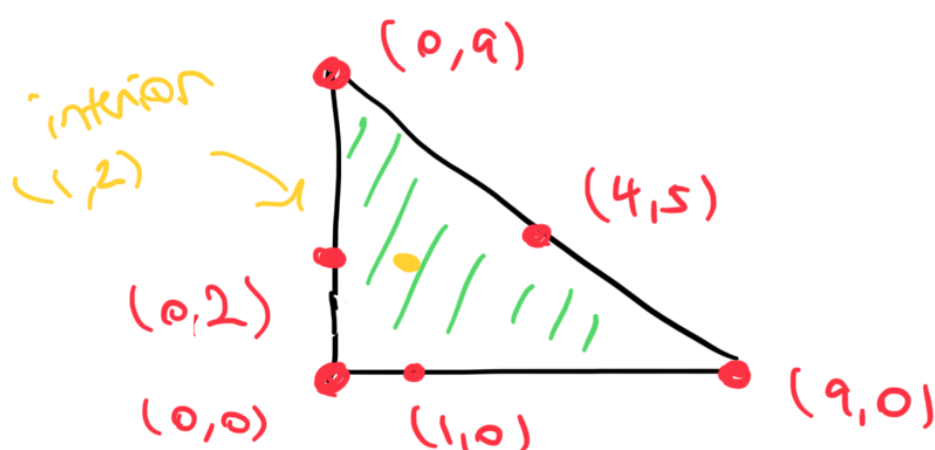
(iii). $x=0$ $\gamma(t) = (0, 9 - t)$ from $t=0$ to $t=9$

$$\begin{aligned} (f \circ \gamma)(x) &= 2 + 4(9-x) - (9-x)^2 \\ &= -43 + 14x - x^2 \end{aligned}$$

$$\text{So } (f \circ \gamma)'(x) = 14 - 2x = 0 \text{ at } x =$$

$$\text{So } \gamma(7) = \underline{(0, 2)}$$

So list of points to on boundary are



14.8: Lagrange Multipliers

Constrained optimization problems.

ex: Calculate the point on the plane

$$2x + 3y + z = 5 \quad \text{closest to the origin.}$$

could think of this as minimizing the function

$$f(x, y, z) = \sqrt{x^2 + y^2 + z^2} = \text{dist}((x, y, z), (0, 0, 0)).$$

minimizing $\uparrow$ is same as minimizing the square though, so

$$\text{instead let's take } f(x, y, z) = x^2 + y^2 + z^2.$$

However, we want our point to lie in the plane

$$z = 5 - 2x - 3y. \text{ So minimize}$$

$$f(x, y) = x^2 + y^2 + (5 - 2x - 3y)^2$$

$$f_x = 2x + 2(5 - 2x - 3y)(-2) = 2(-10 + 5x + 6y) = 0$$

$$f_y = 2y + 2(5 - 2x - 3y)(-3) = -30 + 12x + 20y = 0$$

$$\text{So } \begin{cases} 5x + 6y = 10 \\ 12x + 20y = 30 \end{cases} \quad (x, y) = \left(\frac{5}{7}, \frac{15}{14} \right)$$

Then you could check that $f_{xx} + f_{yy} - f_{xy} > 0$

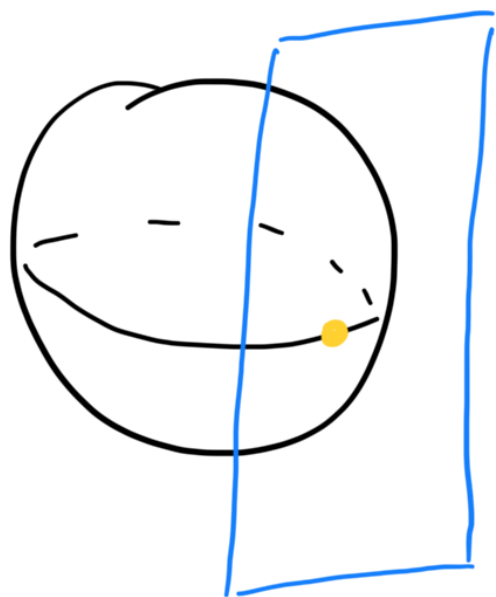
and $f_{xx} = 10 > 0$ so it's a local min,

$$\text{so the point is } \left(\frac{5}{7}, \frac{15}{14}, z = 5 - 2x - 3y \right) = \frac{5}{14}$$

closest point

ex: Another way is to imagine level surfaces of

$$f(x, y, z) = x^2 + y^2 + z^2.$$



at point of contact, the two surfaces will have the same tangent plane (and therefore parallel normals).

this is expressible algebraically as

$\nabla f = \lambda \nabla g$ where f is function of (x, y, z) that defines sphere of radius a and $g(x, y, z)$ equation that defines the plane.

$$f(x, y, z) = x^2 + y^2 + z^2 - a^2 = \text{sphere of radius } a$$

$$g(x, y, z) = 2x + 3y + z - 5 = \text{plane.}$$

$$\nabla f = (2x, 2y, 2z) \quad 2x = \lambda 2$$

$$\nabla g = (2, 3, 1) \quad \begin{array}{l} 2y = \lambda 3 \\ 2z = \lambda 1 \end{array} \quad \text{then solve.}$$

$$x = \lambda$$

$$y = \frac{3}{2}\lambda \quad \text{and we know } 2(\lambda) + 3\left(\frac{3}{2}\lambda\right) + \frac{1}{2}\lambda - 5 = 0$$

$$z = \frac{1}{2}\lambda \quad \lambda \left(\frac{4 + 9 + 1}{2} \right) = 5 \quad \text{so } \lambda = 5/7$$

$$\text{thus } (x, y, z) = \left(\frac{5}{7}, \frac{15}{14}, \frac{5}{14} \right)$$

Theorem of Lagrange Multiplier

Suppose $f(x, y, z)$ and $g(x, y, z)$ are differentiable and $\nabla g \neq 0$ when $g(x, y, z) = 0$.

To find the local max/min values of f

subject to constraint $g(x, y, z) = 0$

find the values of (x, y, z) that satisfy both

$$\nabla f = \lambda \nabla g \quad \text{and} \quad g(x, y, z) = 0$$

(1.1) for functions of 2-variables.

ex 14, 8, 23: Find max/min to $f(x, y, z) = x - 2y + 5z$
on the sphere $x^2 + y^2 + z^2 = 30$.

Constraint $g(x, y, z) = x^2 + y^2 + z^2 - 30$

function $f(x, y, z) = x - 2y + 5z$

$$\nabla f = (1, -2, 5) \quad \nabla g = (2x, 2y, 2z)$$

$$\begin{array}{lll} 1 = \lambda 2x & \lambda = 2x & x = \lambda/2 \\ -2 = \lambda 2y & \text{or } -2\lambda = 2y & y = -\lambda \\ 5 = \lambda 2z & 5\lambda = 2z & z = 5/2 \lambda \end{array}$$

↓ plug into g solve λ .

$$\left(\frac{\lambda}{2}\right)^2 + (-\lambda)^2 + \left(\frac{5}{2}\lambda\right)^2 - 30 = 0$$

$$\lambda^2 \left(\frac{1}{4} + 1 + \frac{25}{4} \right) = 30$$

$$\lambda^2 \left(\frac{30}{4} \right) = 30 \quad \text{so} \quad \lambda^2 = 4, \quad \lambda = \pm 2.$$

thus $(a, b, c) = (1, -2, 5)$ or $(a, b, c) = (-1, 2, -5)$

$$\begin{aligned} f(1, -2, 5) &= 1 - 2(-2) + 25 & \& \quad f(-1, 2, -5) = -30 \\ &= 30 \text{ max} & & \text{min} \end{aligned}$$

ex: 14, 8, 14

temperature on plate is $T(x, y) = 4x^2 - 4xy + y^2$.

ant on circle of radius 5 about origin walks
around

... at the highest / lowest temperatures.

$$\text{function: } T(x, y) = 4x^2 - 4xy + y^2$$

$$\text{constraint: } g(x, y) = x^2 + y^2 - 25$$

$$\nabla T = \lambda \nabla g \quad \nabla T = (8x - 4y, -4x + 2y)$$

$$\nabla g = (2x, 2y) \quad -$$

$$\text{So } \begin{aligned} (8x - 4y) &= \lambda 2x \\ (-4x + 2y) &= \lambda 2y \end{aligned} \quad , \quad \begin{aligned} 2y - 2y\lambda &= 4x \\ 2y(1 - \lambda) &= 4x \end{aligned}$$

$$\begin{aligned} 2y(1 - \lambda) &= 4x \\ \frac{1}{2} y(1 - \lambda) &= x \end{aligned}$$

$$4x - 2y = \lambda x$$

$$2y(1 - \lambda) - 2y = \lambda \left(\frac{1}{2} y(1 - \lambda) \right)$$

$$-4y\lambda = \lambda y(1 - \lambda)$$

$$0 = \lambda (y(1 - \lambda) + 4y) = \lambda (5y - y\lambda)$$

$$0 = y\lambda(5 - \lambda)$$

$$y = 0 \Rightarrow x^2 + y^2 = x^2 = 25 \text{ so } \underline{(-5, 0)} \text{ \& } \underline{(+5, 0)}$$

$$\lambda = 0 \Rightarrow \nabla T = \vec{0} \quad \begin{aligned} 8x - 4y &= 0 \\ -4x + 2y &= 0 \end{aligned} \Rightarrow y = 2x$$

$$\text{so } x^2 + 4^2 x^2 = 25 \Rightarrow x = \pm \sqrt{5}$$

$$\underline{(-\sqrt{5}, -2\sqrt{5})} \text{ or } \underline{(+\sqrt{5}, 2\sqrt{5})}$$

$$\lambda = 5 \Rightarrow y(-4) = 2x \quad \text{so} \quad 4y^2 + y^2 = 25 \text{ so}$$

$$x = -2y$$

$$y = \pm \sqrt{5}$$

$$\underline{(2\sqrt{5}, -\sqrt{5})} \text{ or } \underline{(-2\sqrt{5}, \sqrt{5})}$$

$$\begin{aligned} f(\pm 5, 0) &= 100 \leftarrow \text{doesn't count bc } \nabla g \neq \vec{0} \\ f(\sqrt{5}, 2\sqrt{5}) &= 0 \leftarrow \text{min} \\ f(2\sqrt{5}, \sqrt{5}) &= 125 \leftarrow \text{max} \end{aligned}$$

ex: 14.5.7 (two constraints)

find maxima of $f(x, y, z) = x^2 + 2y - z^2$

subject to $2x - y = 0$ and $y + z = 0$

here $\nabla f = \lambda \nabla g + \mu \nabla h$

where $f = \text{above}$ and $g = 2x - y$ $h = y + z$

$$\nabla f = (2x, 2, -2z) \quad (2x, 2, -2z) = (2\lambda, -\lambda, 0)$$

$$\nabla g = (2, -1, 0) \quad + (0, \mu, \mu)$$

$$\nabla h = (0, 1, 1) \quad 2x = 2\lambda$$

$$2 = -\lambda + \mu \Rightarrow \mu = 2 + \lambda$$

$$-2z = \mu$$

$$x = \lambda$$

$$\mu = 2 + \lambda = -2z$$

$$z = -1 - \frac{\lambda}{2}$$

$$2x - y = 0$$

$$\text{so } 2\lambda + z = 0 \text{ bc } z = -y$$

$$2\lambda - 1 - \frac{\lambda}{2} = 0$$

$$\frac{3}{2}\lambda = 1 \text{ so } \lambda = \frac{2}{3}$$

$$\text{and } \mu = \frac{8}{3}$$

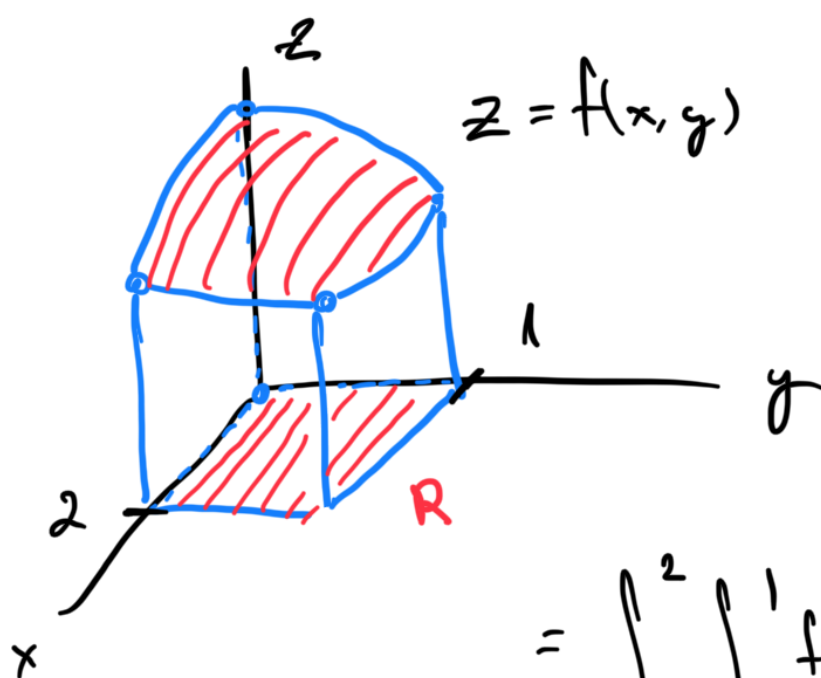
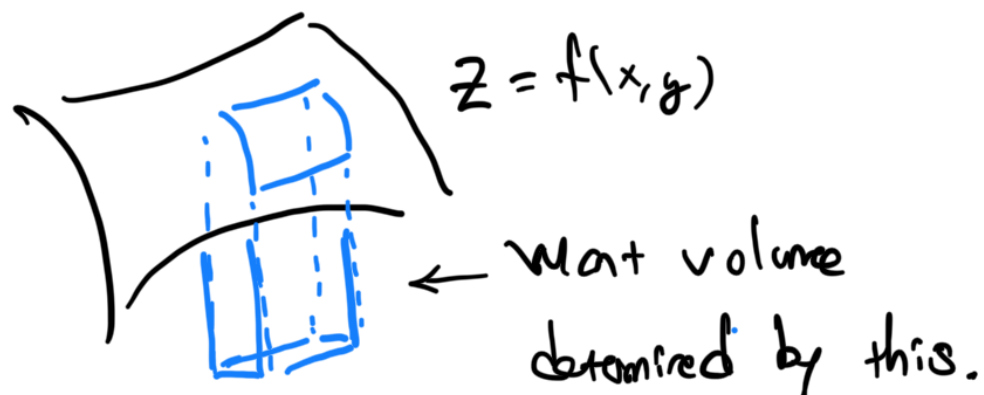
$$\text{so } x = \frac{2}{3}$$

$$z = -1 - \frac{1}{3} = -\frac{4}{3}$$

$$y = \frac{4}{3}$$

15.1: Double integrals over rectangles.

let $z = f(x, y)$ be some function.



$$\text{Volume} = \iint_R f(x, y) dA$$

$$= \int_0^1 \int_0^2 f(x, y) dx dy$$

$$= \int_0^2 \int_0^1 f(x, y) dy dx$$

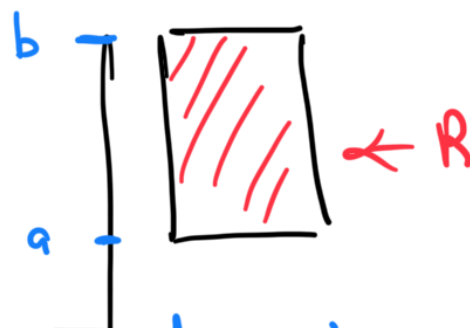
true in general: Fubini's theorem:

let $f(x, y)$ be defined over rectangular

region R , then

$$\iint_R f(x, y) dA = \int_a^b \int_c^d f(x, y) dx dy$$

$$= \int_c^d \int_a^b f(x, y) dy dx$$



ex: $\iint_R 4 - x - y^2$ on region $R = \begin{matrix} 0 \leq x \leq 4 \\ 0 \leq y \leq 2 \end{matrix}$

$$= \int_0^4 \int_0^2 4 - x - y^2 dy dx = \int_0^4 \left. 4y - xy - \frac{1}{3}y^3 \right|_0^2 dx$$

$$= \int_0^4 8 - 2x - \frac{8}{3} dx = \frac{16}{3} \int_0^4 dx - 2 \int_0^4 x dx$$

$$= \frac{16}{3} (x) \Big|_0^4 - 2 \left(\frac{1}{2} x^2 \right) \Big|_0^4 = \frac{16}{3} \cdot 4 - 2 \cdot 8$$

$$= 16/3$$

or

$$\iint_R 4 - x - y^2 dx dy = \int_0^2 \left. 4x - \frac{1}{2}x^2 - y^2 x \right|_0^4 dy$$

$$= \int_0^2 16 - 8 - 4y^2 dy = 8 \int_0^2 dy - 4 \int_0^2 y^2 dy$$

$$= 8(y) \Big|_0^2 - \frac{4}{3} y^3 \Big|_0^2 = 16 - \frac{32}{3} = 16/3$$

ex: $\int_{-1}^1 \int_{-\pi}^{\pi} \frac{\sin(xy^2)}{1+y^2} dy dx$ 22
e.

However...

$$\int_{-\pi}^{\pi} \int_{-1}^1 \frac{\sin(xy^2)}{1+y^2} dx dy$$

$$= \int_{-\pi}^{\pi} \frac{-\cos(xy^2)}{y^2(1+y^2)} \Big|_{x=-1}^{x=1} dy = \int_{-\pi}^{\pi} \frac{-\cos(y^2) + \cos(-y^2)}{y^2(1+y^2)} dy$$

$$= \int_{-\pi}^{\pi} \frac{0}{y^2(1+y^2)} dy = 0 \quad (\text{Sometimes reversing order of integration helps!})$$

15.2. Integration over general regions

We know how to integrate over rectangles.

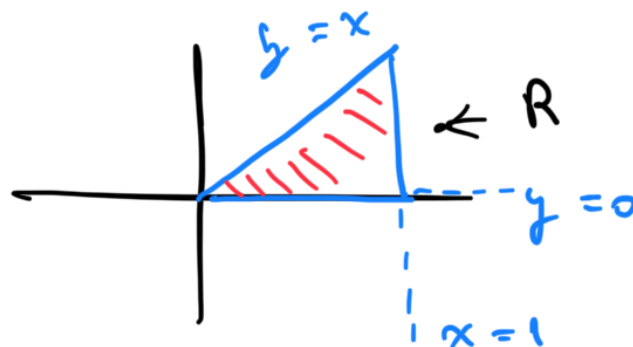
What about general regions?

e.g.

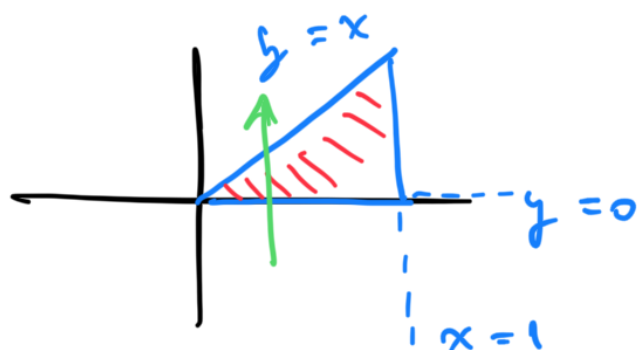


$$\iint_R f(x,y) dA = ?$$

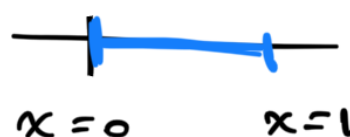
ex: $\iint_R x+y^2 dA$ over triangle defined by $y=x$, $y=0$, $x=1$.



(i).



smash



enter at $y=0$

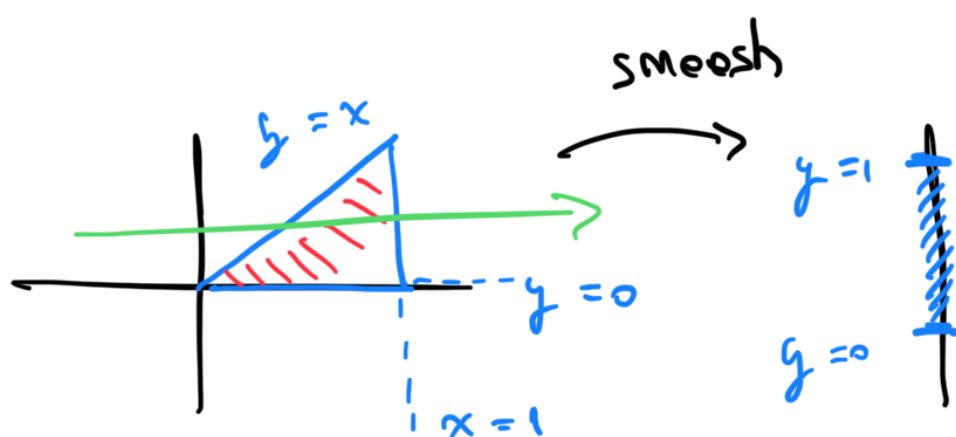
exit at $y=x$

$$\int_{\text{enter } y=0}^{\text{exit } y=x} f(x, y) dy + \int_{x=0}^{x=1} \int_{y=0}^{y=x} x + y^2 dy dx$$

$$= \int_0^1 \int_0^x x + y^2 dy dx = \int_0^1 \left. xy + \frac{1}{3}y^3 \right|_0^x dx$$

$$= \int_0^1 x^2 + \frac{1}{3}x^3 dx = \left. \frac{1}{3}x^3 + \frac{1}{12}x^4 \right|_0^1 = \frac{1}{3} + \frac{1}{12} = \frac{5}{12}$$

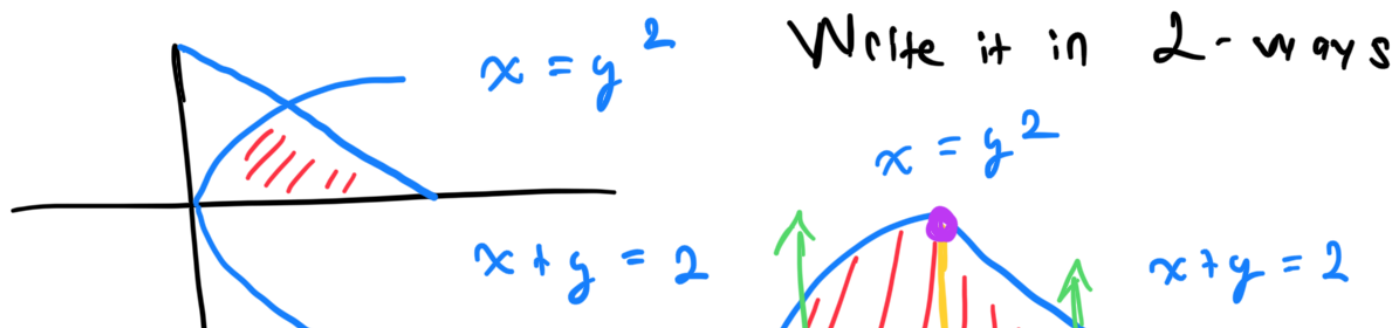
or

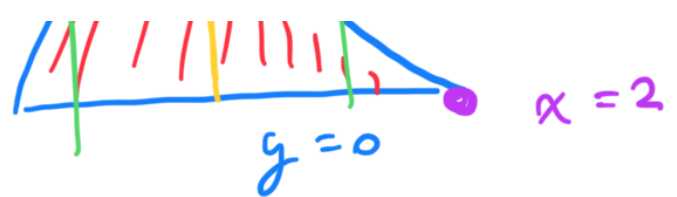


$$\int_{\text{enter } x=y}^{\text{exit } x=1} f(x, y) dx + \int_{y=0}^{y=1} \int_{\text{enter } x=y}^{\text{exit } x=1} f(x, y) dx dy$$

Can do integral, same answer.

ex: Integrate a function $f(x, y)$ over

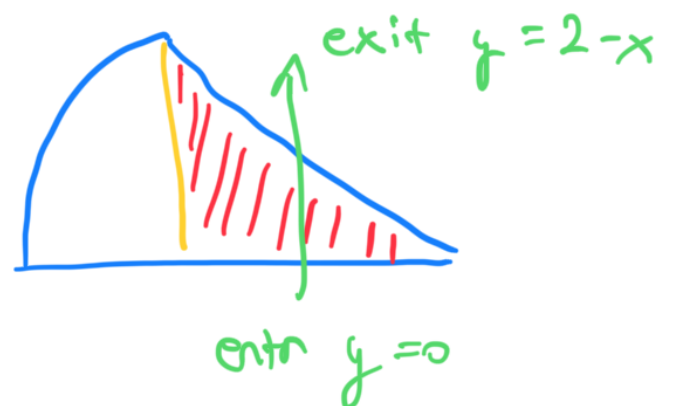
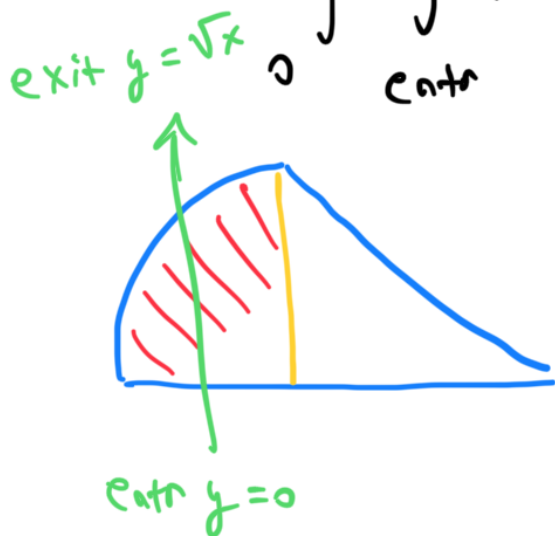




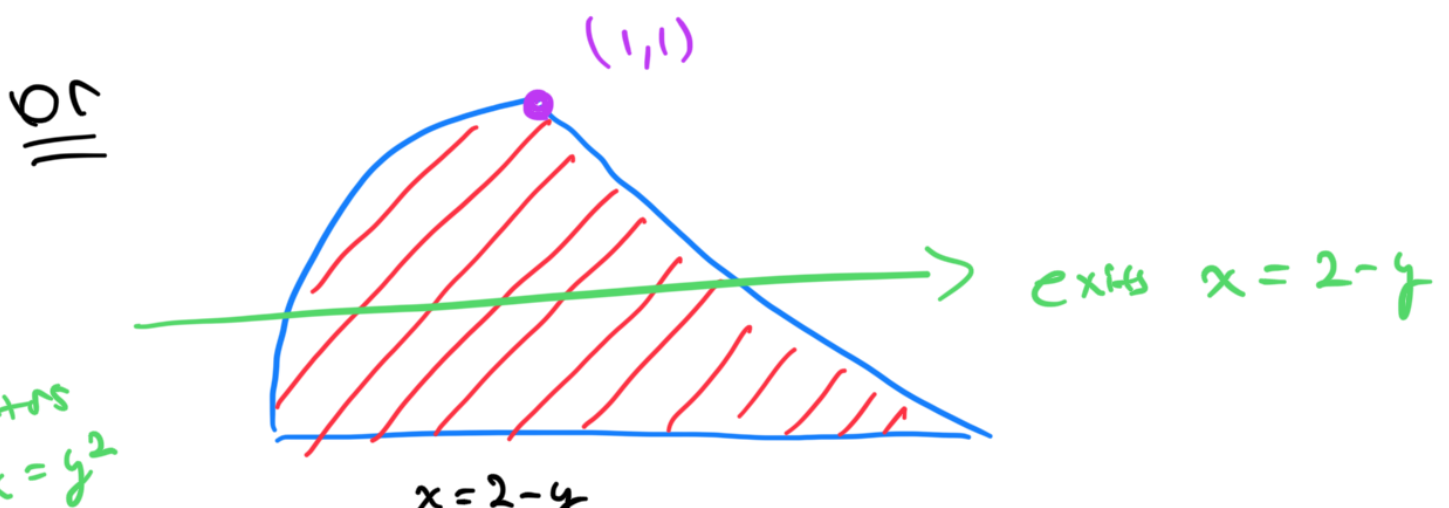
notice where you enter and exit now depends on which x -value you're at! point in purple is where curves intersect $y^2 = 2 - x$

$$y^2 + y - 2 = 0 \text{ solutions } y = 1 \\ = (y+2)(y-1) = 0 \text{ and } y = -2$$

$$\text{So } I = \int_0^1 \int_{\text{entr}}^{\text{exit}} \text{---} dy dx + \int_1^2 \int_{\text{entr}}^{\text{exit}} \text{---} dy dx$$



$$\text{So } I = \int_0^1 \int_{y=0}^{y=\sqrt{x}} f(x,y) dy dx + \int_1^2 \int_{y=0}^{y=2-x} f(x,y) dy dx$$



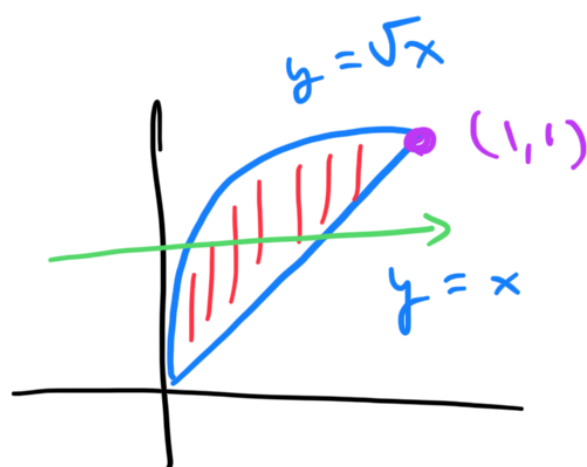
$$\text{So } I = \int_0^1 \int_{x=y^2}^{x=2-y} f(x,y) dx dy$$

In particular if $f(x,y) \equiv 1$, then we just

Get the area:

$$\begin{aligned} \text{e.g. } A &= \int_0^1 \int_{y^2}^{2-y} dx dy = \int_0^1 2-y-y^2 dy \\ &= 2y - \frac{1}{2}y^2 - \frac{1}{3}y^3 \Big|_0^1 \\ &= 2 - \frac{1}{2} - \frac{1}{3} = \frac{7}{6} \end{aligned}$$

$$\text{ex: } \int_0^1 \int_x^{\sqrt{x}} \frac{\sin(y)}{y} dy dx$$



$$= \int_0^1 \int_{y^2}^y \frac{\sin(y)}{y} dx dy$$

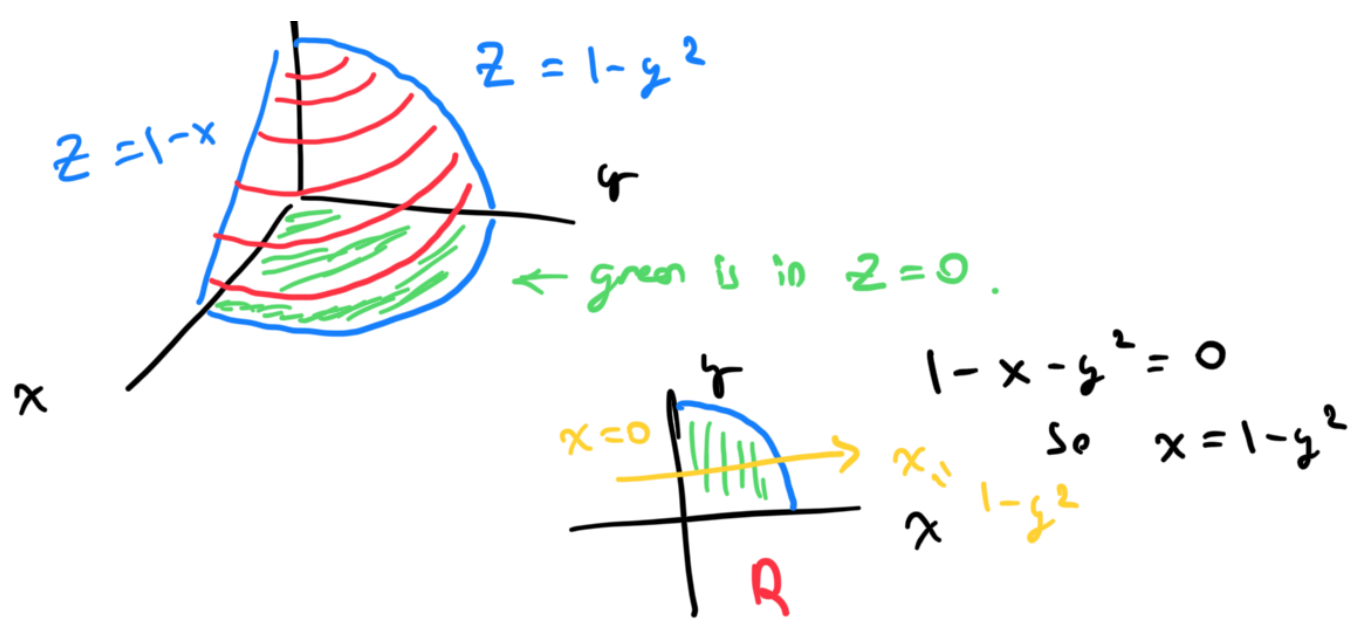
enters $x = y^2$ exits $x = y$

$$= \int_0^1 \frac{\sin(y)}{y} x \Big|_{y^2}^y dy = \int_0^1 \frac{\sin(y)}{y} (y - y^2) dy$$

$$= \int_0^1 \underbrace{\sin(y)}_{\text{simple}} - y \underbrace{\sin(y)}_{\text{integration by parts}} dy = 1 - \sin(1)$$

two applications: Volume of a section of a surface and average value.

ex: Calculate volume determined by $z = 1 - x - y^2$ in first octant bounded by z .



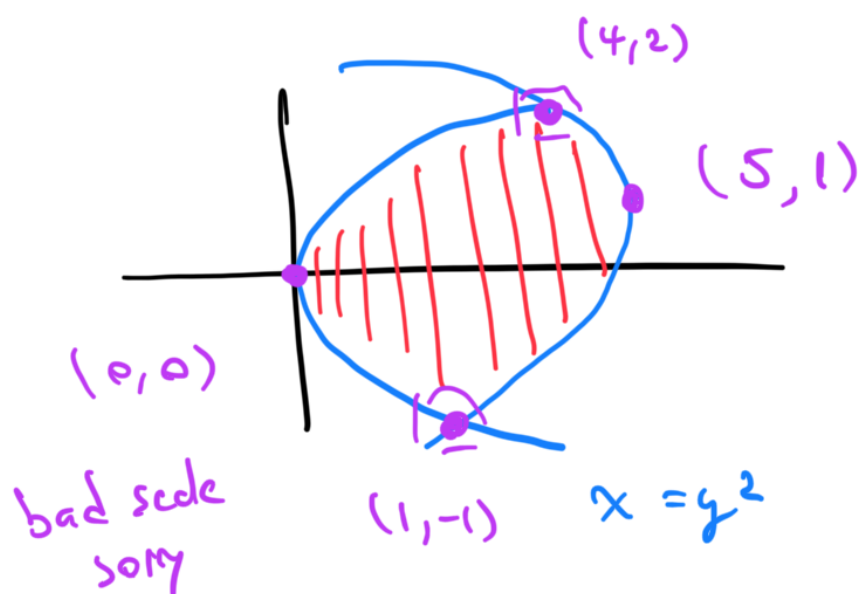
$$V = \iint_R z \, dA = \int_0^1 \int_0^{1-y^2} (1-x-y^2) \, dx \, dy = \frac{4}{15}$$

15.3. Areas by double integrals

As mentioned earlier if integrate $f(x,y) \equiv 1$ on a region R , you just get Area of region.

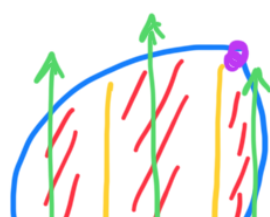
ex: Calculate area of region defined by

$$x = y^2 \text{ and } x = 5 - (y-1)^2$$



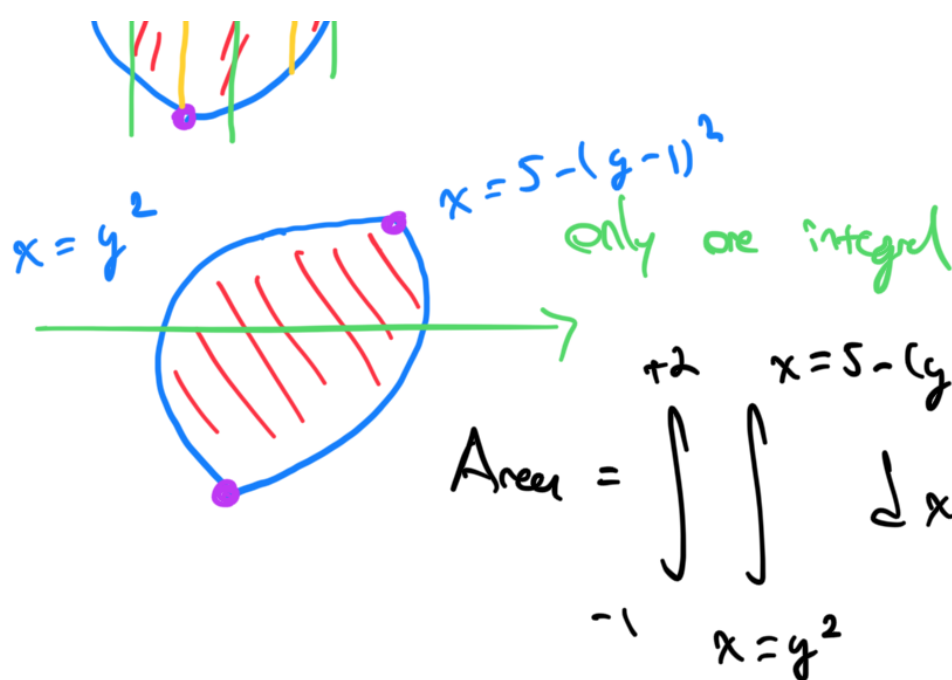
Solve for boxed points by setting $y^2 = 5 - (y-1)^2$.

(i).



3 different integrals $\therefore$

(i).



ex: Calculate average value of a function over region R.

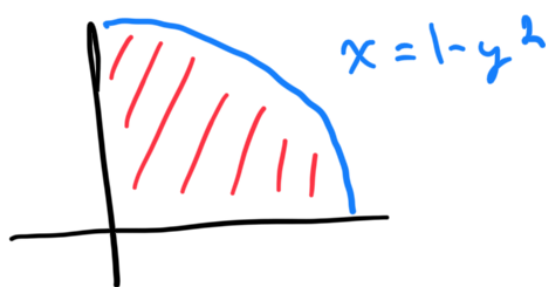
$$Avg(f, R) = \frac{\iint_R f dA}{\text{Area of } R}$$

So for example, with $f(x, y) = 1 - x - y^2$ and R from 15.2

$$Avg(f, R) = \frac{\iint_0^1 \int_0^{1-y^2} 1 - x - y^2 dx dy}{\iint_0^1 \int_0^{1-y^2} dx dy}$$

(i).

(ii).



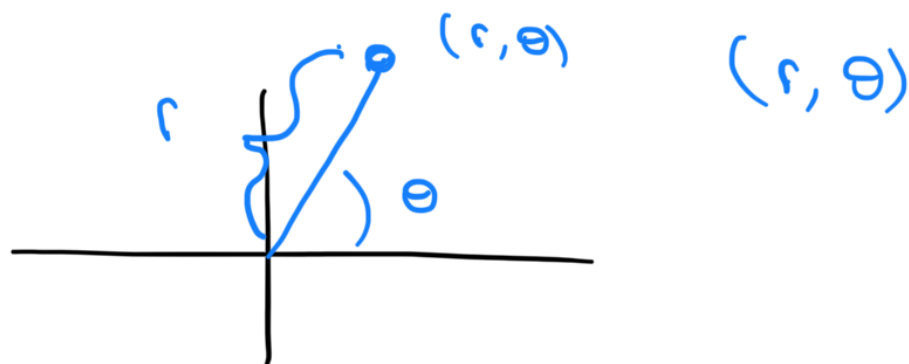
(i). Already did, $4/15$

$$(ii). \int_0^1 \int_0^{1-y^2} dx dy = \int_0^1 1 - y^2 dy = \left[y - \frac{1}{3}y^3 \right]_0^1 = 2/3$$

$$\text{so } \text{Avg}(f, R) = \frac{4/15}{2/3} = \frac{2}{5}$$

15.4: Polar Coordinate Integrals

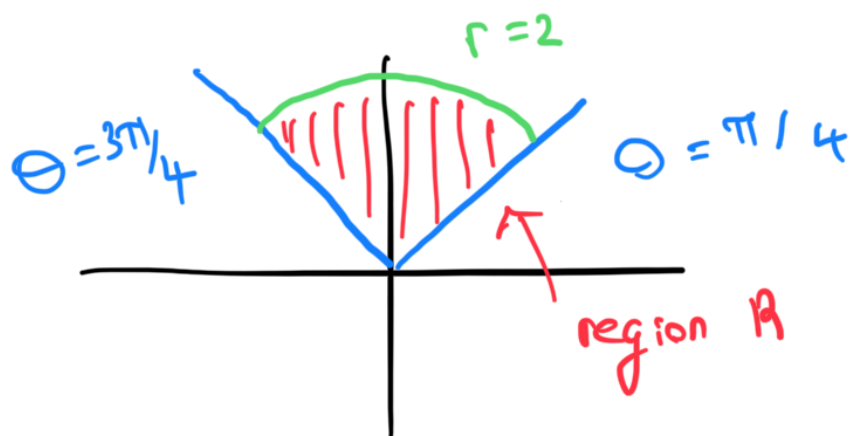
Polar coordinates are another way of specifying points in the plane instead of (x, y) .



one issue however is that coordinates are no longer unique. e.g.: $(1, \pi/4)$ and $(1, \pi/4 + 2\pi)$ are same point.

Also $(0, \pi)$ and $(0, \pi/2)$ are same point. true for any $(0, \theta)$.

ex: What does all (r, θ) with $r=2$ and $\pi/4 \leq \theta \leq 3\pi/4$ look like?



in green we get $r=2, \pi/4 \leq \theta \leq 3\pi/4$

in red we get region
 $0 \leq r \leq 2, \pi/4 \leq \theta \leq 3\pi/4$

ex: What does $r = \cos \theta$ look like?

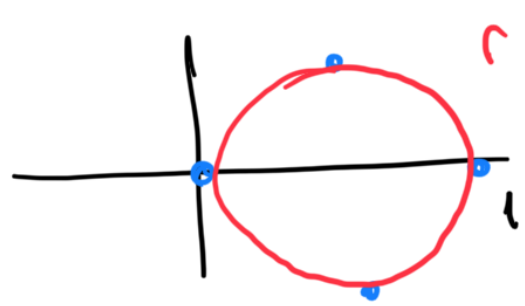
$$\theta = \pi/2, r(\pi/2) = 0$$

$$\theta = \pi/4, r(\pi/4) = \sqrt{2}/2$$

$$\theta = 3\pi/4, r(3\pi/4) = -\sqrt{2}/2$$

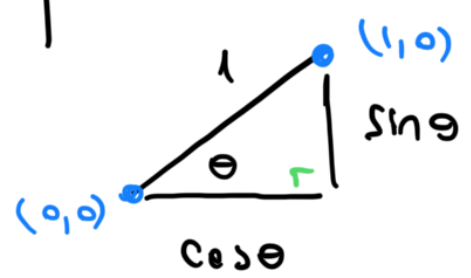
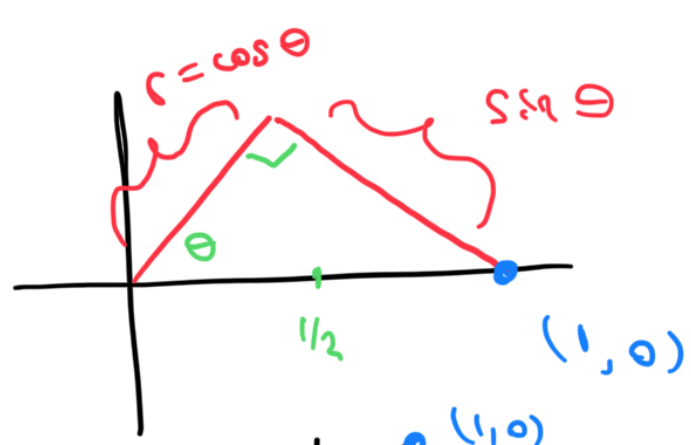
$$\theta = 0, r(0) = 1$$

keep doing ...



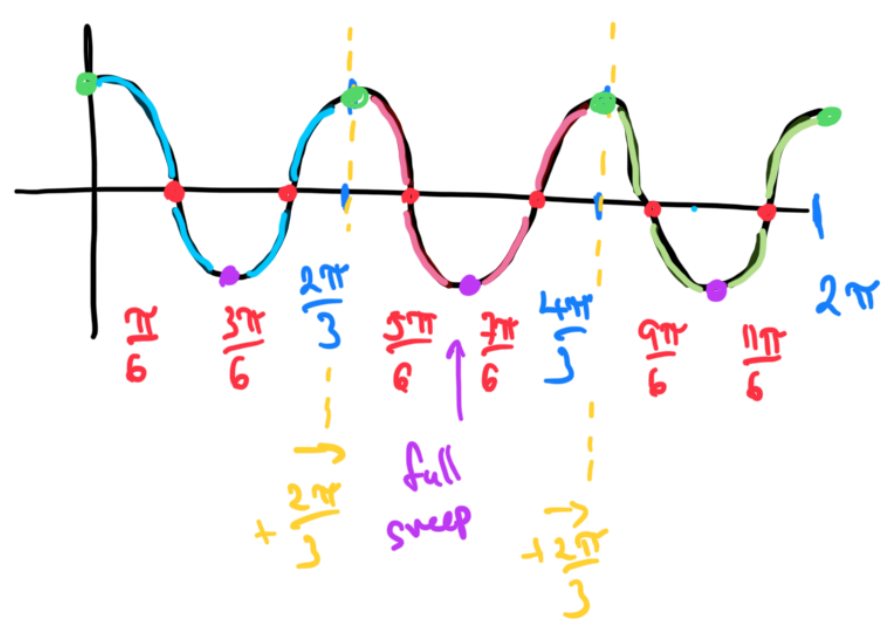
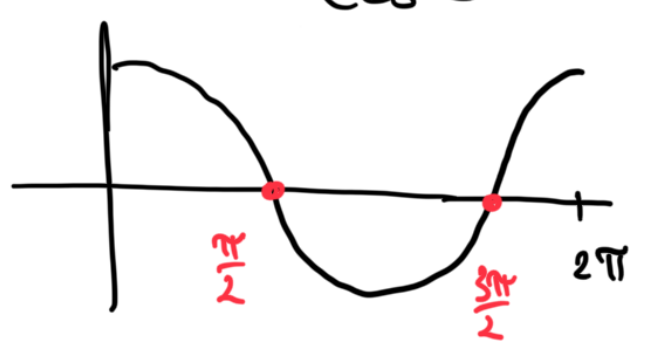
$r = \cos \theta$

one way to see this

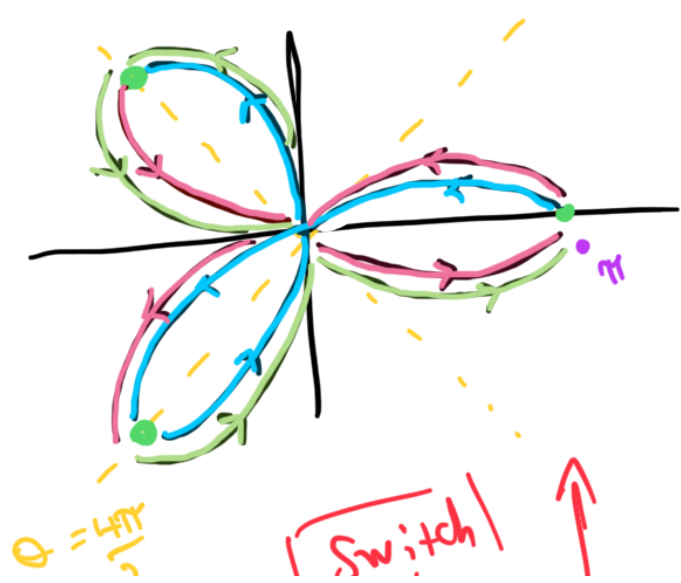


ex: $r = \cos 3\theta$

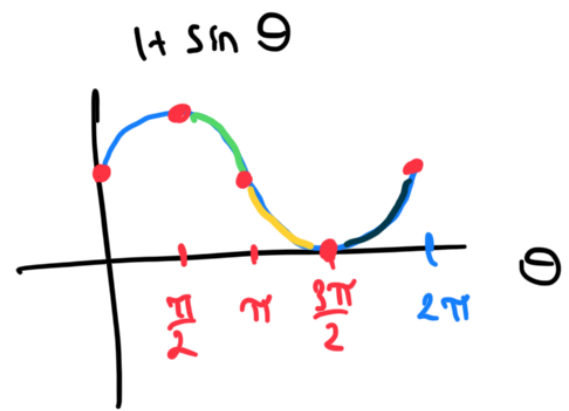
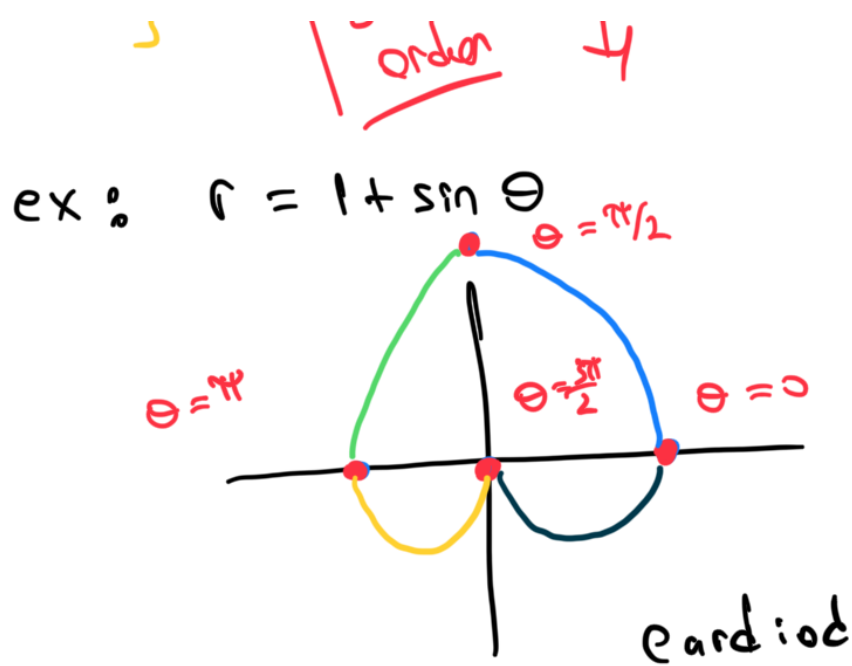
$\cos \theta$



$\theta = 2\pi/3$



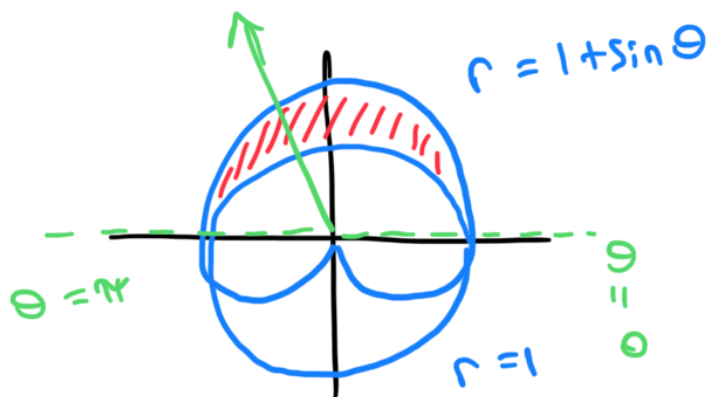
don't sweat this example too much. Just wanted to show how this looks mostly.



Integrate functions $f(r, \theta)$ over regions R

$$\iint_R f(r, \theta) dA = \int_{\theta=\alpha}^{\theta=\beta} \int_{r=g_1(\theta)}^{r=g_2(\theta)} f(r, \theta) \underbrace{r dr d\theta}_{dA = r dr d\theta}$$

ex: Calculate area between circle radius 1 and cardioid $r = 1 + \sin \theta$ as illustrated



enters at $r=1$
exits at $r=1+\sin \theta$

$$\begin{aligned} \iint_R 1 \cdot r dr d\theta \\ = \int_0^{\pi} \int_{r=1}^{r=1+\sin \theta} r dr d\theta \end{aligned}$$

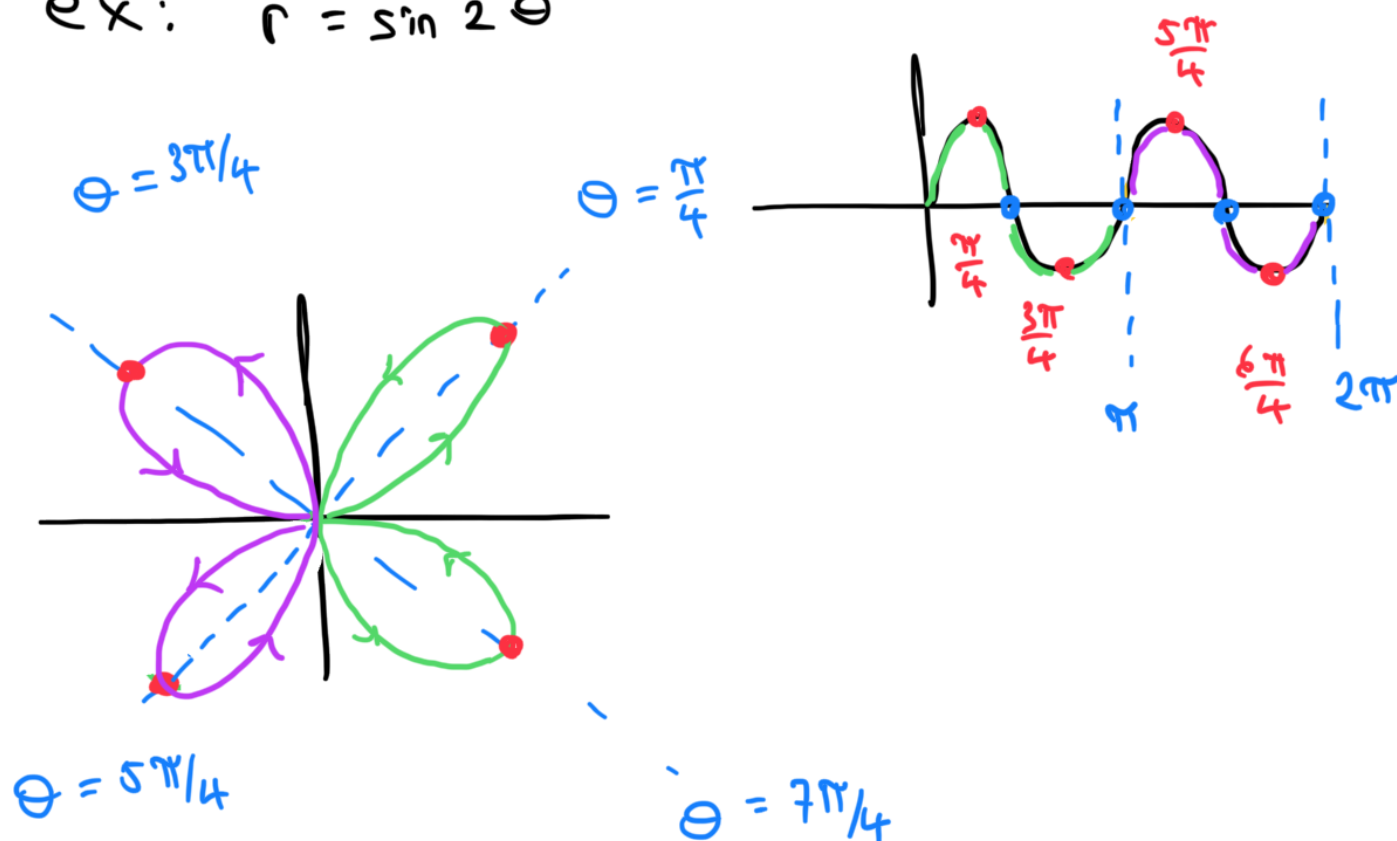
$$= \int_0^{\pi} \left(\frac{1}{2} r^2 \right) \Big|_1^{1+\sin \theta} d\theta$$

$$= \frac{1}{2} \int_0^{\pi} [(1+\sin \theta)^2 - 1^2] d\theta$$

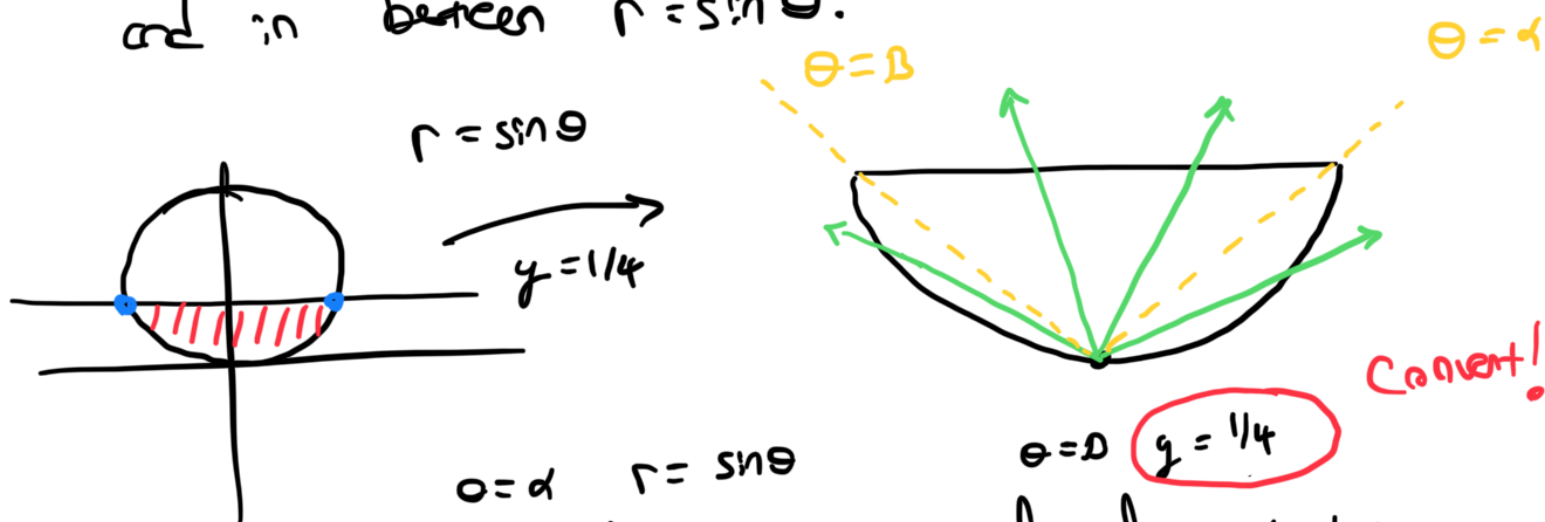
$$= \frac{1}{2} \left(\int_0^{\pi} 2 \sin(\theta) + \sin^2 \theta \, d\theta \right)$$

$$= \frac{1}{2} \left(\frac{8+\pi}{2} \right) = 2 + \frac{\pi}{4}$$

ex: $r = \sin 2\theta$



ex: Calculate area below $y = \frac{1}{4}$ above $y = 0$ and in between $r = \sin \theta$.



So Area =

$$\int_{\theta=0}^{\theta=\pi} \int_{r=0}^{r=\sin \theta} r \, dr \, d\theta \quad (i)$$

$$+ \int_{\theta=\alpha}^{\theta=\beta} \int_{r=0}^{r=\sin \theta} r \, dr \, d\theta \quad (ii)$$

$$+ \int_{\theta=\beta}^{\theta=\pi} \int_{r=0}^{r=\sin \theta} r \, dr \, d\theta \quad (iii).$$

Cartesian to Polar and vice versa

1.

$$x = r \cos \theta \quad y = r \sin \theta \quad r = \sqrt{x^2 + y^2}$$

$$\tan \theta = y/x \quad (\text{kinda})$$

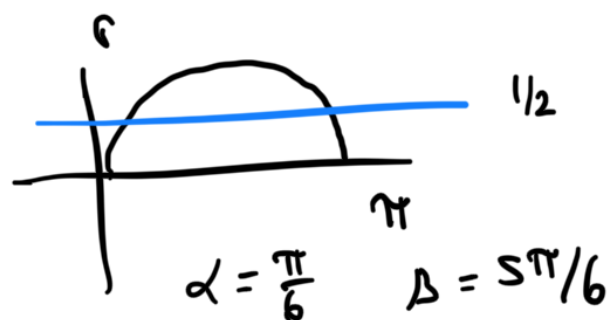
so $y = \frac{1}{4} \rightarrow r \sin \theta = \frac{1}{4} \Rightarrow r = \frac{1}{4} \csc \theta$ so

(ii) is $\int_{\theta=\alpha}^{\theta=\beta} \int_{r=0}^{r=\frac{1}{4} \csc \theta} r \, dr \, d\theta$

2. Find α and β . Then when $r = \frac{1}{4} \csc \theta = \sin \theta$

in other words $\frac{1}{4} = \sin^2 \theta \quad \sin \theta = \frac{1}{2}$

in $0 \leq \theta \leq \pi$ so



so (i) $\int_{\theta=0}^{\theta=\pi/6} \int_{r=0}^{r=\sin(\theta)} r \, dr \, d\theta$

(ii) $\int_{\theta=\pi/6}^{\theta=5\pi/6} \int_{r=0}^{r=\frac{1}{4} \csc \theta} r \, dr \, d\theta$

(iii) $\int_{\theta=5\pi/6}^{\theta=\pi} \int_{r=0}^{r=\sin(\theta)} r \, dr \, d\theta$

(i) $= \frac{1}{48} (2\pi - 3\sqrt{3})$

(ii) $= \sqrt{3}/16$

(iii) $= \frac{1}{48} (2\pi - 3\sqrt{3})$

so $\Sigma i = \text{Area}$

$= \frac{1}{48} (4\pi - 3\sqrt{3})$

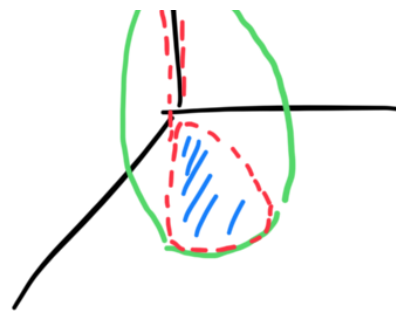
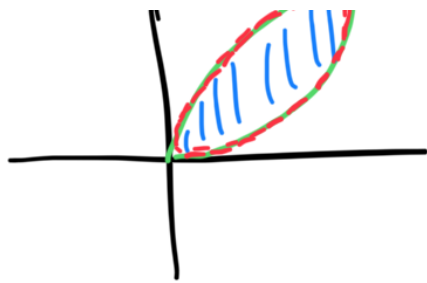
ex: Calculate volume of solid bounded by

$z = 2 - x^2 - y^2, \quad z = 0 \quad \text{and} \quad r = \sin 2\theta$

in the first quadrant.

this drawing is so bad.





$$\begin{aligned}
 V &= \iint_R z \, dA = \iint_R (2 - x^2 - y^2) (r \, dr \, d\theta) \\
 &= \int_0^{\pi/2} \int_0^{\sin 2\theta} (2 - r^2) (r \, dr \, d\theta) = \int_0^{\pi/2} \left[r^2 - \frac{1}{4} r^4 \right]_0^{\sin 2\theta} d\theta \\
 &= \int_0^{\pi/2} \underbrace{\sin^2 2\theta}_{(i)} - \frac{1}{4} \underbrace{\sin^4 2\theta}_{(ii)} d\theta
 \end{aligned}$$

$$(i). \quad \int_0^{\pi/2} \sin^2 2\theta \, d\theta = \left[\frac{\theta}{2} - \frac{1}{8} \sin(4\theta) \right]_0^{\pi/2} = \frac{\pi}{4}$$

$$\begin{aligned}
 (ii). \quad \int_0^{\pi/2} \sin^4 2\theta \, d\theta &= \int_0^{\pi/2} \sin^2 2\theta (1 - \cos^2 \theta) \, d\theta \\
 &= \underbrace{\int_0^{\pi/2} \sin^2 2\theta \, d\theta}_{\pi/4} - \underbrace{\int_0^{\pi/2} \sin^2 2\theta \cos^2 \theta \, d\theta}_{(\sin 2\theta \cos 2\theta)^2} \\
 &= \left(\frac{1}{2} \sin 4\theta \right)^2 \\
 \int_0^{\pi/2} \sin^2 4\theta \, d\theta &= \frac{3\pi}{16}
 \end{aligned}$$

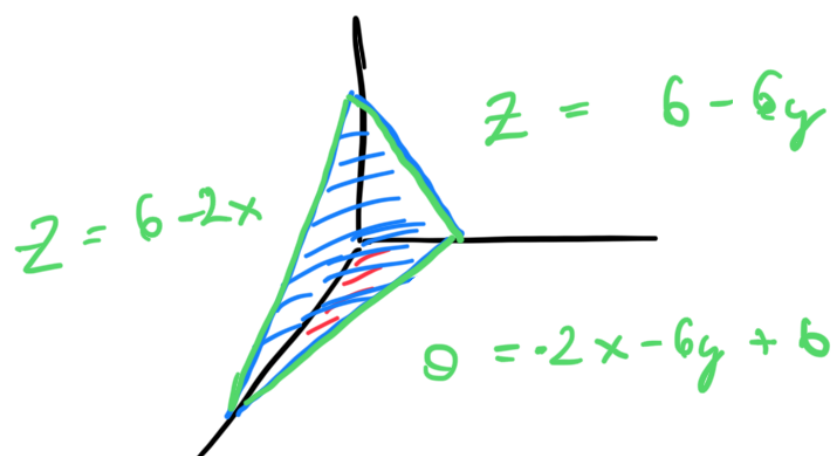
So total is

$$\frac{\pi}{4} + \left(\frac{\pi}{4} - \frac{1}{4} \left(\frac{3\pi}{16} \right) \right) = \frac{29\pi}{64}$$

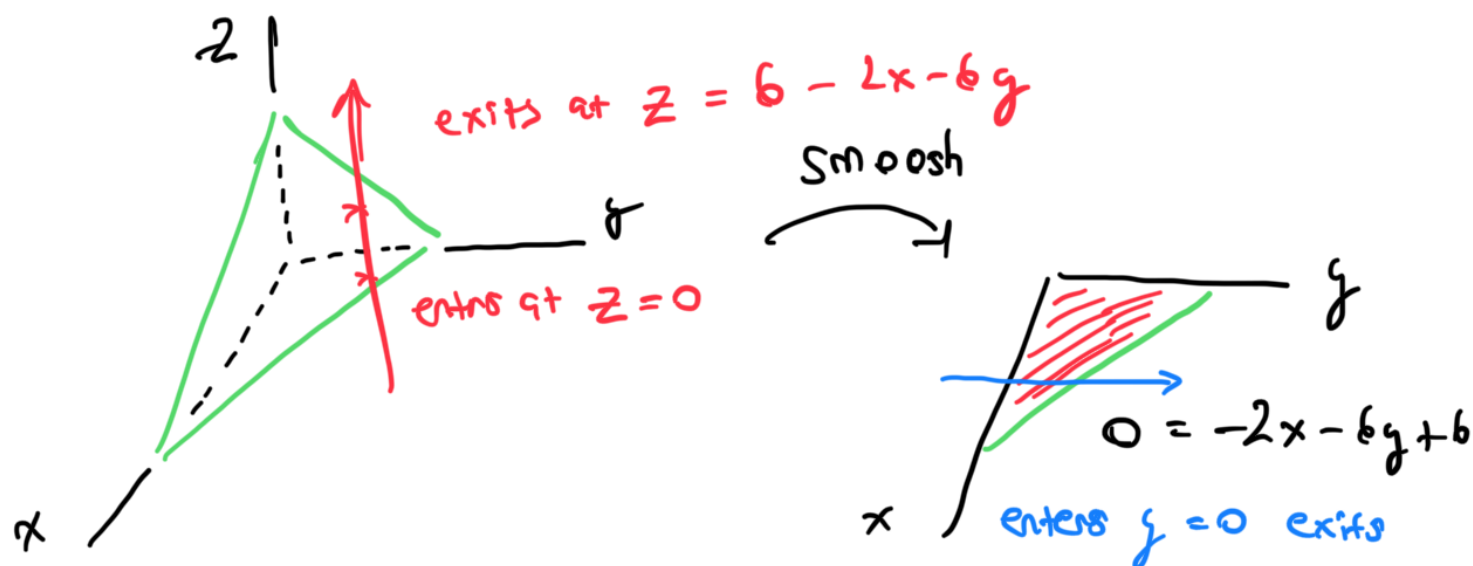
15.5: Triple Integrals in Rectangular Coordinates

Why stop at 2 variables? Why not integrate functions over space? Well that's triple integrals.

ex: Calculate the volume of the tetrahedron bounded by the 1st octant and the plane $z = -2x - 6y + 6$.



One way is really similar to what we did before.



$$y = \frac{6-2x}{6} = 1 - \frac{1}{3}x$$

Smooosh again



$$\text{So... } V = \int_{x=0}^{x=3} \int_{y=0}^{y=1-\frac{1}{3}x} \int_{z=0}^{z=6-2x-6y} 1 \, dz \, dy \, dx = 3$$

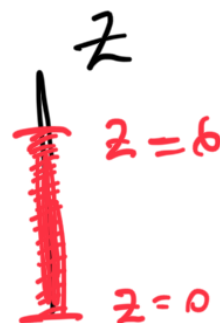
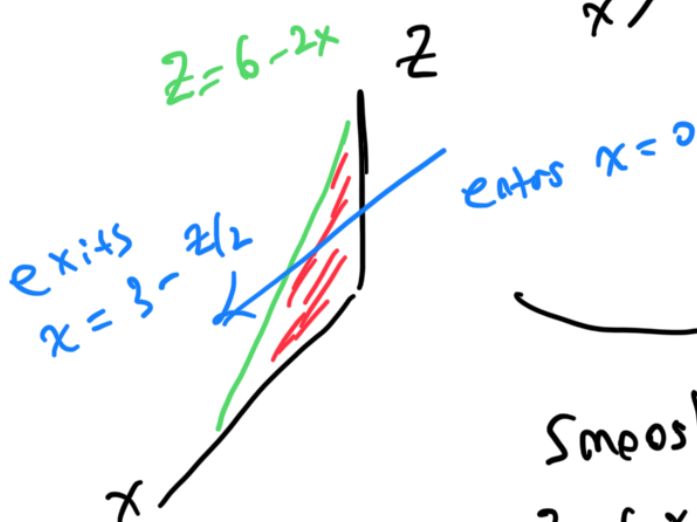
(Much easier way with cross products by the way!)

ex: Same example, but now switch order to

$$dy \, dx \, dz \quad z = 6 - 2x - 6y$$



Smooosh

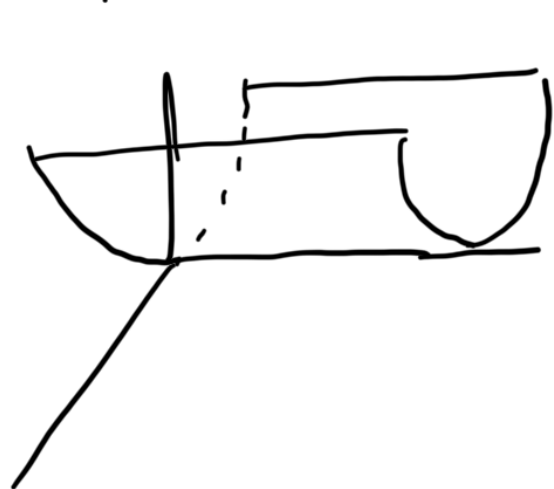


Smooosh!

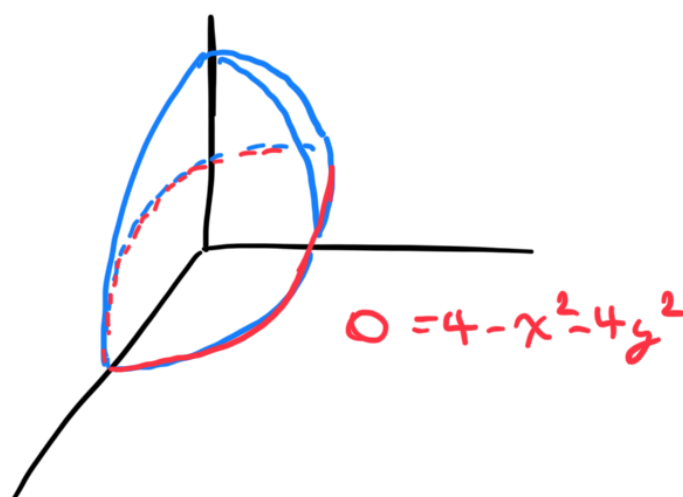
$$\text{So } V = \int_{z=0}^{z=6} \int_{x=0}^{x=3-\frac{z}{2}} \int_{y=0}^{y=1-\frac{1}{3}x-\frac{1}{6}z} 1 \, dy \, dx \, dz = 3$$

$$z = 0 \quad x = 0 \quad y = 0$$

ex: Write an integral that calculates the volume of the solid region bounded by $z = x^2$ and $z = 4 - x^2 - 4y^2$

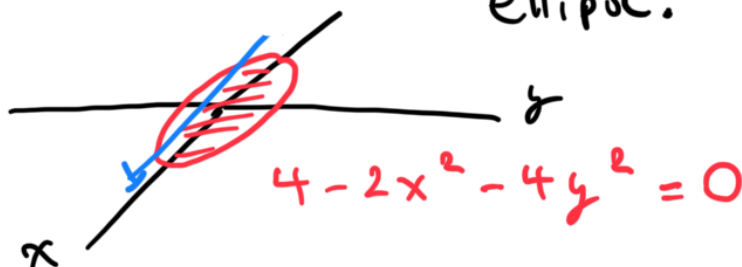


$$z = x^2$$

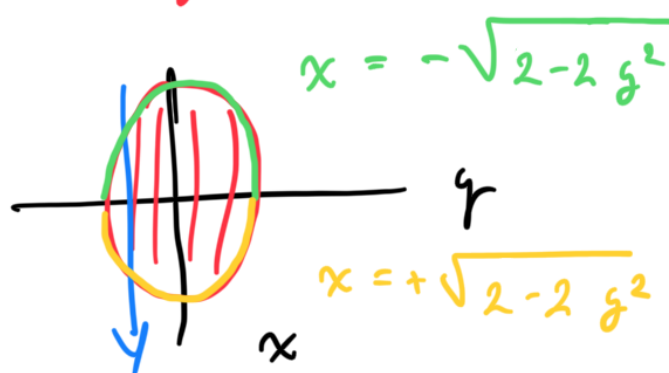


intersection is $z = x^2 = 4 - x^2 - 4y^2 = z$

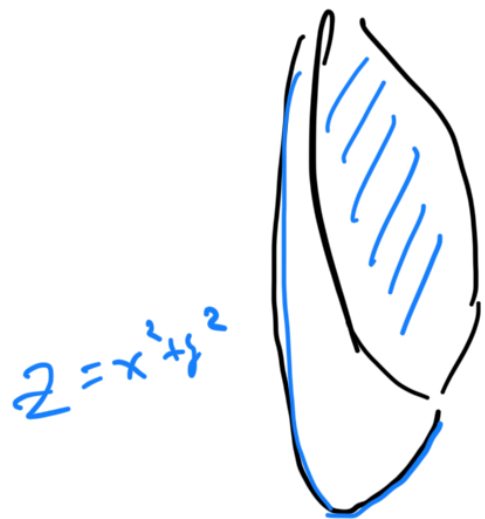
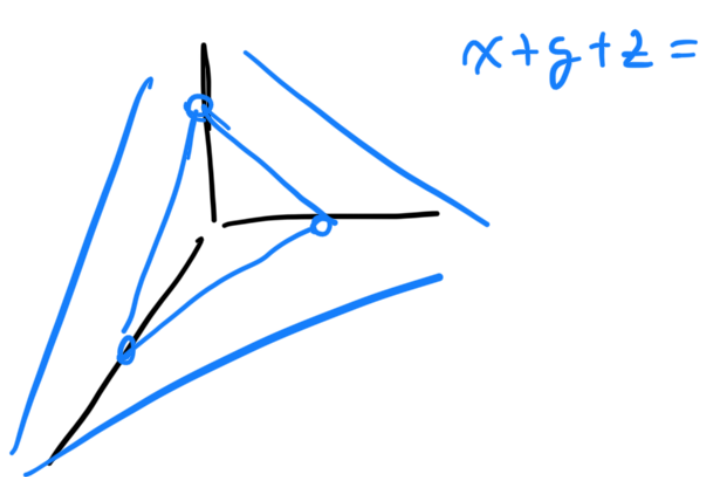
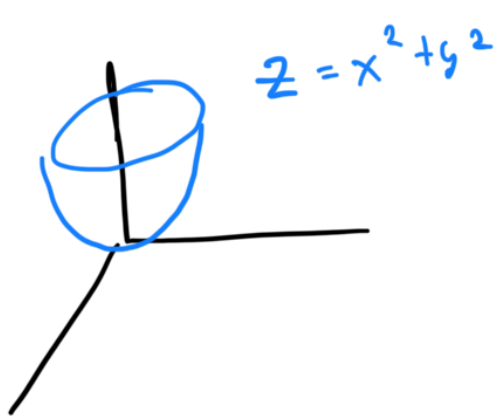
So $0 = 4 - 2x^2 - 4y^2$ which is an ellipse.



So $V = \int_{y=-1}^{y=1} \int_{x=-\sqrt{2-2y^2}}^{x=+\sqrt{2-2y^2}} \int_{z=x^2}^{z=4-2x^2-4y^2} dz dx dy$



ex: Find average value of function $f(x, y, z) = x^2 + y^2$ on the solid region bounded by the plane $x + y + z = 1$ and the parabola $z = x^2 + y^2$.



$$x + y + z = 1$$

So average value just like

before

$$\text{Avg}(f, \text{Solid } S) = \frac{\iiint_S f \, dV}{\iiint_S dV}$$

$$= \frac{\iiint_S f \, dV}{\text{Volume of } S} \quad \begin{matrix} (i) \\ (ii) \end{matrix}$$

(i).

$$x + y + z = 1 \text{ and } z = x^2 + y^2$$

$$x + y + x^2 + y^2 = 1$$

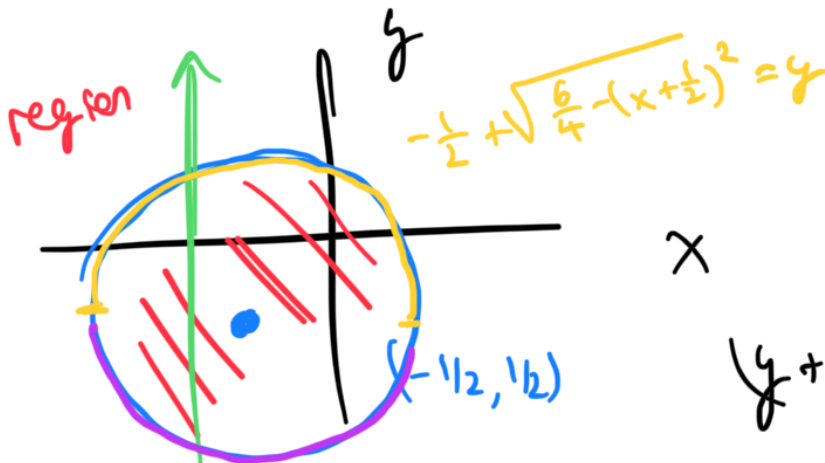
$$(x^2 + x) + (y^2 + y) = 1$$

Circle centred at $(-1/2, -1/2)$

$$\left(x + \frac{1}{2}\right)^2 + \left(y + \frac{1}{2}\right)^2 = 1 + \frac{1}{4} + \frac{1}{4}$$

$$= 6/4 \text{ radius } \frac{\sqrt{6}}{2}$$

So



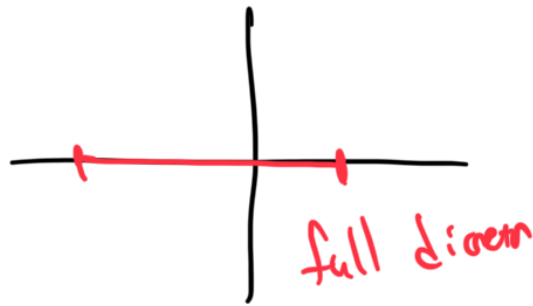
$$y = -\frac{1}{2} - \sqrt{\frac{6}{4} - \left(x + \frac{1}{2}\right)^2}$$

x

$$\left(y + \frac{1}{2}\right)^2 = \frac{6}{4} - \left(x + \frac{1}{2}\right)^2$$

$$y = -\frac{1}{2} \pm \sqrt{\frac{6}{4} - \left(x + \frac{1}{2}\right)^2}$$

Smooosh



$$\text{Solve } y = -\frac{1}{2} \pm \sqrt{\frac{6}{4} - (x + \frac{1}{2})^2} = -\frac{1}{2}$$

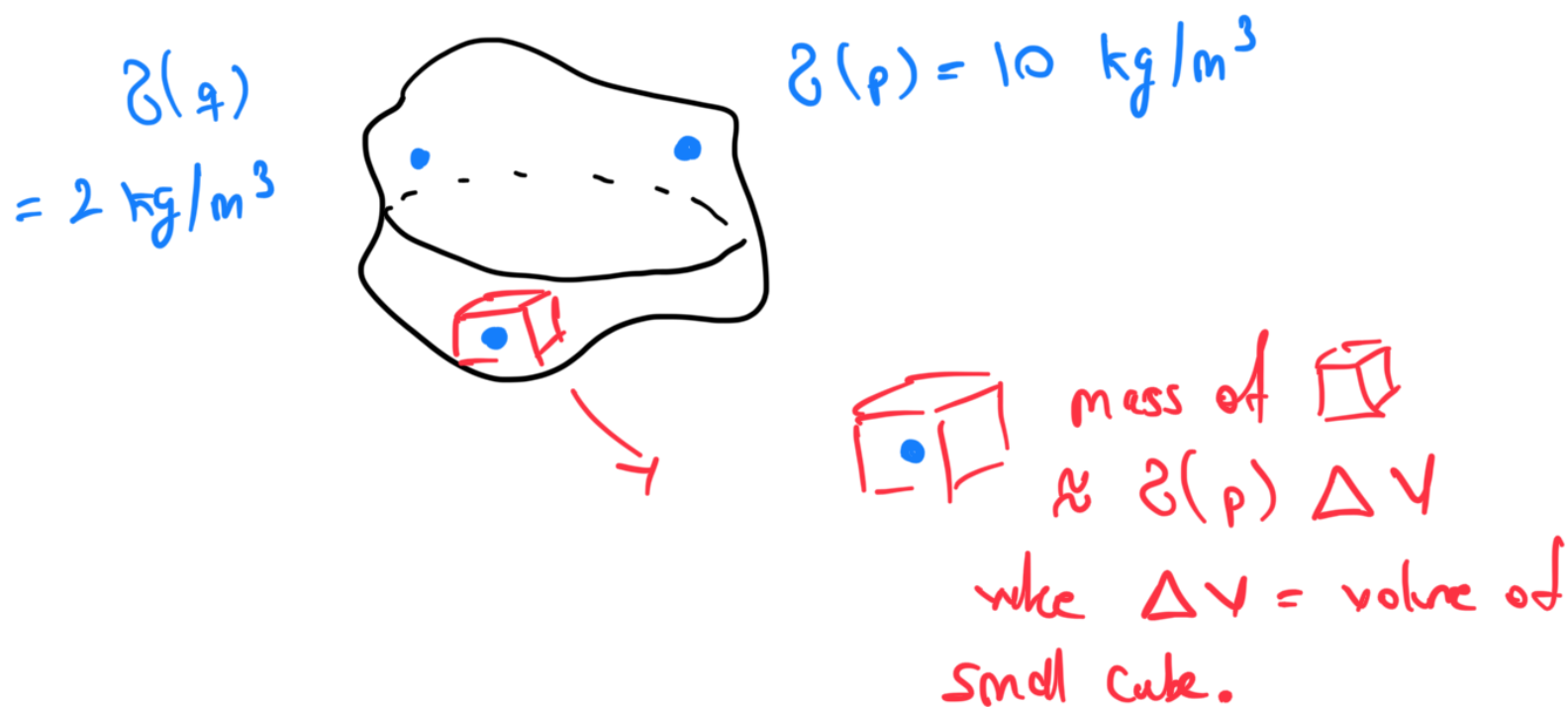
$$\text{So } x = \frac{1}{2}(-1 \pm \sqrt{6})$$

$$\text{So (i)} = \int_{x = \frac{1}{2}(-1 - \sqrt{6})}^{x = \frac{1}{2}(-1 + \sqrt{6})} \int_{y = -\frac{1}{2} - \sqrt{\frac{6}{4} - (x + \frac{1}{2})^2}}^{y = -\frac{1}{2} + \sqrt{\frac{6}{4} - (x + \frac{1}{2})^2}} \int_{z = 1-x-y}^{z = x^2+y^2} (x^2 + y^2) dz dy dx$$

(ii). Replace integrand above $x^2 + y^2$ with 1 to get volume. Do not evaluate.

15.6: Mass and Moments of Inertia

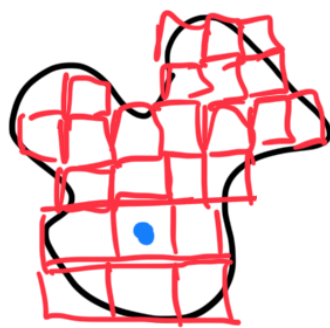
Let's say have a solid body whose density modeled by $\rho(x, y, z)$



$$\text{So Mass} \approx \sum_{\text{cubes}} \rho(p_i) \Delta V_i \xrightarrow{\text{limit}} \iiint_B \rho(p) dV$$

where B is the body in question.

Similar picture in 2D



$$\text{Mass} \approx \sum_{\text{squares}} \rho(p_i) \Delta A_i$$

$$\boxed{\bullet} = \rho(p) \Delta A$$

$$\text{in limit Mass} = \iint_R \rho(p) dA$$

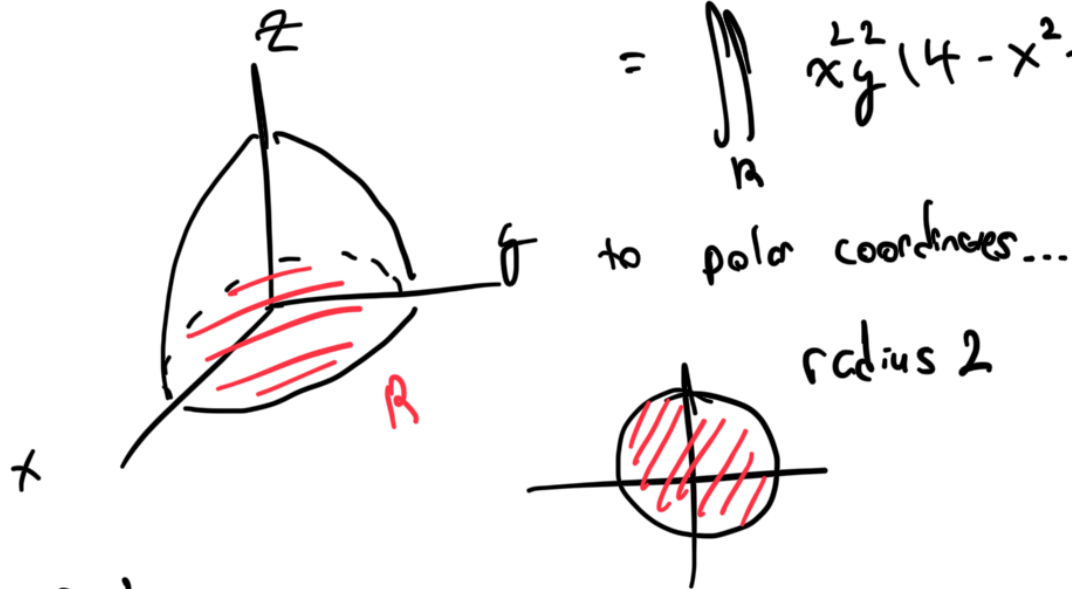
ex: Calculate mass of body B

$$\text{bounded by } z = 4 - x^2 - y^2 \text{ and } z = 0$$

Subject to density function $\rho(x, y, z) = x^2 y^2$

$$M = \iiint_B \rho(\rho) dV = \iiint_{\substack{A \\ z=0}}^{z=4-x^2-y^2} x^2 y^2 dz dA$$

$$= \iint_A x^2 y^2 (4 - x^2 - y^2) dA$$



$$\text{So } M = \int_{\theta=0}^{\theta=2\pi} \int_{r=0}^{r=2} (r \cos \theta)^2 (r \sin \theta)^2 (4 - r^2) \underbrace{r dr d\theta}_{dA}$$

$$= \int_0^{2\pi} \int_0^2 \cos^2 \theta \sin^2 \theta (r^5) (4 - r^2) dr d\theta$$

$$= \left(\int_0^2 r^5 (4 - r^2) dr \right) \left(\int_0^{2\pi} \cos^2 \theta \sin^2 \theta d\theta \right)$$

$$= \left(\int_0^2 4r^5 - r^7 dr \right) \left(\frac{1}{4} \int_0^{2\pi} \sin^2 2\theta d\theta \right)$$

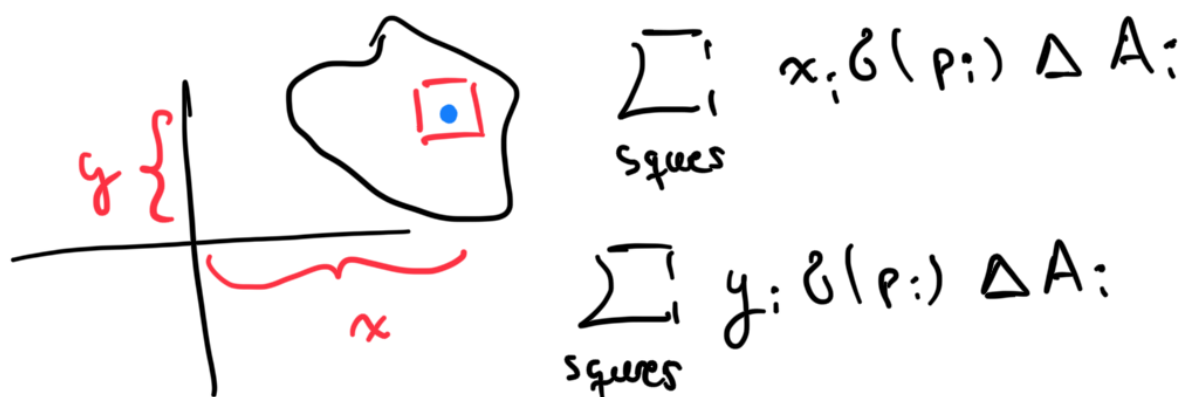
$$= \left(\frac{4}{6} r^6 - \frac{1}{8} r^8 \Big|_0^2 \right) \left(\frac{1}{24} \int_0^{2\pi} \left(\frac{1}{2} (1 - \cos 2\theta) \right) d\theta \right)$$

$$= \left(\frac{4}{6} \cdot 48 - \frac{1}{8} 128 \right) \left(\frac{1}{8} \right) (2\pi) = \left(\frac{32}{3} \right) \left(\frac{1}{8} \right) (2\pi)$$

$$= \frac{8}{3} \pi$$

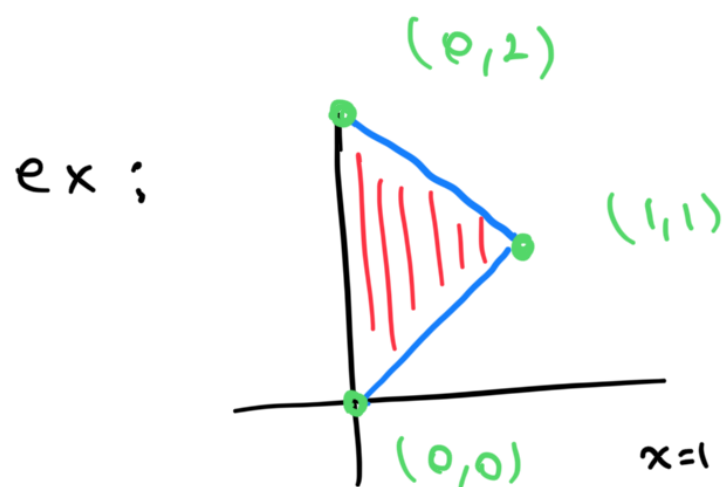
Center of Mass :

Integral that takes into account distance
and mass relative to an origin.



in limit converge to $M_y = \iint_R x \rho(p) dA$

$$M_x = \iint_R y \rho(p) dA$$



$$\rho(x,y) = x^2 y$$

$$M_y = \iint_R x \rho(x,y) dA$$

$$= \int_{x=0}^1 \int_{y=x}^{y=2-x} x (x^2 y) dy dx$$

$$= \int_0^1 x^3 \int_{y=x}^{y=2-x} y dy dx = \frac{1}{2} \int_0^1 x^3 [(2-x)^2 - x^2] dx$$

$$= \frac{1}{2} \left(\frac{1}{5} \right) = \frac{1}{10}$$

Similarly, $M_x = \iint_R y (x^2 y) dy dx$

$$= \int_0^1 \int_{y=x}^{y=2-x} y^2 x^2 dy dx = \int_0^1 x^2 \left[\frac{y^3}{3} \right]_{y=x}^{y=2-x} dx$$

$$\int_0^1 \int_x^1 x^2 y^2 dy dx = \frac{1}{3} \int_0^1 x^2 (2-x) dx = \frac{1}{3} \int_0^1 (2x^2 - x^3) dx$$

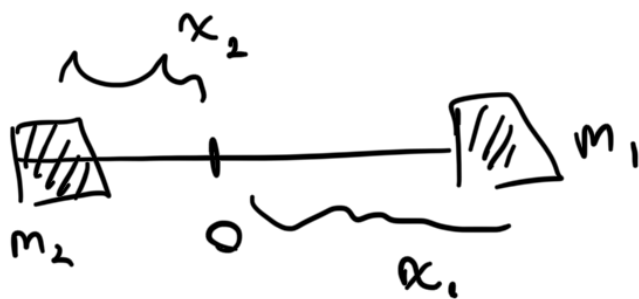
$$= \left(\frac{1}{3}\right) \left(\frac{8}{15}\right) = \frac{8}{45}$$

Center of mass is where if you balance the object, it will remain still, under ideal circumstances.

$$\bar{x} = M_y / M \quad \bar{y} = M_x / M$$

Can think of M_x, M_y as average of weighted mass-distances.

Called moments of mass.



$$\bar{x} = \frac{x_1 m_1 + x_2 m_2}{m_1 + m_2}$$

ex: Above example, we only need $M = \int_0^1 \int_x^1 x^2 y^2 dy dx$

$$= \frac{1}{2} \int_0^1 x^2 (2-x)^2 - x^2 dx = \left(\frac{1}{2}\right) \left(\frac{1}{3}\right) = \frac{1}{6}$$

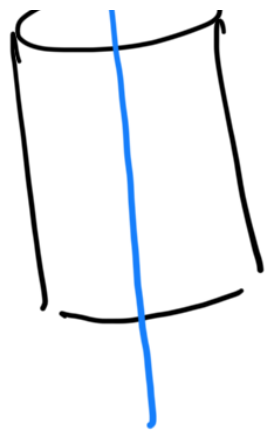
so center of mass is at $\left(\frac{M_y}{M}, \frac{M_x}{M}\right)$

$$(\bar{x}, \bar{y}) = \left(\frac{1/10}{1/6}, \frac{8/45}{1/6}\right) = \left(\frac{2}{5}, \frac{16}{15}\right)$$

Moment of inertia:



Consider a spinning mass about a



line, e.g., z -axis. Assume body spinning constant rotational speed ω .
 then for a mass spinning r -away from line, we have



$$KE = \frac{1}{2} m v^2, \quad \omega = \text{rotational velocity}$$

$$\omega r = v$$

$$\text{so } KE \text{ of small mass} = \frac{1}{2} m (\omega r)^2$$

$$\text{Summing total energy } \sum \frac{1}{2} m_i (\omega r_i)^2$$

$$\approx \sum \frac{1}{2} \rho(r_i) r_i^2 \omega^2 dV$$

$$\text{we get } KE = \frac{1}{2} \iiint_B \rho r^2 \omega^2 dV$$

$$= \frac{1}{2} \omega^2 \iiint_B (x^2 + y^2) \rho(r) dV$$

$$v = r \omega$$

$$\frac{ds}{dt} = \frac{d}{dt}(r \theta)$$

$$= r \frac{d\theta}{dt} = r \omega$$

$$\text{so } KE = \frac{1}{2} \omega^2 I_z$$

moment of inertia
 $I_z =$ about line L , in our case z

You can think of I_z as mass. I takes

$\frac{1}{2} m v^2$ energy to get a body m in motion.

I takes $\frac{1}{2} \omega^2 I_z$ to get something to spin

about z -axis at angular velocity ω .

$$\text{Similarly... } T = \iiint_B \rho r^2 \omega^2 dV$$

$$I_x = \iiint_B (y^2 + z^2) \rho \, dV$$

$$I_y = \iiint_B (x^2 + z^2) \rho \, dV$$

In 2 dimensions ...

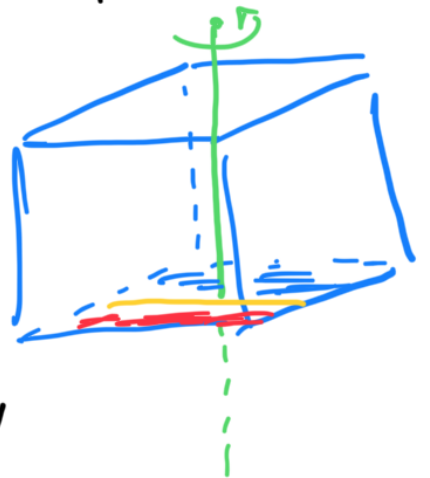
$$I_x = \iint_R y^2 \rho \, dA \quad I_y = \iint_R x^2 \rho \, dA$$

$$I_o = \iint_R (x^2 + y^2) \rho \, dA$$

Now in this context, object spinning around a point $(0,0)$ so $KE = \frac{1}{2} \omega^2 I_o$

ex: Calculate moment of inertia of a cube with vertices at $(\pm 1, \pm 1, 0)$ and $(\pm 1, \pm 1, 1)$ with density $\rho(x, y, z) = |xz|$.

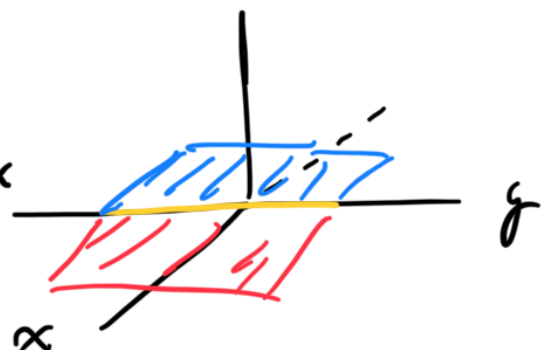
$$I_z = \iiint_B (x^2 + y^2) \rho \, dV$$



$$= \iiint_{B \text{ with } x \leq 0} (x^2 + y^2) \rho \, dV + \iiint_{B \text{ with } x \geq 0} (x^2 + y^2) \rho \, dV$$

$$= \int_{x=-1}^{x=0} \int_{y=-1}^{y=+1} \int_{z=0}^{z=1} (x^2 + y^2) (-xz) \, dz \, dy \, dx$$

(i)



$$+ \int_{x=0}^{x=1} \int_{y=-1}^{y=+1} \int_{z=0}^{z=1} (x^2 + y^2) (xz) dz dy dx \quad (\text{ii})$$

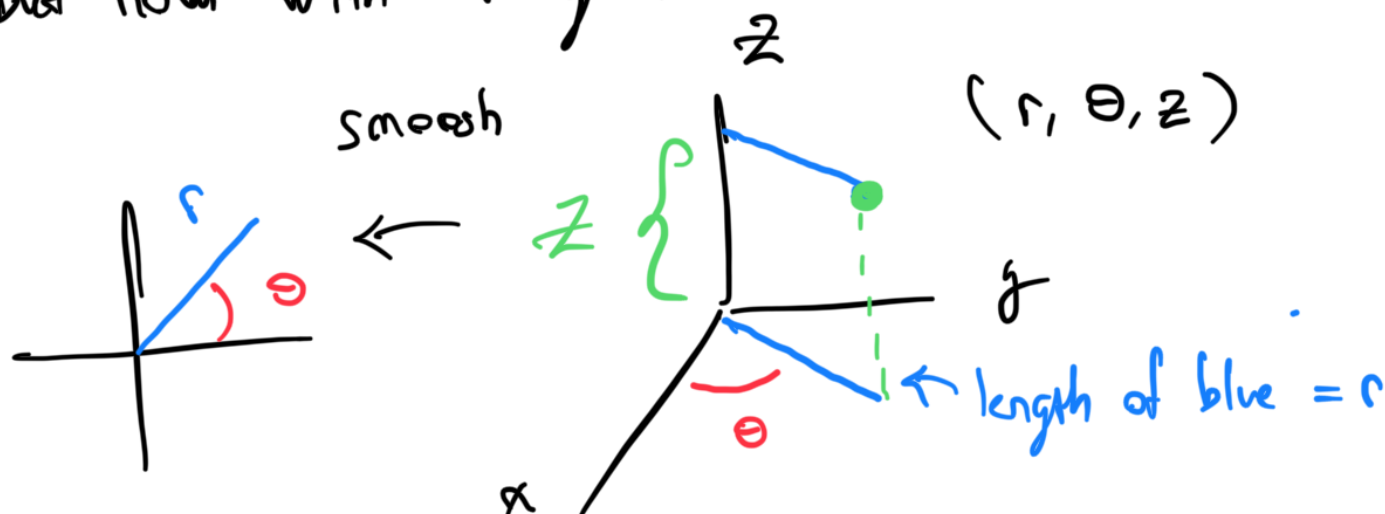
$$(i). \int_{-1}^0 \int_{-1}^1 \frac{1}{2} (x^2 + y^2) (-x) dy dx \quad (ii). \quad 5/12$$

$$= \int_{-1}^0 \int_{-1}^1 \frac{1}{2} (-x^3 - y^2 x) dy dx$$

$$= \int_{-1}^0 \left(-x^3 - \frac{x}{3} \right) dx = 5/12 \quad \text{so } I_z = 10/12 = 5/6$$

15.7 : Integrals in Spherical and Cylindrical coordinates

Cylindrical coordinates: A point P in $\mathbb{R}^3$ is determined by (r, θ, z) . Just polar coordinates but now with height.



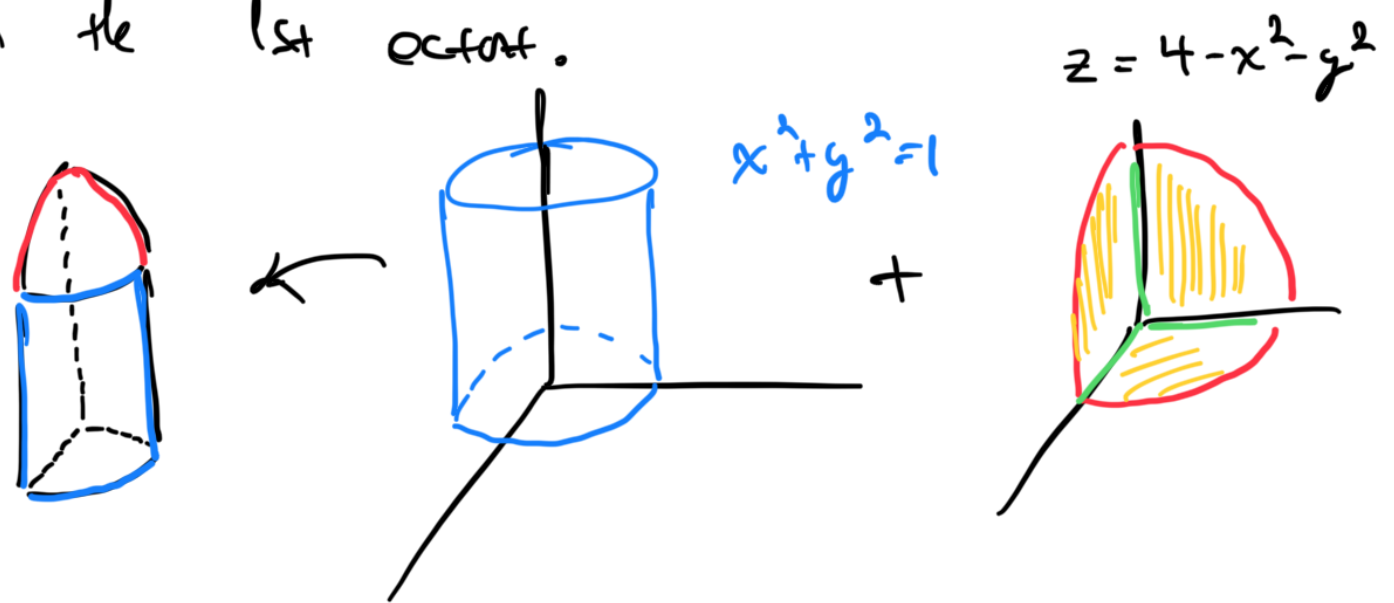
You can equate cartesian and cylindrical like before.

$$x = r \cos \theta \quad y = r \sin \theta \quad z = z$$

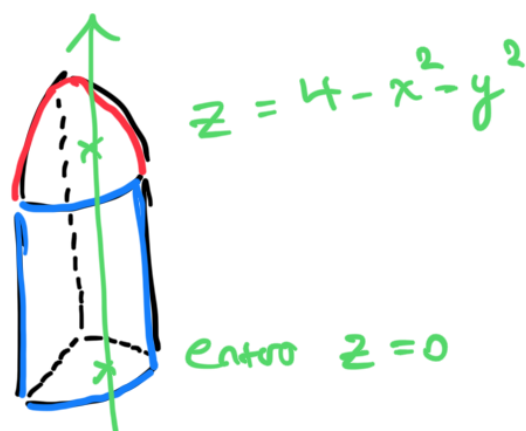
$$r^2 = x^2 + y^2 \quad \tan \theta = y/x \quad (\text{when defined})$$

Why use them? Well good for problems where you have an axis of symmetry.

ex: Calculate volume bounded by surfaces $x^2 + y^2 = 1$ and $z = 4 - x^2 - y^2$, in the 1st octant.



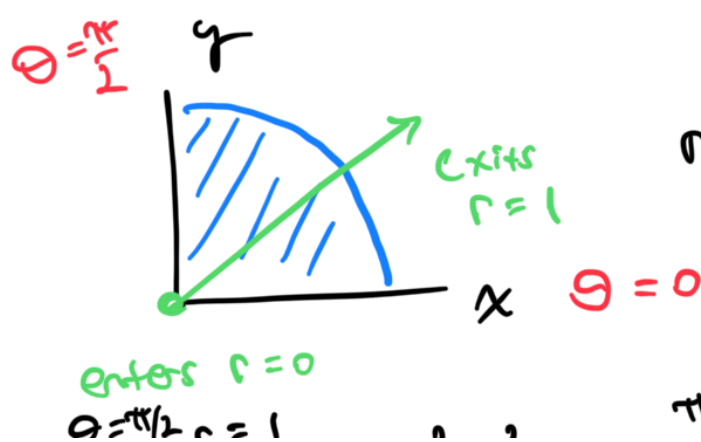
Find z -limits



smoosh



now do polar.



$$\pi/2, 4 - r^2$$

$$V = \iiint_{\substack{z=4-x^2-y^2 \\ z=0 \\ \theta=0, r=0}} dV = \iiint_0^1 r dz dr d\theta$$

$$dV = r dz dr d\theta //$$

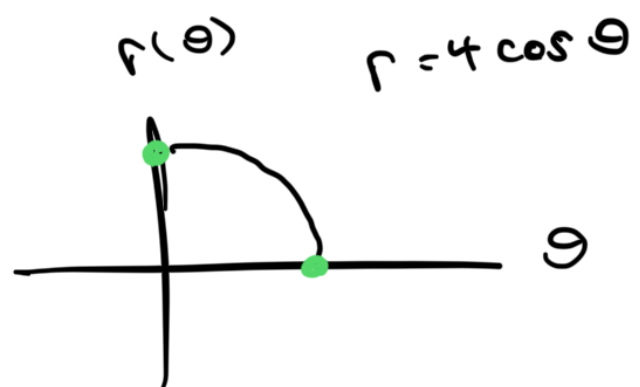
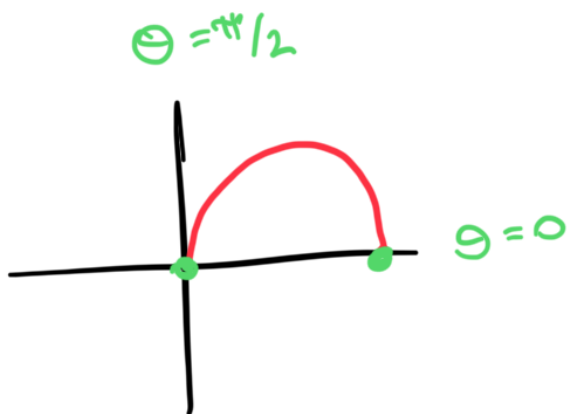
$$= \int_0^{\pi/2} \int_0^1 r(4-r^2) dr d\theta$$

$$= \int_0^{\pi/2} \left(2r^2 - \frac{1}{4}r^4 \right) \Big|_0^1 d\theta$$

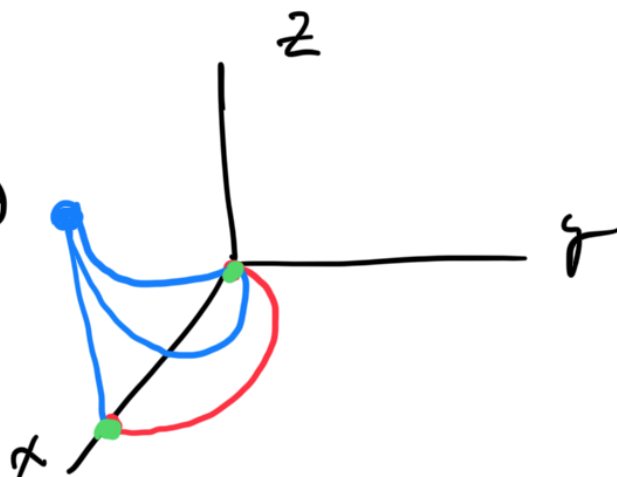
$$= \int_0^{\pi/2} \frac{7}{4} d\theta = \frac{7\pi}{8}$$

ex: 15.7.11 Calculate volume

$$0 \leq r \leq 4 \cos \theta, \quad \theta \leq \theta \leq \pi/2, \quad \theta \leq z \leq r^2$$



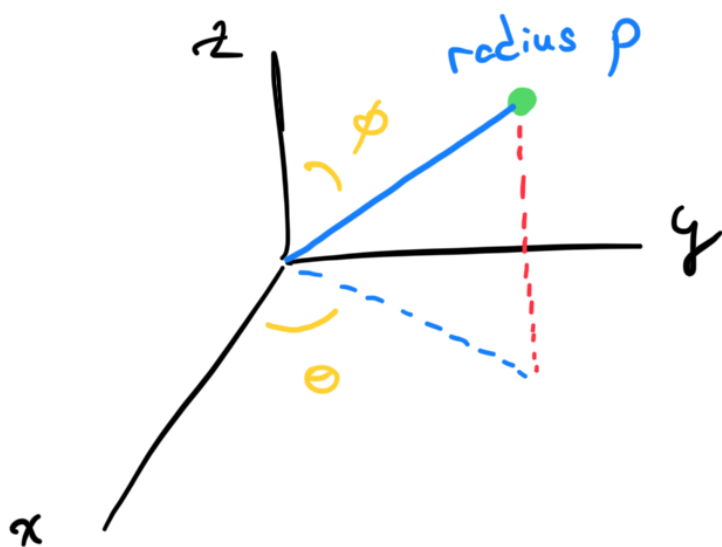
$$V = \int_{\theta=0}^{\pi/2} \int_{r=0}^{4 \cos \theta} \int_{z=0}^{r^2} r dz dr d\theta$$



$$V = \int_0^{\pi/2} \int_0^{4 \cos \theta} r^3 dr d\theta = \int_0^{\pi/2} \frac{1}{4} (4 \cos \theta)^4 d\theta$$

$$= (1/4)(48\pi) = 12\pi$$

Spherical coordinates



$P = (\rho, \phi, \theta)$
 or (ρ, θ, ϕ) depending
 on choice. Book uses
 (ρ, ϕ, θ)

Again have ways of going back and forth
 between Cartesian and spherical,

$$x = \rho \sin \phi \cos \theta$$

$$y = \rho \sin \phi \sin \theta$$

$$z = \rho \cos \phi$$

$$\rho^2 = x^2 + y^2 + z^2$$

Can also relate cylindrical and spherical

$$r = \rho \sin \phi$$

$$z = \rho \cos \phi$$

$$\theta = \theta$$

$$\rho^2 = r^2 + z^2$$

Why spherical coordinates? Use when you have a
 point of symmetry.

ex: Calculate volume of body bounded by
by sphere of radius 2 centered at origin

and the cone $x^2 + y^2 = z^2$

and $z \geq 0$.

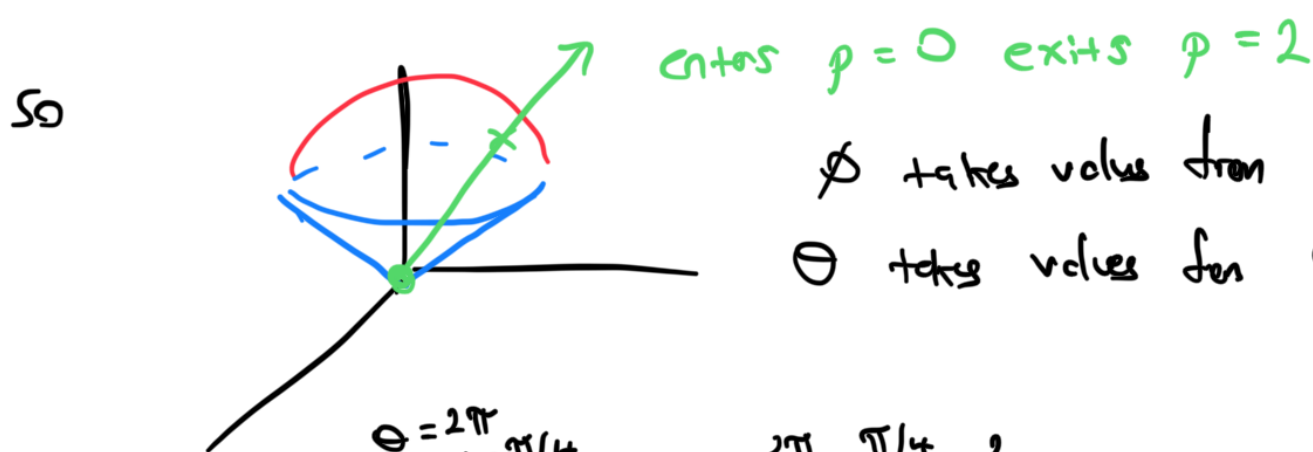
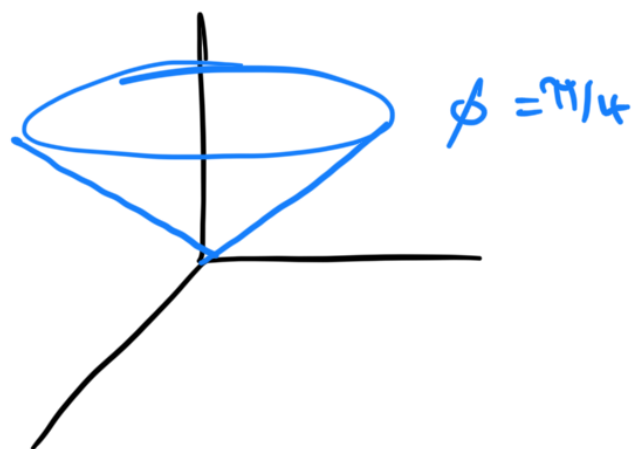
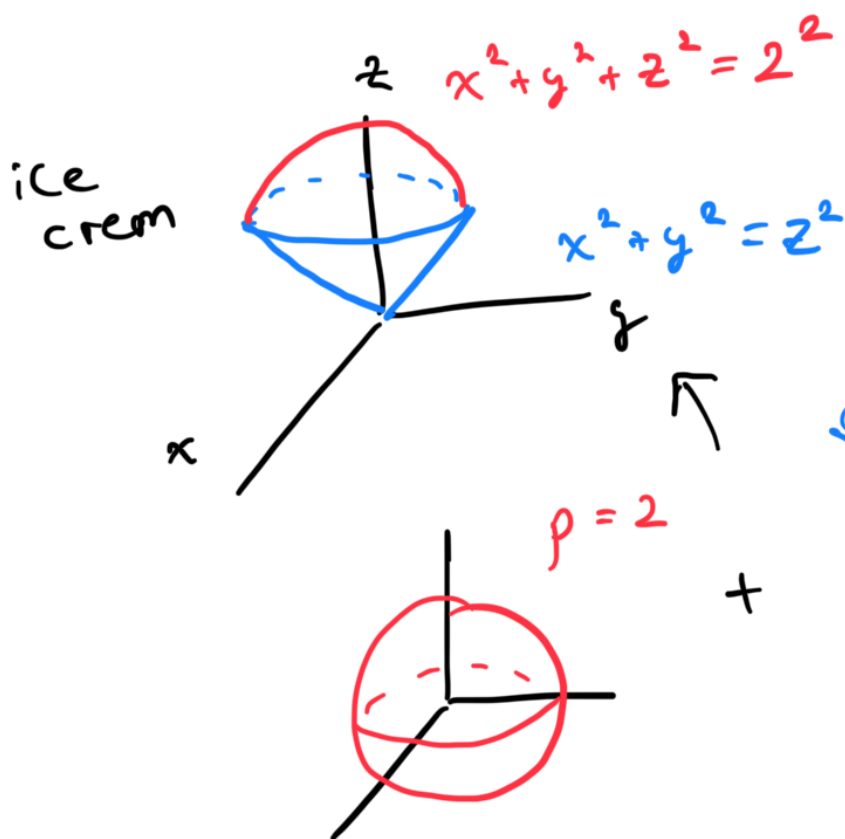
$$r^2 = z^2$$

$$\rho^2 \sin^2 \phi = \rho^2 \cos^2 \phi$$

$$\sin^2 \phi = \cos^2 \phi$$

$$\sin \phi = \cos \phi$$

$$\phi = \pi/4$$



ϕ takes values from 0 to $\pi/4$

θ takes values from 0 to 2π

So

$$V = \int_{\theta=0}^{2\pi} \int_{\phi=0}^{\pi/4} \int_{\rho=0}^2 dV = \int_0^{2\pi} \int_0^{\pi/4} \int_0^2 \rho^2 \sin \phi \, d\rho \, d\phi \, d\theta$$

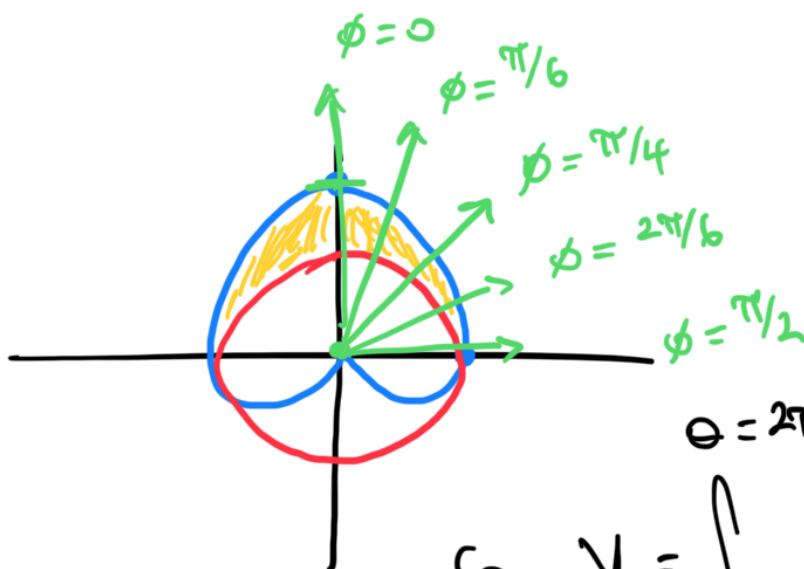
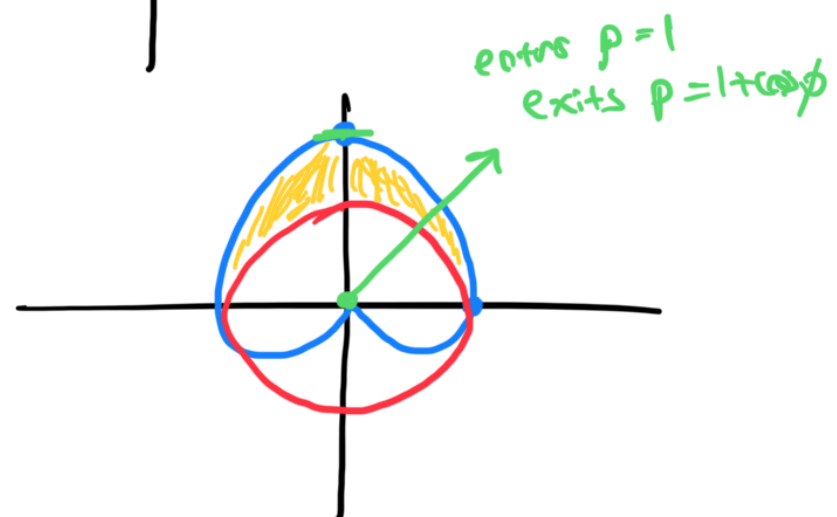
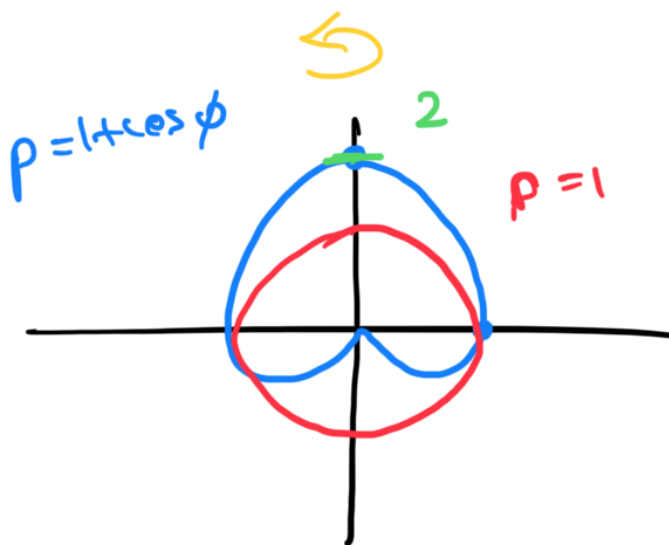
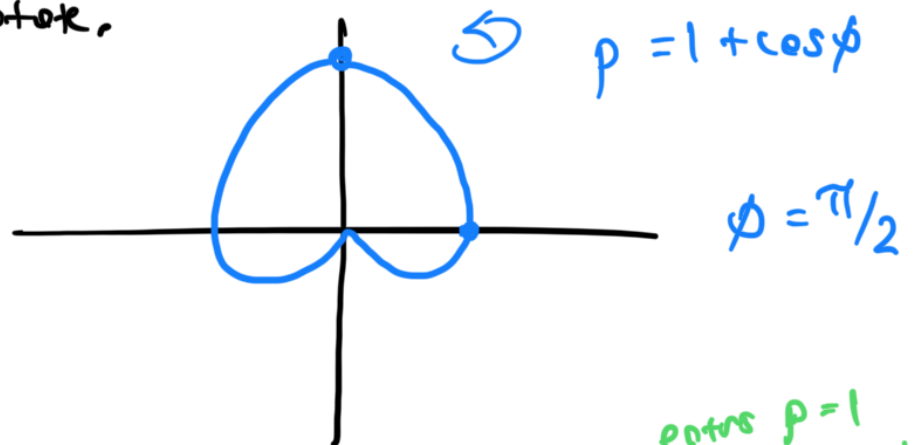
$$= \int_0^{2\pi} \int_0^{\pi/4} \frac{8}{3} \sin \phi \, d\phi \, d\theta$$

$$= \frac{8}{3} (1 - \sqrt{2}/2) (2\pi) = \frac{16\pi}{3} (1 - \sqrt{2}/2)$$

15.7.56. Find volume of solid bounded below hemisphere $\rho = 1$, $z \geq 0$, and above $\rho = 1 + \cos \phi$

First, what does $\rho = 1 + \cos \phi$ look like?

Well first it has Θ -symmetry. So draw
in a plane, then rotate.



So
$$V = \int_{\Theta=0}^{2\pi} \int_{\phi=0}^{\pi/2} \int_{\rho=1}^{1+\cos\phi} \underbrace{dV}_{\rho^2 \sin\phi \, d\rho \, d\phi \, d\Theta}$$

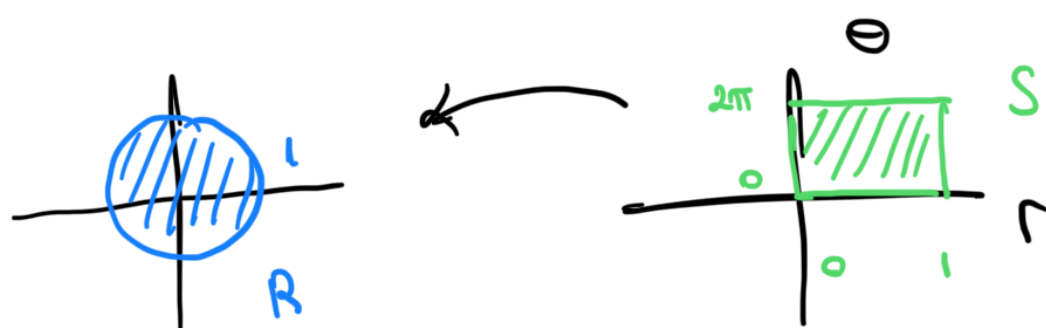
$$= 11\pi/6 \text{ (according to Mathematica)}$$

15.8: Substitution in Multiple Integrals

When you change from one coordinate system to another, the dA or dV changes too.

You can see this in the following

$$dA = dx dy = r dr d\theta$$



$$\begin{aligned} \text{so when } \iint_R f(x, y) dx dy &= \iint_S f(x(r, \theta), y(r, \theta)) r dr d\theta \\ &= \iint_S f(r \cos \theta, r \sin \theta) \underset{\substack{\uparrow \\ 2 \\ 0}}{r} dr d\theta \quad \text{called the Jacobian} \end{aligned}$$

More generally...

theorem: let S be in (u, v) -coordinates

and say $x = g(u, v)$ $y = h(u, v)$ for

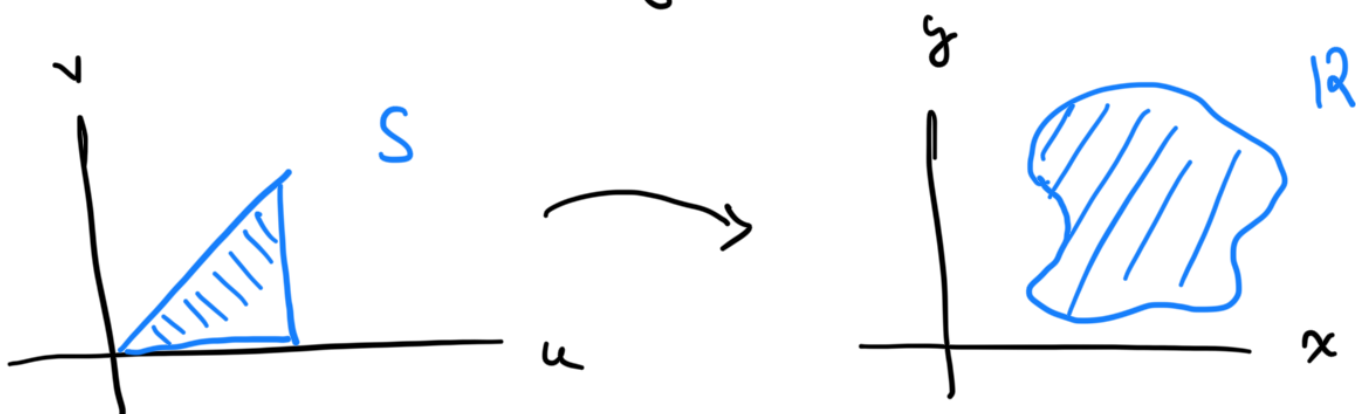
some functions g, h so that

$$J(u, v) = \begin{vmatrix} \frac{dx}{du} & \frac{dx}{dv} \\ \frac{dy}{du} & \frac{dy}{dv} \end{vmatrix} = \frac{dx}{du} \frac{dy}{dv} - \frac{dx}{dv} \frac{dy}{du} \neq 0 \quad \text{on } S$$

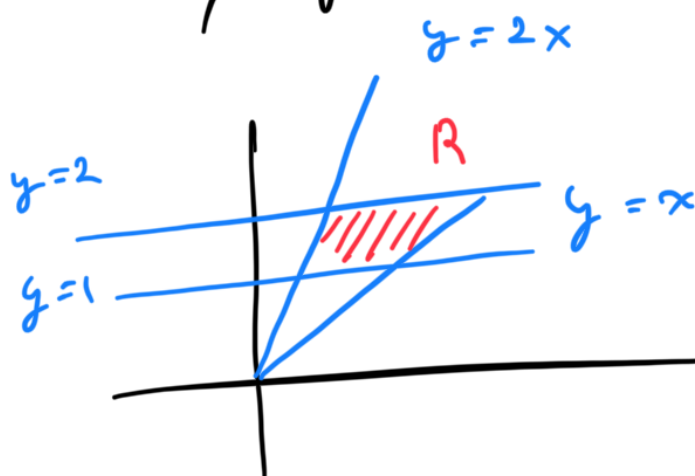
then

let R denote image of S under (g, h) .

$$\iint_R f(x, y) dx dy = \iint_S f(g(u, v), h(u, v)) |J(u, v)| du dv$$



ex: Calculate integral of $\frac{x}{y} + \frac{y}{x}$
over region bounded by $y = 2x$, $y = x$
 $y = 1$ and $y = 2$



$$u = \frac{y}{x} \quad v = y$$

then solve for x and y .

$$y = v \quad \text{so} \quad x = \frac{y}{u} = \frac{v}{u}$$

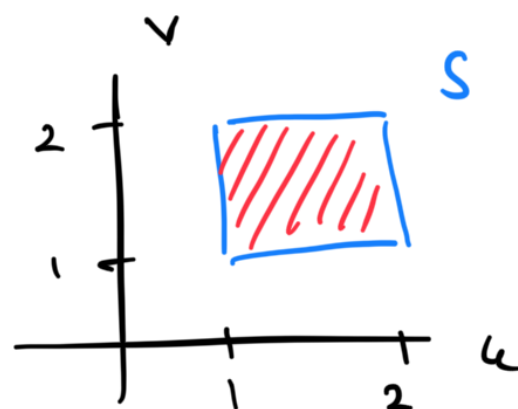
What is the region?

$$(i). \quad y = 1 \sim v = 1$$

$$(ii). \quad y = 2 \sim v = 2$$

$$(iii). \quad y = x \sim \frac{y}{x} = 1 \sim u = 1$$

$$(iv). \quad y = 2x \sim \frac{y}{x} = 2 \sim u = 2$$



Jacobian:

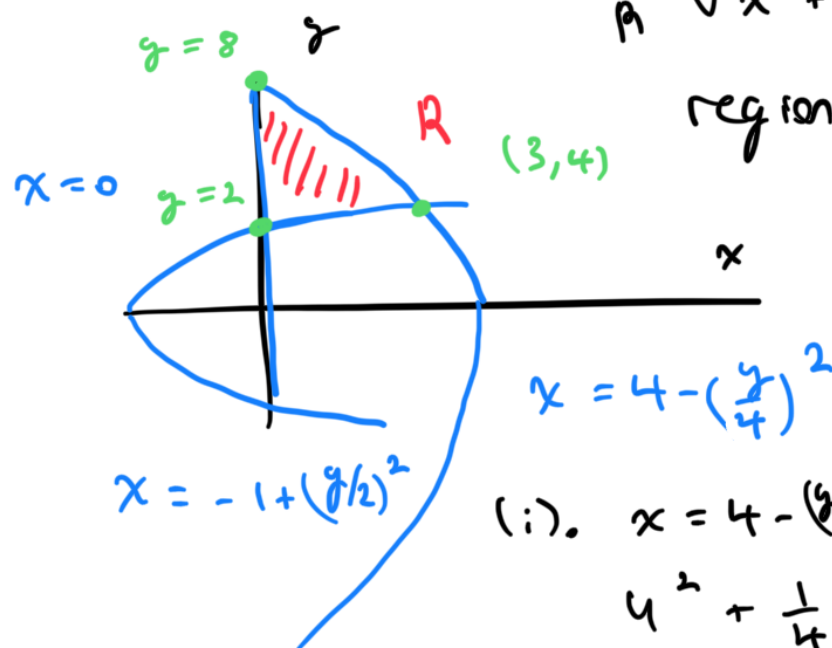
$$\begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \begin{vmatrix} -v/u^2 & 1/u \\ 0 & 1 \end{vmatrix} = -v/u^2$$

$$\left| \frac{\partial u}{\partial x} \frac{\partial y}{\partial x} \right|$$

$$\begin{aligned} \text{So } \iint_R \frac{x}{y} + \frac{y}{x} dA &= \iint_S \left(v + \frac{1}{v} \right) \left| \frac{-v}{u^2} \right| dA' \\ &= \int_1^2 \int_1^2 \left(v + \frac{1}{v} \right) \frac{v}{u^2} du dv = \int_1^2 \int_1^2 \frac{(v^2 + 1)v}{u^2} du dv \\ &= 2^{3/2} \text{ (according to Mathematica)} \end{aligned}$$

(do this ex last!)

ex: Integrate $\iint_R \frac{1}{\sqrt{x^2 + y^2}} dA$ where R



region bounded by $x = 4 - (y/4)^2$

$x = (y/2)^2 - 1$ and $x = 0$

using $x = u^2 - v^2$ and $y = 2uv$

$$\begin{aligned} \text{(i). } x &= 4 - (y/4)^2 \sim u^2 - v^2 = 4 - \left(\frac{1}{2}uv\right)^2 \\ u^2 + \frac{1}{4}u^2v^2 - v^2 - 4 &= 0 \end{aligned}$$

$$(u^2 - 4) + v^2 \left(\frac{1}{4}u^2 - 1 \right) = 0$$

$$(u^2 - 4) \left(1 + \frac{1}{4}v^2 \right) = 0$$

so $u = -2$ or $u = 2$. because

$x \geq 0$ and $x = u^2 - v^2$, we know

$u \geq 0$, so $u = 2$ //

$$\text{(ii). } x = -1 + (y/2)^2 \sim u^2 - v^2 = -1 + (uv)^2$$

$$u^2 - u^2v^2 - v^2 + 1 = 0$$

$$u^2(1 - v^2) + (1 - v^2) = 0$$

$$(u^2+1)(1-v^2)=0 \text{ so}$$

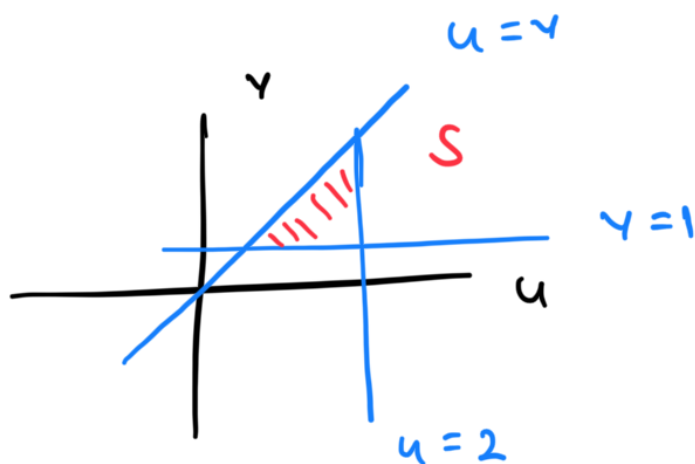
$1=v$ or $-1=v$. bc $x \geq 0$
 $u \geq 0$ like before. Also $y \geq 0$
 and $y=2uv$ so $v \geq 0$. Thus

$$v = +1 //$$

(iii). $x=0 \sim u^2-v^2=0$ so $u=v$ or $u=-v$.

bc all $y \geq 0$ need $u=v$. //

So S bounded by



$$\text{Jacobian: } J(u,v) = \begin{vmatrix} 2u & -2v \\ 2v & 2u \end{vmatrix} = 4u^2 + 4v^2$$

$$\begin{aligned} \text{Integrand: } \sqrt{x^2+y^2} &= \sqrt{(u^2-v^2)^2 + (2uv)^2} \\ &= (u^4 - 2u^2v^2 + v^4 + 4u^2v^2)^{1/2} \\ &= (u^4 + 2u^2v^2 + v^4)^{1/2} = u^2 + v^2 \end{aligned}$$

$$\text{so } I = \iint_S \left(\frac{1}{u^2+v^2} \right) (4u^2+4v^2) du dv = 4 \iint_S du dv$$

$\uparrow$ integrand $\uparrow$ Jacobian $= 4 \left(\frac{1}{2} \right) = 2$

ex: Integrate $\sqrt{1+y^3}$ over region bounded

by $y=0$, $x=2y^2$, $x=1+y^2$ using

$$x = u + v^2$$

$$y = v$$

(i). $y = 0 \sim v = 0 //$

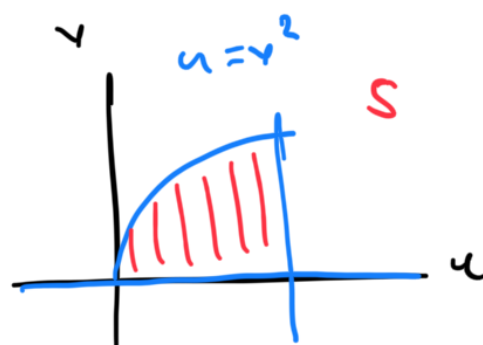
Jacobi: $J(u, v) = \begin{vmatrix} 1 & 2v \\ 0 & 1 \end{vmatrix}$

(ii). $x = 2y^2 \sim u + v^2 = 2v^2$
so $u = v^2 //$

$$= 1$$

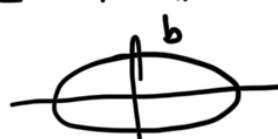
Integrand: $\sqrt{1+v^3}$

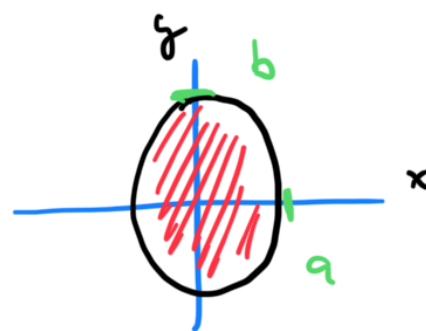
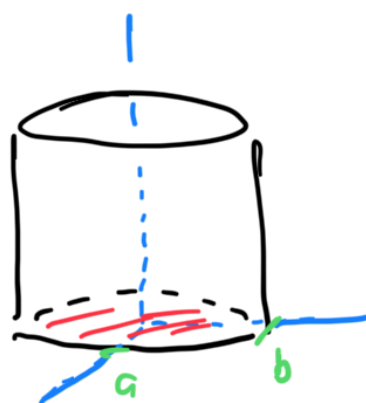
(iii). $x = 1 + y^2 \sim u + v^2 = 1 + v^2$
so $u = 1 //$



so $I = \iint_S \sqrt{1+v^3} \, du \, dv$

$$= \int_0^1 \int_0^{v^2} \sqrt{1+v^3} \, du \, dv = 2(2\sqrt{2}-1)/9$$

ex: Calculate volume of an elliptic cylinder
of base  and height h.

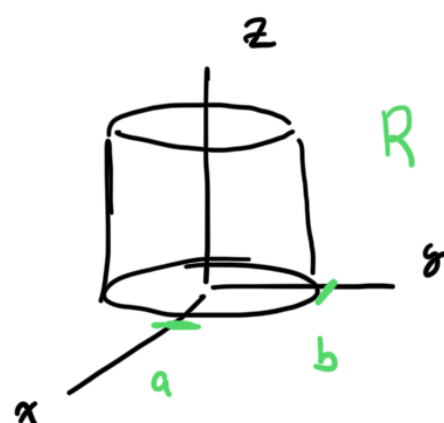
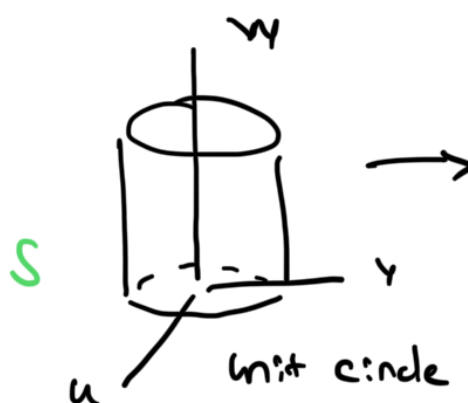


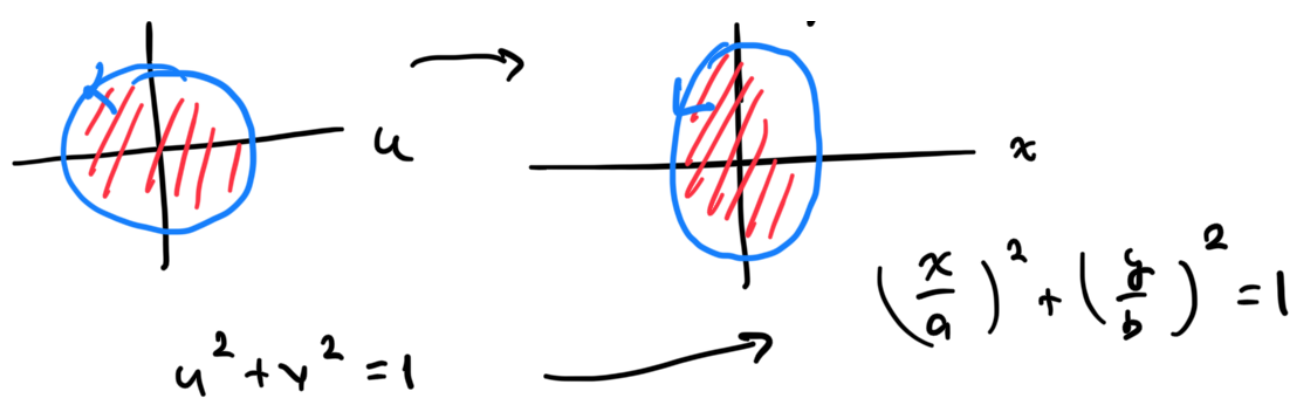
$$a u = x$$

$$b v = y$$

$$w = z$$

then





$$\text{Jacobian } (u, v, w) = \begin{vmatrix} x_u & x_v & x_w \\ y_u & y_v & y_w \\ z_u & z_v & z_w \end{vmatrix} = \begin{vmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & 1 \end{vmatrix} = ab$$

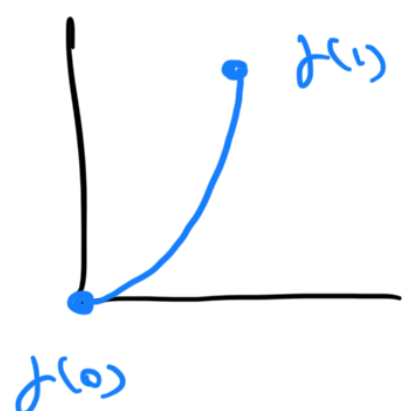
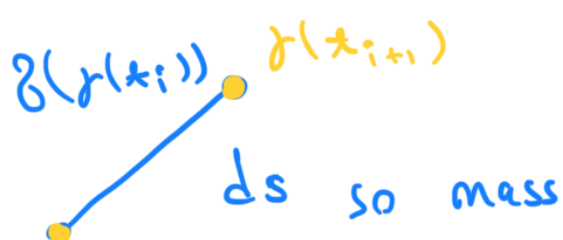
so $\iiint_R dV = \iiint_S ab dV'$ $dV' = da dv dw$

$$= ab \iiint_S dV' \leftarrow \begin{array}{l} \text{volume cylinder height } h \\ \text{unit circle base} \end{array}$$

$$= \pi abh$$

16.1: Line integrals of scalar functions

Motivated by example of mass of a wire in $\mathbb{R}^2$. Say we have $\rho(x, y) = x$ kg/m and have a curve by $\gamma(t) = (t, t^2)$ for $0 \leq t \leq 1$. So want the mass of a small part of the wire



$$f(x_i)$$

$$\approx \underbrace{\rho(x_i) (\text{length from } x_{i+1} \text{ and } x_i)}_{\Delta s_i}$$

$$\text{Mass} \approx \sum_{\text{bunch of pieces}} \rho(x_i) \Delta s_i$$

$$\xrightarrow{\text{limit}} \int_0^1 \rho(x) ds$$

$$ds = \sqrt{1 + (2x)^2} dx$$

$$\text{So } M = \int_0^1 x \cdot 1 \cdot (\sqrt{1 + 4x^2}) dx$$

$$= \int_1^5 \frac{1}{8} \sqrt{u} du$$

$$u = 1 + 4x^2$$

$$du = 8x dx$$

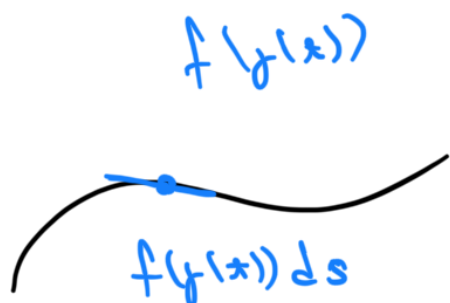
$$\frac{1}{8} du = x dx$$

$$u(0) = 1$$

$$u(1) = 5$$

$$= \frac{1}{12} (3\sqrt{5} - 1)$$

So in general, if C is a curve in $\mathbb{R}^2$ or $\mathbb{R}^3$,
we calculate 'line integrals' of a scalar
function f (even if C isn't a line).



$$\int_C f ds = \int_a^b f(x) |\vec{v}(x)| dx$$

where $f(x)$ goes from $f(a)$ to $f(b)$.

ex: Evaluate $f(x, y, z) = x^2 + y^2 + z^2$
along the line segment from $(0, 0, 0)$ to
 $(1, 1, 1)$.

$$f(x) = (x, x, x) \text{ from } x=0 \text{ to } x=1.$$

$$ds = \sqrt{1^2 + 1^2 + 1^2} dx = \sqrt{3} dx$$

$$\text{so } \int f ds = \int_0^1 (x^2 + x^2 + x^2) \sqrt{3} dx$$

$$= 3\sqrt{3} \left. \frac{t^3}{3} \right|_0^1 = \sqrt{3}$$

ex: Same problem but $\alpha(t) = (\sin t, \sin t, \sin t)$
 from $t=0$ to $t=\pi/2$.

$$(f \circ \alpha)(t) = 3\sin^2 t \quad ds = \sqrt{3\cos^2 t} dt$$

$$ds = \sqrt{3} |\cos t| dt$$

$$\text{so } \int_{\alpha} f ds = \int_0^{\pi/2} 3\sin^2 t \sqrt{3} \cos t dt$$

$$= \int_0^1 3\sqrt{3} u^2 du$$

$$u = \sin t \quad u(0) = 0$$

$$du = \cos t dt \quad u(\pi/2) = 1$$

$$0 = \sqrt{3}$$

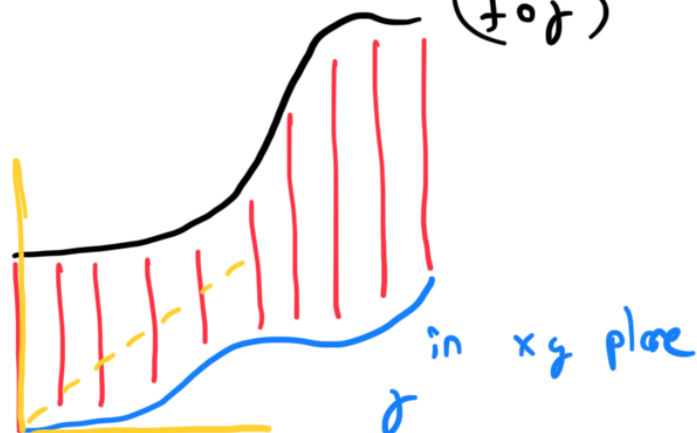
Moral: Doesn't matter how you parametrize
 the path, so choose most convenient!

ex: let $z = x^2 + y^2$ integrate function over

path $\gamma(t) = (\cos t, \sin t)$

f of blue
 $(f \circ \gamma)$

In green:



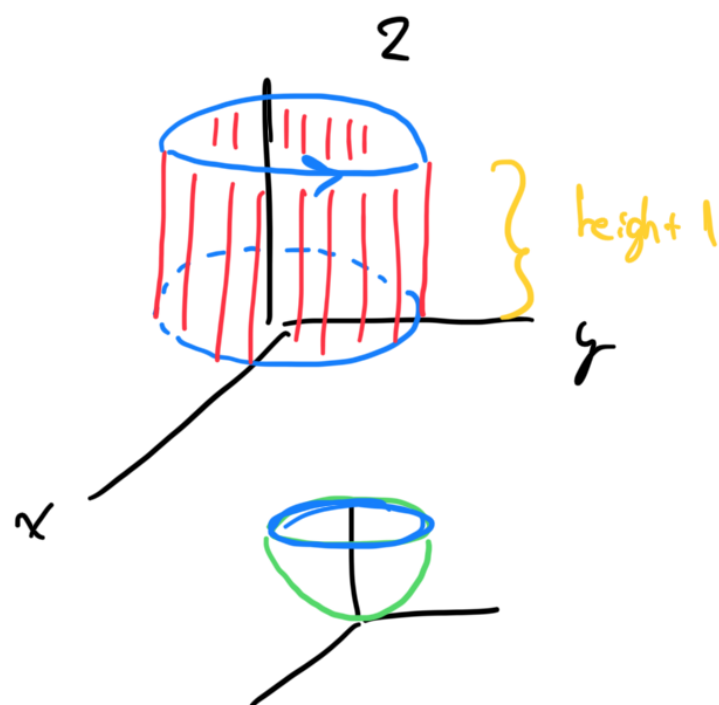
$$\text{Area} = \int_{\gamma} f ds.$$

In our example $f(y(x)) = \cos^2 x + \sin^2 x$

$$ds = \sqrt{\sin^2 x + \cos^2 x} dx$$

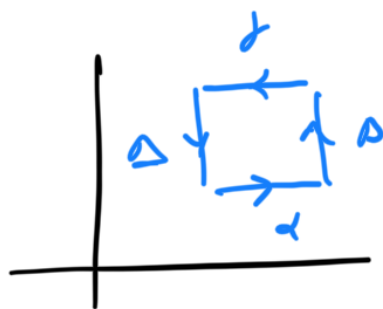
$$\text{So } ds = dx$$

$$\text{So Area} = \int_0^{2\pi} 1 dx = 2\pi$$



ex: Say have a $\mathcal{C}(x, y) = \frac{x}{y}$.

Want to calculate mass of square with vertices $(1,1), (2,1), (1,2), (2,2)$.



$$(i). \alpha(x) = (1+x, 1) \quad ds = dx$$

$$(ii). \beta(x) = (2, 1+x) \quad ds = dx$$

$$(iii). \gamma(x) = (2-x, 2) \quad ds = dx$$

$$(iv). \Delta(x) = (1, 2-x) \quad ds = dx$$

all $0 \leq x \leq 1$

$$(i). \mathcal{C}(\alpha(x)) = \frac{1+x}{1} = 1+x \quad (ii). (\mathcal{C} \circ \beta)(x) = \frac{2}{1+x}$$

$$\int_0^1 (1+x) dx = 3/2$$

$$\int_0^1 \frac{2}{1+x} dx = \ln(4)$$

$$(iii). (\mathcal{C} \circ \gamma)(x) = \frac{2-x}{2}$$

$$(iv). (\mathcal{C} \circ \Delta)(x) = \frac{1}{2-x}$$

$$\int_0^1 \frac{2-x}{2} dx = 3/4$$

$$\int_0^1 \frac{1}{2-x} dx = \ln(2)$$

$$M = M_1 + M_2 + M_3 + M_4 = 9/4 + 3\ln(2)$$

ex: let's say have wire $\gamma(t) = (\cos t, \sin t, t)$

$\phi(x, y, z) = (x^2 + y^2)e^z$. Write integrals for the various moments of inertia of the wire relative to each of the coordinate axes. Do not calculate.

$$I_g = \int_0^1 (x^2 + z^2) \rho ds$$

$$I_z = \int_S (x^2 + y^2) \rho \, dS$$

$$I_x = \int_0^{2\pi} (\sin^2 x + x^2) (\cos^2 x + \sin^2 x) e^x \sqrt{2} dx$$

$$= \sqrt{2} \int_0^{2\pi} (\sin^2 x + x^2) e^x dx$$

$$\begin{aligned} I_y &= \int_0^{2\pi} (\cos^2 x + x^2) (\cos^2 x + \sin^2 x) e^x \sqrt{2} dx \\ &= \sqrt{2} \int_0^{2\pi} (\cos^2 x + x^2) e^x dx \end{aligned}$$

$$\begin{aligned} I_2 &= \int_0^{2\pi} (\cos^2 x + \sin^2 x) (\cos^2 x + \sin^2 x) e^x \sqrt{2} dx \\ &= \sqrt{2} \int_0^{2\pi} e^x dx \end{aligned}$$

ex: Same path as before but assign constant

1 2 0.1-1m ratio of mass of

density ρ . Calculate the center of mass of the wire. Intuitively $(\bar{x}, \bar{y}, \bar{z}) = (0, 0, \pi)$.

$$M_x = \int_C x \rho \, ds = \rho \int_0^{2\pi} (\cos t) \sqrt{2} \, dt = 0$$

$$M_y = \int_C y \rho \, ds = \rho \int_0^{2\pi} (\sin t) \sqrt{2} \, dt = 0$$

$$M_z = \int_C z \rho \, ds = \rho \int_0^{2\pi} t \sqrt{2} \, dt = \rho 2\sqrt{2} \pi^2$$

$$M = \int_C \rho \, ds = \rho \int_0^{2\pi} \sqrt{2} \, dt = \rho 2\pi\sqrt{2}$$

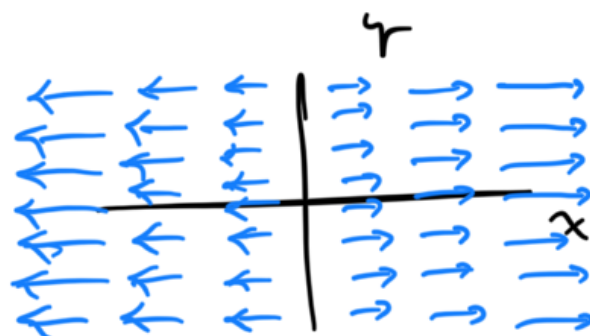
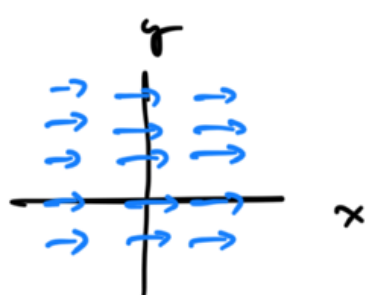
$$\text{So } (\bar{x}, \bar{y}, \bar{z}) = \frac{(0, 0, \rho 2\sqrt{2} \pi^2)}{\rho 2\pi\sqrt{2}}$$

$$= (0, 0, \pi)$$

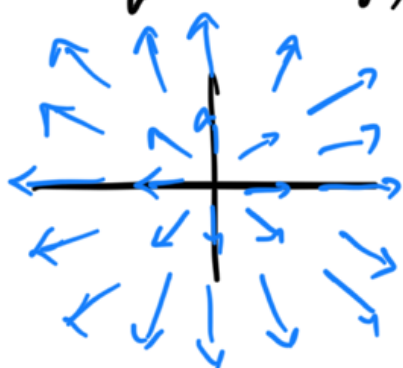
16, 2: Line integrals, Vector Fields, Work, Circulation, Flux.

A vector field is a map that associates each point (x, y) a vector $\vec{F}(x, y)$. Can visualize them by drawing a bunch of arrows.

e.g.: $\vec{F}(x, y) = (1, 0)$ e.g. $\vec{F}(x, y) = (x, 0)$



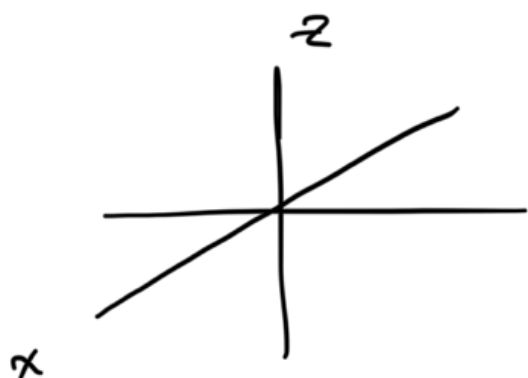
e.g. $\vec{F}(x, y) = (x, y)$



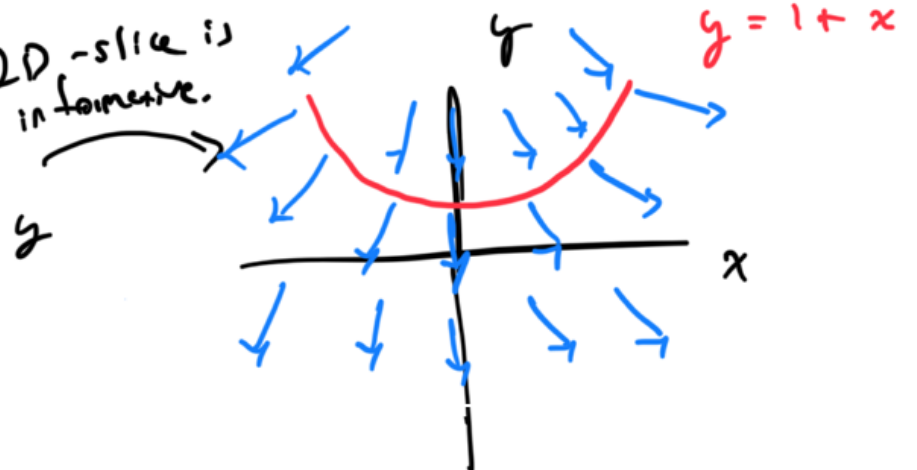
Why? : Velocity field of wind map, Electric field of particles, magnetic fields, Force fields more generally, etc.

ex: let $f(x, y, z) = x^2 - y$ then

$$\nabla f(x, y, z) = (2x, -1, 0)$$

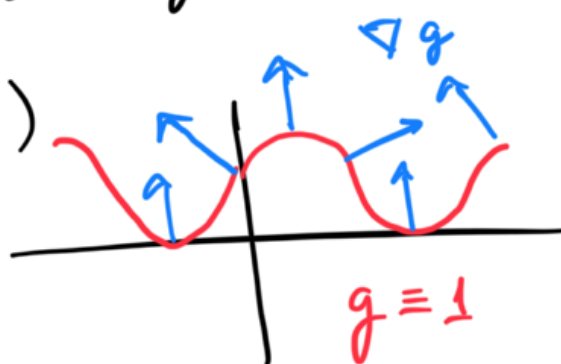


2D-slice is informative.



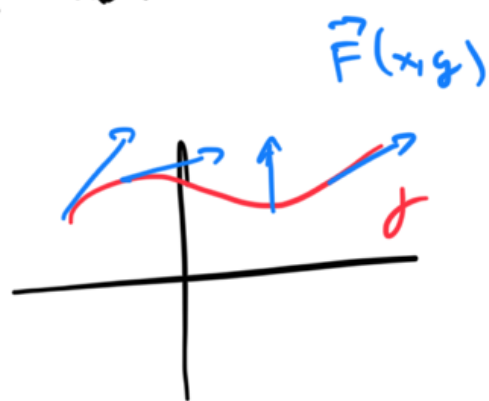
example of a gradient vector field. Take your favorite function. e.g. $g(x, y) = y - \sin(x)$

and $\nabla g(x, y) = (-\cos(x), 1)$

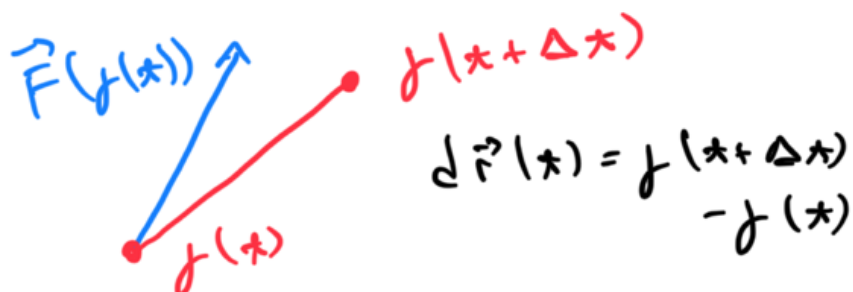


let's say have a force vector field

$\vec{F}(x, y)$. Say you have a curve γ . Want to calculate how much work it takes to do $\vec{F}(x, y)$ along γ .



at infinitesimal level...



$$W(\gamma(t)) \approx \vec{F}(\gamma(t)) \cdot d\vec{r}(t) \\ \approx \vec{F}(\gamma(t)) \cdot (\gamma(t + \Delta t) - \gamma(t))$$

$$\text{So Work} = \int_{\gamma} \vec{F} \cdot d\vec{r} = \int_a^b \underbrace{\vec{F}(\gamma(t)) \cdot \frac{d\vec{r}}{dt}(t)}_{\text{we did last section.}} dt$$

ex: Consider $\vec{F}(x, y, z) = (x - y, x + y, z)$

and calculate work along straight line from $(0, 0, 0)$ to $(1, 1, 0)$.

$$\gamma(t) = (t, t, 0) \quad \text{so} \quad \frac{d\vec{r}}{dt} = (1, 1, 0)$$

$$\vec{F}(\gamma(t)) = (t - t, t + t, 0) = (0, 2t, 0)$$

$$\text{So } W = \int_0^1 (0, 2x, 0) \cdot (1, 1, 0) dx = \int_0^1 2x dx = 1 \text{ Nm}$$

Gives rise to notion of a line integral (even though not always lines).

def: let $\vec{F}$ be a vector field and let γ be a smooth curve parametrized by $\vec{r}(x)$. Define

$$\int_{\gamma} \vec{F} \cdot \vec{T} ds = \int_{\gamma} \vec{F} \cdot \frac{d\vec{r}}{ds} ds = \int_{\gamma} \vec{F} \cdot d\vec{r}$$

where s is arc length parameter and $\vec{T}$ is unit tangent vector.

ex: let $\vec{F}(x, y, z) = (y^2, 2xy, -1)$.

Calculate line integral of $\vec{F}$ over the curve

$$\gamma(x) = (x, x^2, 1) \text{ from } (0, 0, 1) \text{ to } (1, 1, 1).$$

$$\vec{F}(\gamma(x)) = (x^4, 2x^3, -1)$$

$$\frac{d\vec{r}}{dx} = (1, 2x, 0) \quad x = 0 \text{ to } x = 1.$$

$$\begin{aligned} \text{So } \int_{\gamma} \vec{F} \cdot d\vec{r} &= \int_0^1 (x^4, 2x^3, -1) \cdot (1, 2x, 0) dx \\ &= \int_0^1 x^4 + 4x^4 + 0 dx = \int_0^1 5x^4 dx \\ &= 1 \end{aligned}$$

You may see differential form version that looks like

$$\int_{\gamma} M dx + N dy + P dz$$

which is just done in the following manner.

ex: Calculate $\int_{\gamma} x dx + y dy + z dz$

along the curve $\gamma(t) = (t, t^2, t^3)$ from $t=0$ to $t=1$.

$$\begin{aligned} x &= t & dx &= dt \\ y &= t^2 & dy &= 2t dt \\ z &= t^3 & dz &= 3t^2 dt \end{aligned}$$

So --

$$I = \int_0^1 t dt + (t^2)(2t) dt + (t^3)(3t^2) dt$$

$$\begin{aligned} &= \int_0^1 (t + 2t^3 + 3t^5) dt = \frac{1}{2} + \frac{2}{3} + \frac{3}{6} \\ &= 3 + 4 + 3/6 = 10/6 = 5/3 \end{aligned}$$

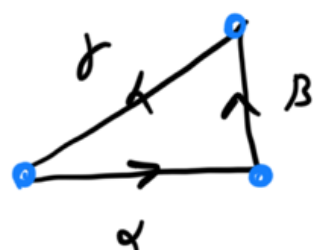
def: if $\gamma(t)$ is a smooth curve and $\vec{F}$ is a velocity field, e.g. velocity of water, then the flow of $\vec{F}$ along γ is given by

$$\text{Flow} = \int_{\gamma} \vec{F} \cdot d\vec{r}$$

this is called a flow integral. If γ starts and ends at the same point, then we call the integral the circulation. Denoted $\oint$ or $\oint$ depending on orientation.

ex: let $\vec{F}(x,y) = (x+y)\hat{i} + (x-y)\hat{j}$ and

let γ be the triangle with vertices at $(0,0)$, $(1,0)$ and $(1,1)$. Write out integrals to calculate the circulation if path is traversed counter clockwise.



$$\alpha = (x, 0)$$

$$\beta = (1, x)$$

$$\gamma = (1-x, 1-x)$$

$$\alpha: d\vec{r} = (1, 0) dx \quad \vec{F} \cdot d\vec{r} = (x, x) \cdot (1, 0) dx$$

$$\beta: d\vec{r} = (0, 1) dx \quad \vec{F} \cdot d\vec{r} = (1+x, 1-x) \cdot (0, 1) dx$$

$$\gamma: d\vec{r} = (-1, -1) dx \quad \vec{F} \cdot d\vec{r} = (2-2x, 0) \cdot (-1, -1) dx$$

$$\text{so } \int_{\alpha} \vec{F} \cdot d\vec{r} = \int_0^1 x dx = 1/2$$

$$\int_{\beta} \vec{F} \cdot d\vec{r} = \int_0^1 1-x dx = 1/2$$

$$\int_{\gamma} \vec{F} \cdot d\vec{r} = \int_0^1 -(2-2x) dx = -1$$

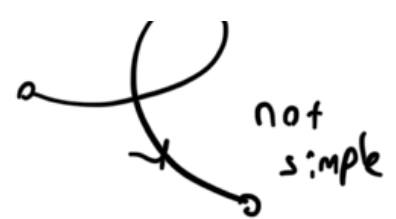
$$\text{so } \oint_C \vec{F} \cdot d\vec{r} = 1/2 + 1/2 - 1 = 0$$

Flux integrals.

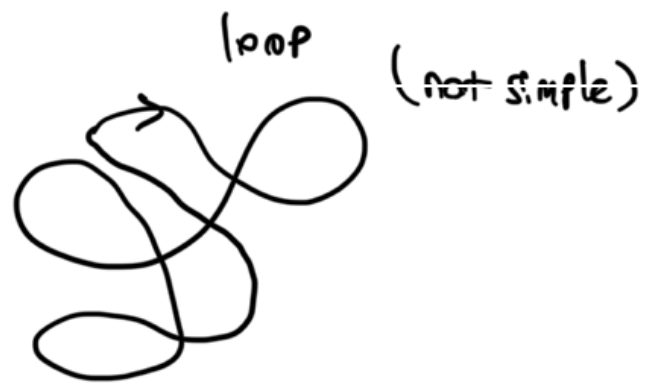
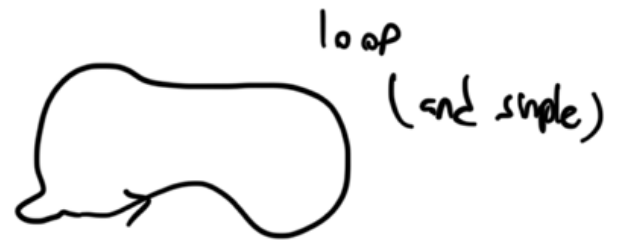
A curve in $\mathbb{R}^2$ is called simple if it does

circle

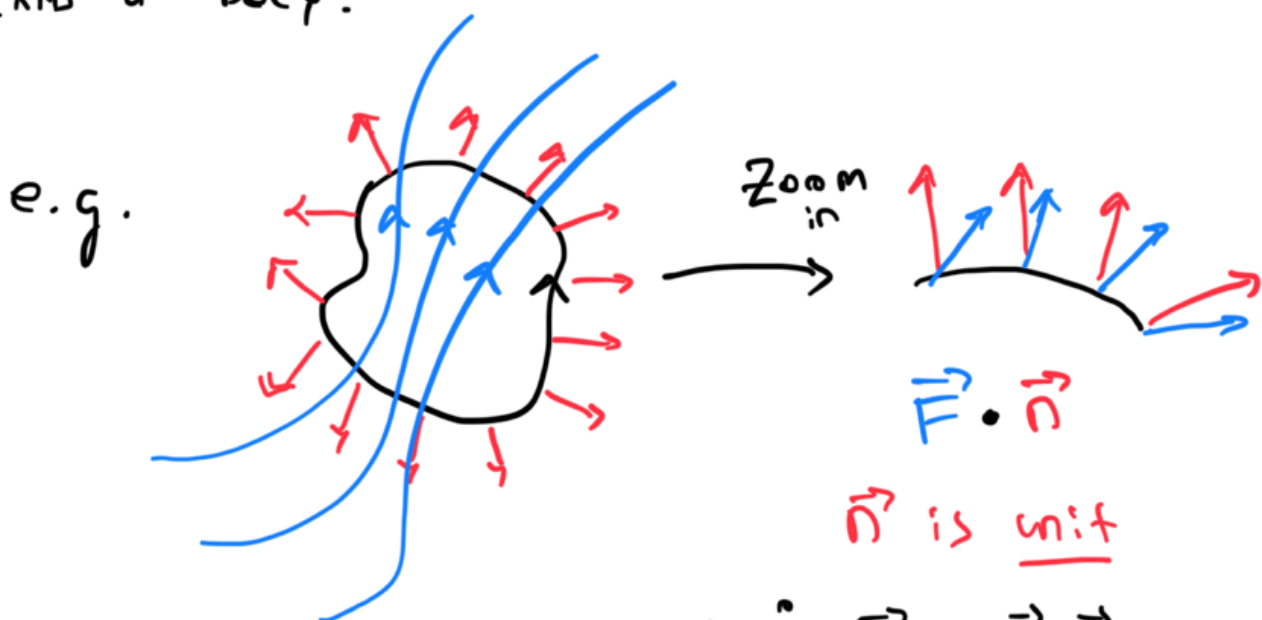
not cross itself.



A curve is called a loop if it starts and ends at the same point.



Sometimes interested in calculating how much enters a body and exits a body.



Want to add all $\vec{F} \cdot \vec{n}$ along boundary so get

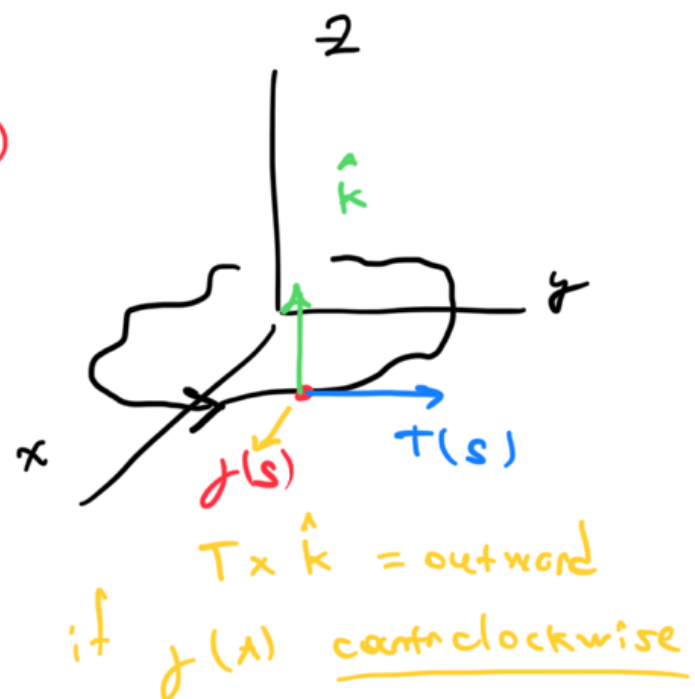
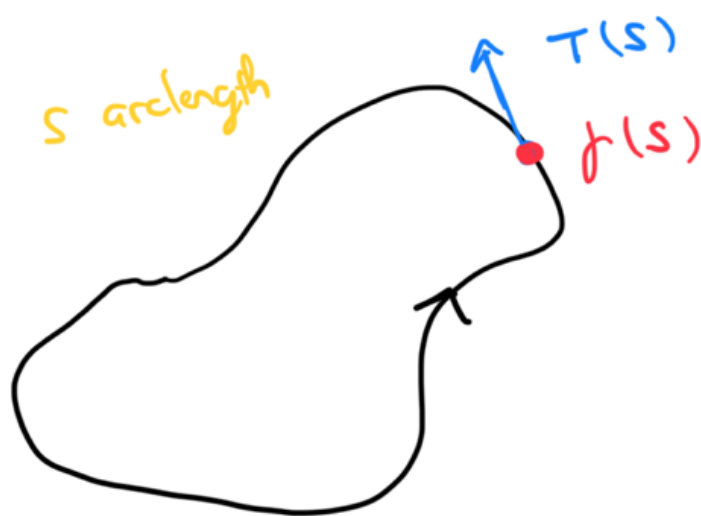
$$\text{proj}_{\vec{u}} \vec{v} = \frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\|^2} \vec{u}$$

def: let C be simple closed curve in the plane and consider vector field $\vec{F}$. We define the flux of $\vec{F}$ across C to be

$$\text{Flux of } \vec{F} \text{ across } C = \int_C \vec{F} \cdot \vec{n} \, ds$$

where $\vec{n}$ is unit outward normal to C .

Question: How to get unit normal?



In coordinates if $j(s) = (x(s), y(s), 0)$ then

$$\vec{n}(s) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{dx}{ds} & \frac{dy}{ds} & 0 \\ 0 & 0 & 1 \end{vmatrix} = \hat{i} \left(\frac{dy}{ds} \right) - \hat{j} \left(\frac{dx}{ds} \right) + 0 \hat{k}$$

$$T(s) = \left(\frac{dx}{ds}, \frac{dy}{ds}, 0 \right)$$

so $\vec{n}(s) = \left(\frac{dy}{ds}, -\frac{dx}{ds}, 0 \right)$ then

$$\vec{F}(x, y) \cdot \vec{n}(s) = M(x, y) \frac{dy}{ds} - N(x, y) \frac{dx}{ds}$$

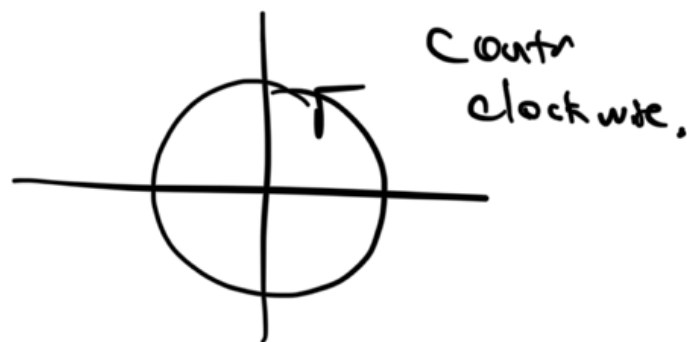
$$\vec{F}(x, y) = (M(x, y), N(x, y))$$

So ...

$$\text{Flux of } \vec{F} = \oint_C M \, dy - N \, dx$$

ex: let $\vec{F}(x, y) = (-y, x)$. Evaluate
the flux of $\vec{F}$ across the unit circle.

$$\gamma(t) = (\cos t, \sin t)$$



so $dx = -\sin t \, dt$

$dy = \cos t \, dt$

and $\vec{F}(\cos t, \sin t)$

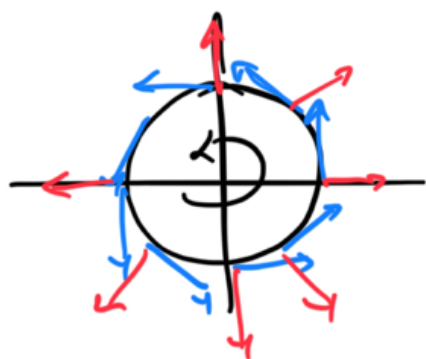
$$= (-\sin t, \cos t)$$

M N

thus $\oint_{\gamma} \vec{F} \cdot \vec{n} \, ds = \int_0^{2\pi} \underbrace{(-\sin t)}_{\text{M}} \underbrace{(\cos t)}_{dy} \, dt = 0$

$$= \underbrace{(\cos t)}_N \underbrace{(-\sin t)}_{dx} \, dt$$

why 0



nothing entering or exiting.

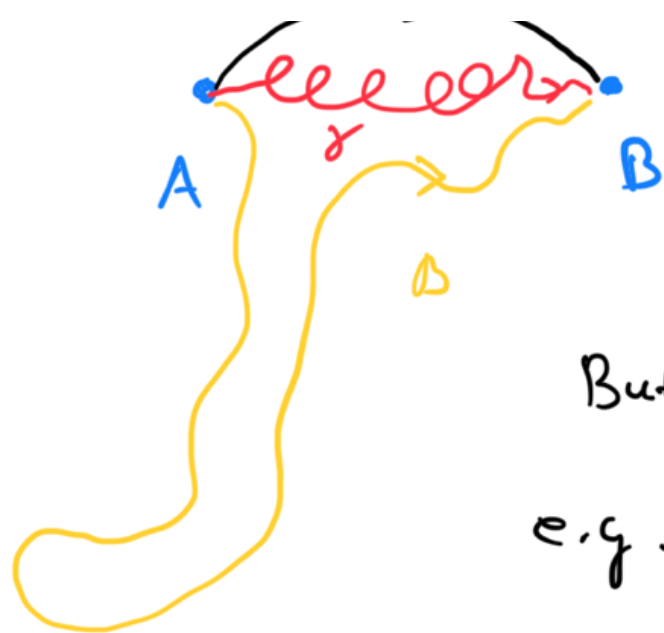
16.3: Path independence, Conservative Fields,
and Potential Functions

Typically if integrating vector field along a path,
it depends on which path.

typically

$$\int_{\gamma} \alpha$$

$$\int_{\gamma} \alpha \neq \int_{\gamma} \vec{F} \cdot d\vec{r}$$



$$\int_{\alpha} \vec{F} \cdot d\vec{r} \neq \int_{\beta} \vec{F} \cdot d\vec{r}$$

But sometimes it happens!

e.g. $\vec{F} = (0, -g)$ gravity.

let γ be any path from $(0,0)$ to $(0,1)$.

$$(x(t), y(t)) = \gamma(t) \text{ with } \gamma(0) = A \text{ } \gamma(1) = B$$

$$\text{then } d\vec{r} = (dx, dy) = (x'(t)dt, y'(t)dt)$$

$$\text{so } W = \int_{\gamma} \vec{F} \cdot d\vec{r} = \int_0^1 -g \frac{dy}{dt} dt$$

$$= -g(y(1) - y(0)) = -g(1 - 0)$$

$$\approx 10 \text{ Nm}$$

def: let $\vec{F}$ be a vector field such that
for any two points A and B, and any two
paths α, β connecting them we have

$$\int_{\alpha} \vec{F} \cdot d\vec{r} = \int_{\beta} \vec{F} \cdot d\vec{r}$$

We say $\vec{F}$ is a conservative vector field and

$$\int_{\alpha} \vec{F} \cdot d\vec{r} \text{ is } \underline{\text{path independent}}.$$

Why did above example work and how can you
construct more? Hence a definition of a

consequence.

def: if $\vec{F}$ is a vector field such that
 $\vec{F} = \nabla f$ for some scalar function f ,
we call f a potential function for $\vec{F}$.

e.g. gravitational potential, electrical potential.

Why these nice? Because we have

$$\int_{\gamma} \vec{F} \cdot d\vec{r} = \int_{\gamma} \nabla f \cdot d\vec{r} = f(B) - f(A)$$

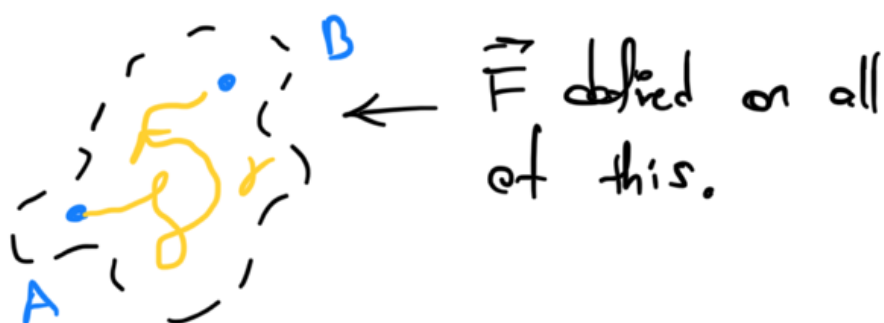
where $\gamma(0) = A$ and $\gamma(1) = B$.

In particular, $\oint_{\gamma} \vec{F} \cdot d\vec{r} = 0$ for any
closed loop γ .

Word of warning: Assumptions are made
on domain of $\vec{F}$, domain of f , derivatives,
and paths.

- We require $\vec{F}$ to be defined on a
connected region containing path γ .

e.g.



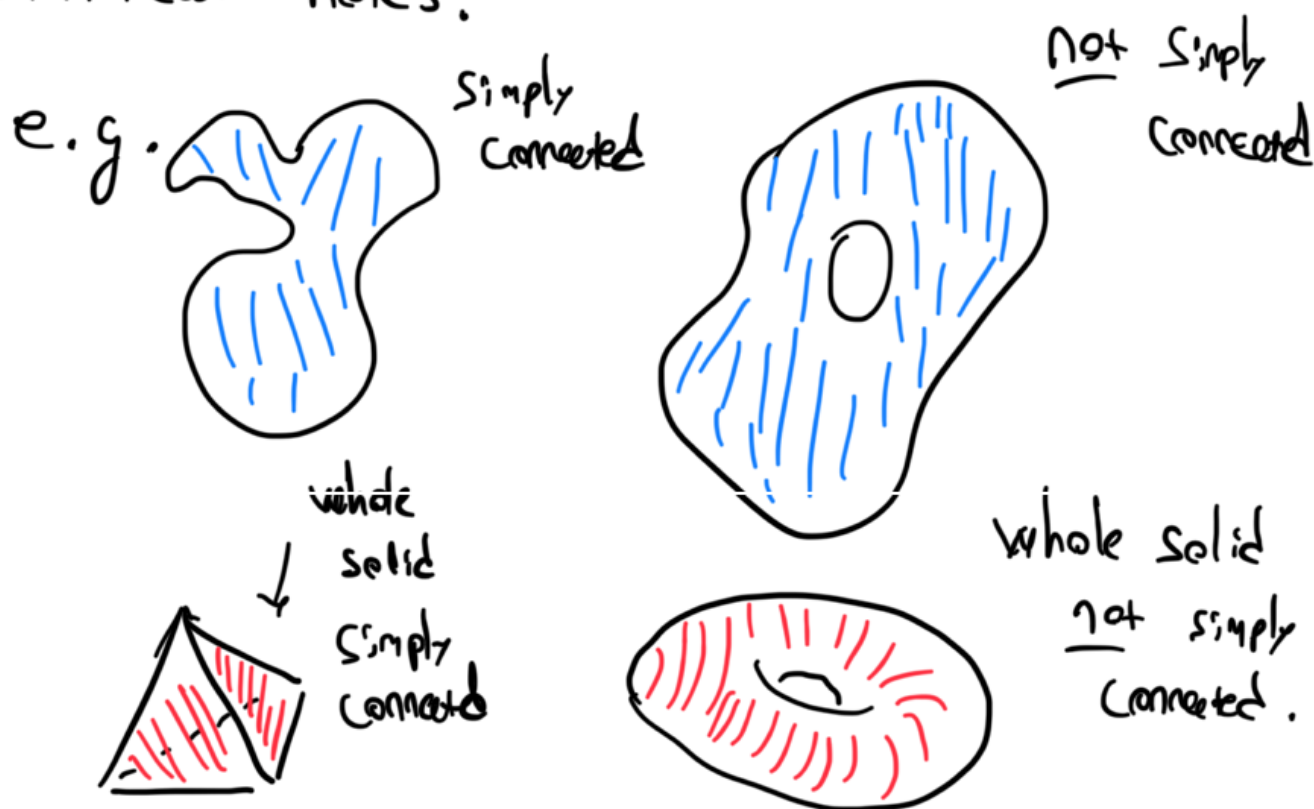
- Same for f

- Want curves to be piecewise smooth

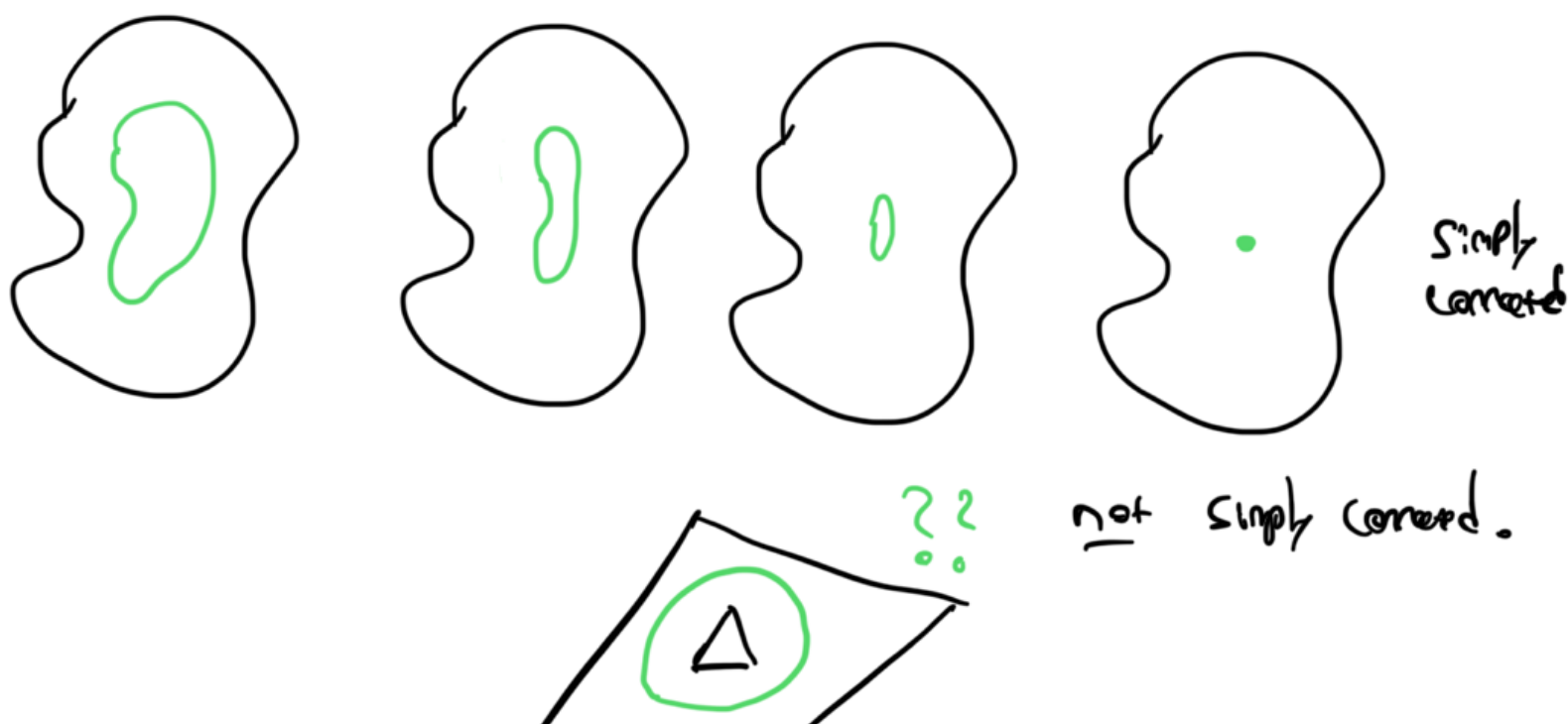
Wario! or

Mario!

- In future theorems we'll need simply connected which is a connected region 'without holes.'



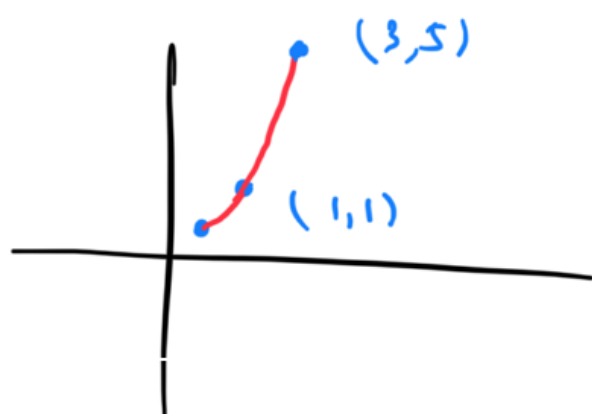
idea is every loop can be shrunk to a point.



ex: Integrate $\vec{F} = \left(\frac{2x}{x^2+y^2}, \frac{2y}{x^2+y^2} \right)$

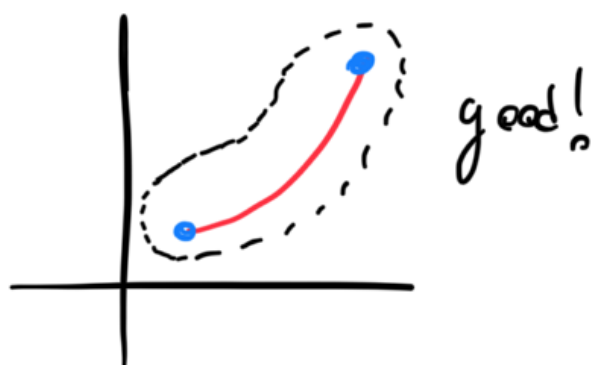
along the parabola connecting the points

$(1,1)$, $(2,2)$ and $(3,5)$, from $(1,1)$ to $(3,5)$



notice $\vec{F}$ is 'bad' only at $(0,0)$. We can

contain entire parabola in a region that avoids $(0,0)$.



May apply theorem. Note $f(x,y) = \ln(x^2+y^2)$

then $\nabla f = \left(\frac{2x}{x^2+y^2}, \frac{2y}{x^2+y^2} \right)$ so

$$\begin{aligned} \int_C \nabla f \cdot d\vec{r} &= f(B) - f(A) = \ln(3^2+5^2) \\ &\quad - \ln(1^2+1^2) \\ &= \ln(34) - \ln(2) \\ &= \ln(17) \end{aligned}$$

We saw that if $\vec{F}$ comes from a potential function i.e. $\vec{F}$ is a gradient field means path integrals are independent of path and only depend on endpoints. Under mild assumptions on domain the converse is true.

Theorem: Let $\vec{F}$ be a vector field whose component functions are continuous on an open connected region D . Then $\vec{F}$ is conservative iff $\vec{F}$ is a gradient field. (i.e. can solve $\vec{F} = \nabla f$ for some function f).

Corollary: $\oint_{\gamma} \vec{F} \cdot d\vec{r} = 0$ for all loops in domain D iff $\vec{F}$ is conservative on D .

Summarize as ... let D be open domain and $\vec{F}$ be 'nice'.

$\vec{F} = \nabla f$ on D for some f iff $\vec{F}$ conservative on D iff $\oint_{\gamma} \vec{F} \cdot d\vec{r} = 0$ for all loops in D

Two obvious questions:

1. How do you test if a vector field is conservative?

2. How do you find a potential function if $\vec{F}$ is conservative?

theorem: let $\vec{F} = (M, N, P)$ all M, N, P functions of x, y, z , on simply connected domain D .

Assume nice differentiability. Then $\vec{F}$ conservative

$$\text{iff } \nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ M & N & P \end{vmatrix} = \text{curl of } \vec{F}$$

$$= \left(\frac{\partial P}{\partial y} - \frac{\partial N}{\partial z} \right) \hat{i} - \left(\frac{\partial P}{\partial x} - \frac{\partial M}{\partial z} \right) \hat{j} + \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) \hat{k} = \vec{0}$$

(should mention in 2D some deal sort of)

$\vec{F} = (M, N)$ then on simply connected

domain $\vec{F}$ conservative iff $\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} = 0$

(Just like we did before!)

ex: Determine if

$$\vec{F} = \left(\cos(y) e^{yz^2}, e^{yz^2} x z^2 \cos(y) + \ln(z) - e^{yz^2} x \sin(y), \left(1 + \frac{y}{z} + 2e^{yz^2} x y z \cos(y) \right) \right) \text{ is conservative}$$

on $z > 0$. Now $\vec{F}$ defined everywhere on $z > 0$ simply connected, so curl test will suffice.

You can do these calculations and find out that

$\nabla \times \vec{F} = \vec{0}$ so by the theorem it's conservative.

What potential function? Options.

1. $\cos(y) e^{yz^2}$ wrt to x ← easiest.

2. $e^{yz^2} x z^2 \cos(y) + \ln(z) - e^{yz^2} x \sin(y)$ wrt to y

3. $1 + \frac{y}{z} + 2e^{yz^2} x y z \cos(y)$ wrt to z

$$f(x, y, z) = x \cos(y) e^{yz^2} + h(y, z).$$

$$\begin{aligned} \frac{df}{dy} &= (-x \sin(y) + x \cos(y) z^2) e^{yz^2} + \frac{dh}{dy} \\ &= -x \sin(y) e^{yz^2} + x \cos(y) z^2 e^{yz^2} + h_y \\ &= -x \sin(y) e^{yz^2} + x z^2 \cos(y) e^{yz^2} + \ln(z) \end{aligned}$$

$$\text{so } \frac{dh}{dy} = \ln(z) \text{ so } h(y, z) = y \ln(z) + j'(z).$$

$$\frac{df}{dz} = x \cos(y) e^{yz^2} \cdot 2yz + \frac{y}{z} + j'(z)$$

$$= 1 + \frac{y}{z} + 2e^{yz^2} x y z \cos(y)$$

$$\text{so } j'(z) = 1 \Rightarrow j(z) = z + C$$

thus potential function is

$$1. \quad \dots e^{yz^2} \cdot \ln(z) + z + C \text{ for}$$

$$f(x, y, z) = x \cos(y) + y \ln(x) + \dots + \text{const } C.$$

Simply connected hypothesis is nessary

$$\text{ex: } \vec{F}(x, y) = \left(\underset{M}{-y/x^2+y^2}, \underset{N}{x/x^2+y^2} \right)$$

$$\text{thn } \frac{dM}{dy} - \frac{dN}{dx} = 0 \quad (\text{can check}). \quad f(*)$$

However domain not simply connected.



Moreover if $\int_{\gamma} \vec{F} \cdot d\vec{r}$ with γ unit circle,

$$\text{get } d\vec{r} = (-\sin(*), \cos(*)) dx \text{ and}$$

$$(\vec{F} \circ \gamma)(*) = \left(\frac{-\sin *}{\cos^2 * + \sin^2 *}, \frac{\cos *}{\cos^2 * + \sin^2 *} \right)$$

$$\text{so } \vec{F} \cdot d\vec{r} = 1 dx \text{ and}$$

$$\int_{\gamma} \vec{F} \cdot d\vec{r} = \int_0^{2\pi} 1 dx = 2\pi \text{ so}$$

not conservative.

No potential function exists!

Differential forms

Recall we had integrals of the form

$$\int \dots (2D) \text{ and}$$

$$\int M dx + N dy$$

$$\int M dx + N dy + P dz \quad (3D)$$

quantities $M dx + N dy$ or $M dx + N dy + P dz$ are called differential forms (more specifically they are called 1-forms) You can integrate them over curves like we've been doing.

A particularly nice type of differential form is an exact differential form.

An exact differential form $\omega = M dx + N dy + P dz$ is one where you can find a function f so that

$$\omega = df = \frac{df}{dx} dx + \frac{df}{dy} dy + \frac{df}{dz} dz \quad \text{so}$$

$$M = \frac{df}{dx} \quad N = \frac{df}{dy} \quad P = \frac{df}{dz}$$

It's nice because we have for any path γ ,

$$\int_{\gamma} \omega = \int_{\gamma} M dx + N dy + P dz = \int_{\gamma} df$$

$$= \int_{\gamma} \nabla f \cdot d\vec{r} = f(B) - f(A) \quad \text{where } A$$

is starting point of γ and B is the end.

To test if a diff form

$$\omega = M dx + N dy + P dz \quad \text{is exact}$$

on a simply connected domain we use the

Score test as before,

thm: $\omega = M dx + N dy + P dz$ is exact on
a simply connected domain if

$$\frac{\partial P}{\partial y} = \frac{\partial N}{\partial z} \quad \frac{\partial M}{\partial z} = \frac{\partial P}{\partial x} \quad \frac{\partial N}{\partial x} = \frac{\partial M}{\partial y}$$

(in 2D) $w = M dx + N dy$
need $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$)

ex: Show $w = (2x+y) dx + x dy + 2z dz$
is exact and then find a function f so that
 $df = w$.

1. Expects just calculate and note down is all of B^3 .

2. $\frac{df}{dx} = 2x+y$ $\frac{df}{dy} = x$ $\frac{df}{dz} = 2z$

↑
why not

$$f(x, y, z) = xy + g(x, z)$$

$$\frac{df}{dx} = y + \frac{dy}{dx} = y + 2x \quad \text{so} \quad \frac{dy}{dx} = 2x$$

so $g(x, z) = x^2 + h(z)$

$$\frac{df}{dz} = 0 + 0 + h'(z) = 2z \quad \text{so} \quad h(z) = z^2 + C$$

$$r_1 = \sqrt{2}, \quad r_2 = \sqrt{2} + C$$

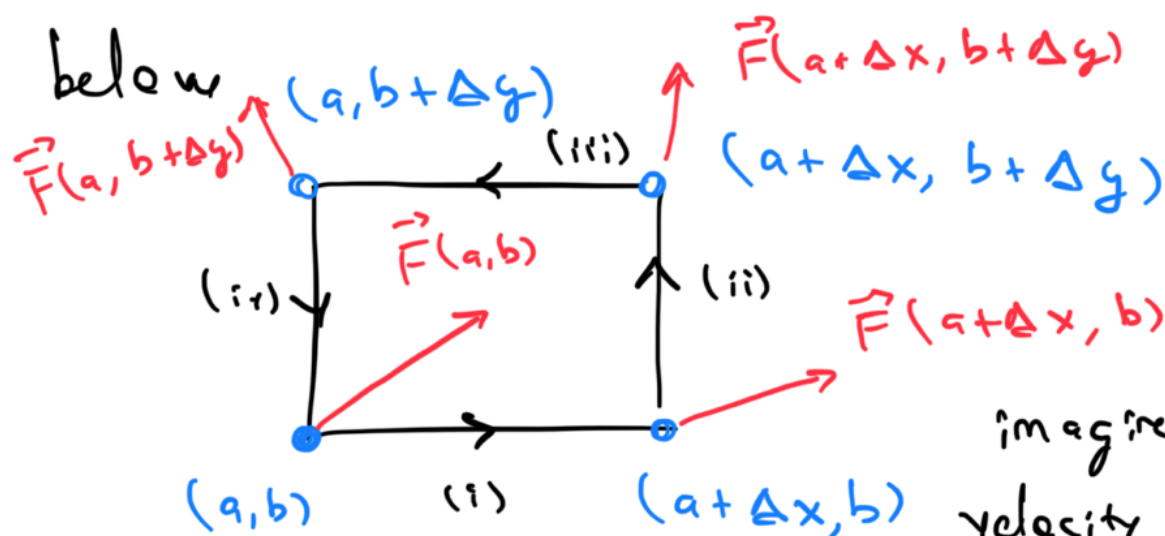
So $f(x, y, z) = x + y + z + 1.$

If we let $\int_C \omega$ where σ goes from $(0, 0, 0)$ to $(1, 1, 1)$ then

$$\begin{aligned}\int_C \omega &= f(1, 1, 1) - f(0, 0, 0) \\ &= 3 //\end{aligned}$$

16.4: Green's Theorem in the Plane

Consider a force field $\vec{F} = M(x,y)\hat{i} + N(x,y)\hat{j}$ in the plane. Consider a small rectangle



imagine $\vec{F}$ is a velocity field of a fluid.

Wish to calculate velocity along the rectangle.

$$(i). \vec{F}(a,b) \cdot d\vec{r} = M(a,b) \Delta x$$

$$(ii). \vec{F}(a+\Delta x, b) \cdot d\vec{r} = N(a+\Delta x, b) \Delta y$$

$$(iii). \vec{F}(a, b+\Delta y) \cdot d\vec{r} = M(a, b+\Delta y) (-\Delta x)$$

$$(iv). \vec{F}(a, b) \cdot d\vec{r} = N(a, b) (-\Delta y)$$

$$(i) + (iii)$$

$$= [M(a, b+\Delta y) - M(a, b)] (-\Delta x)$$

$$\approx -\frac{\partial M}{\partial y}(a, b) \Delta x \Delta y$$

$$(ii) + (iv)$$

$$= [N(a+\Delta x, b) - N(a, b)] \Delta y$$

$$\approx \frac{\partial N}{\partial x}(a, b) \Delta x \Delta y$$

$$\text{so } \Sigma_i (*) = \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) (a, b) \Delta x \Delta y$$

Circulation around rectangle = $\nearrow$

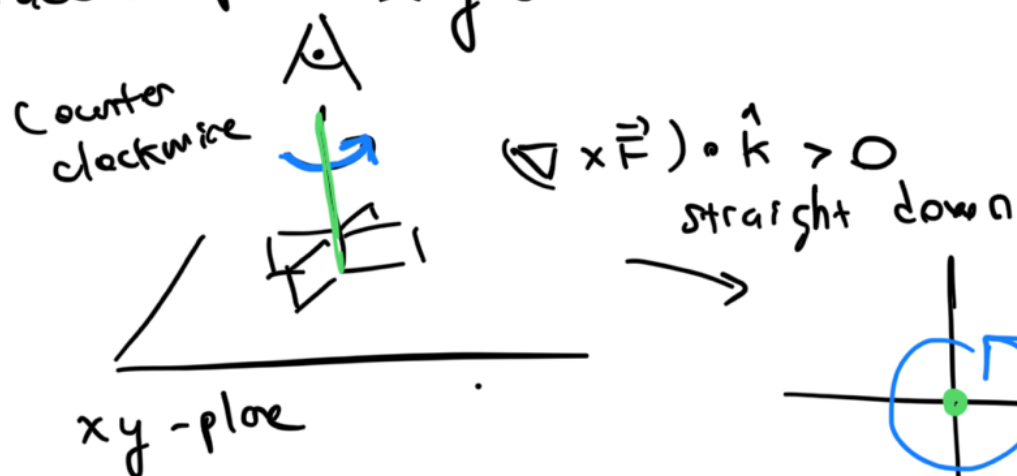
area of rectangle = $\Delta x \Delta y$

Call $\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}$ circulation density

$$= (\nabla \times \vec{F}) \cdot \hat{k}, \quad \vec{F} = (M, N, 0)$$

$$\begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ M & N & 0 \end{vmatrix}$$

= measurement how fast
a paddle spins subject to $\vec{F}$.



ex: Calculate the circulation density of
the below vector fields

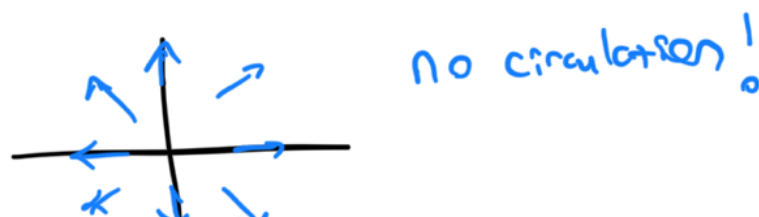
1. $\vec{F} = (x, y)$

2. $\vec{F} = (y, -x)$

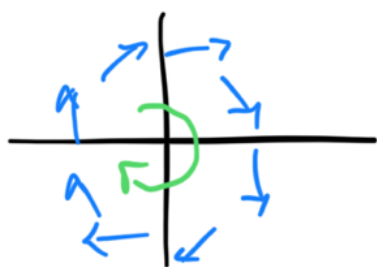
3. $\vec{F} = (0, x)$

4. $\vec{F} = \left(\frac{-y}{x^2+y^2}, \frac{x}{x^2+y^2} \right)$

1. $(\nabla \times \vec{F}) \cdot \hat{k} = \frac{\partial}{\partial x} y - \frac{\partial}{\partial y} x = 0$

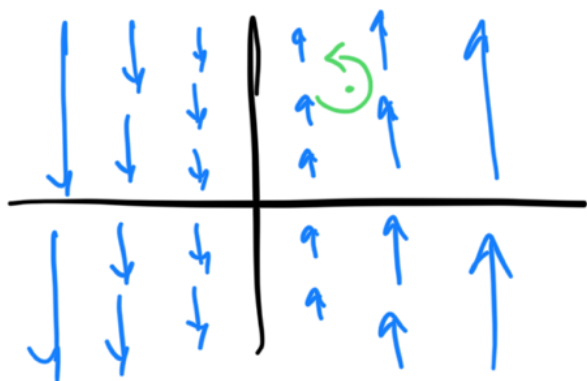


$$2. (\nabla \times \vec{F}) \cdot \hat{k} = \frac{d}{dx}(-x) - \frac{d}{dy}(y) = -2 < 0$$



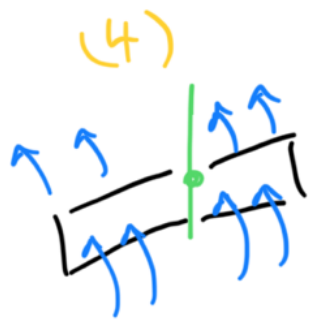
clockwise < 0

$$3. (\nabla \times \vec{F}) \cdot \hat{k} = \frac{d}{dx}(x) = 1 > 0$$

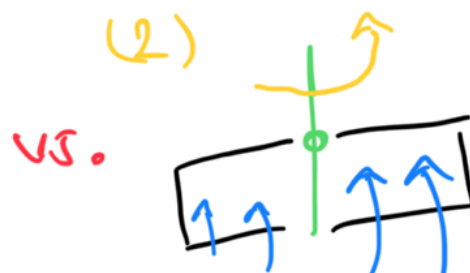


$$4. (\nabla \times \vec{F}) \cdot \hat{k} = \frac{d}{dx} \left(\frac{x}{x^2+y^2} \right) - \frac{d}{dy} \left(\frac{-y}{x^2+y^2} \right) = 0!$$

this is weird, this is just like (2), so
what gives? Note $\vec{F}$ not defined at $(0,0)$,
but also, if you put a paddle in water,
it'd be like this



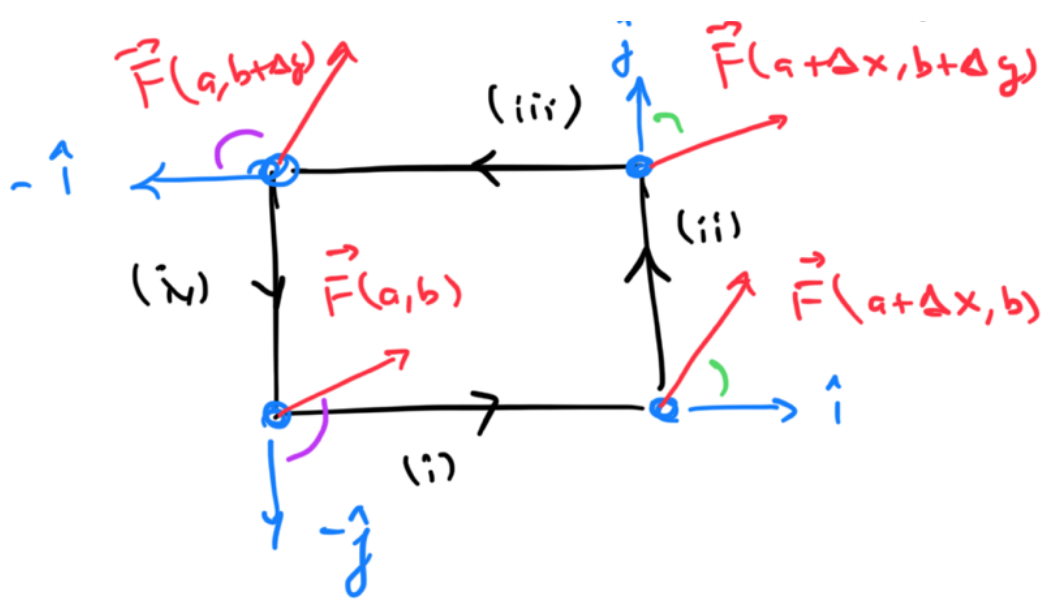
(4)
both hitting at
just right forces
to keep the thing
from moving bc $|\vec{F}|=1$.



(2)
vs. as you move
further out
there's more
force, so the
paddle will
spin bc $|\vec{F}|^2 = r^2$

Divergence

Again consider $\vec{F} = (M, N)$ now want to
measure how much a fluid is leaving a small area.



$$(i). \quad \vec{F}(a, b) \cdot \vec{n} \, ds = -N(a, b) \Delta x$$

$$(ii). \quad \vec{F}(a + \Delta x, b) \cdot \vec{n} \, ds = M(a + \Delta x, b) \Delta y$$

$$(iii). \quad \vec{F}(a, b + \Delta y) \cdot \vec{n} \, ds = N(a, b + \Delta y) (+\Delta x)$$

$$(iv). \quad \vec{F}(a, b) \cdot \vec{n} \, ds = M(a, b) (-\Delta y)$$

$$(i) + (iii) = (N(a, b + \Delta y) - N(a, b)) \Delta x$$

$$\approx \frac{\partial N}{\partial y} \Delta y \Delta x$$

$$(ii) + (iv) = (M(a + \Delta x, b) - M(a, b)) \Delta y$$

$$\approx \frac{\partial M}{\partial x} \Delta x \Delta y$$

$$\text{so } \sum_i (-) = \left(\frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} \right) \Delta x \Delta y$$

$$= \text{Flux of } \vec{F} \text{ across box}$$

so Avg flux across area

$$= \left(\frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} \right) (a, b)$$

flux density
or

divergence

$$\text{Also denoted by } \nabla \cdot \vec{F} = \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y}$$

measures how much stuff is expanding or contracting at a point.

ex: Calculate flux of vector fields below.
Explain results with pictures.

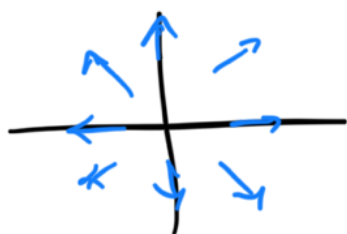
1. $\vec{F} = (x, y)$

2. $\vec{F} = (y, -x)$

3. $\vec{F} = (0, x)$

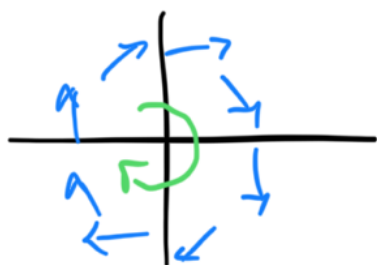
4. $\vec{F} = \left(\frac{-y}{x^2+y^2}, \frac{x}{x^2+y^2} \right)$

1.



We expect $\nabla \cdot \vec{F} > 0$. In fact,
 $\nabla \cdot \vec{F} = \frac{d}{dx}(x) + \frac{d}{dy}(y) = 2 > 0$.

2.

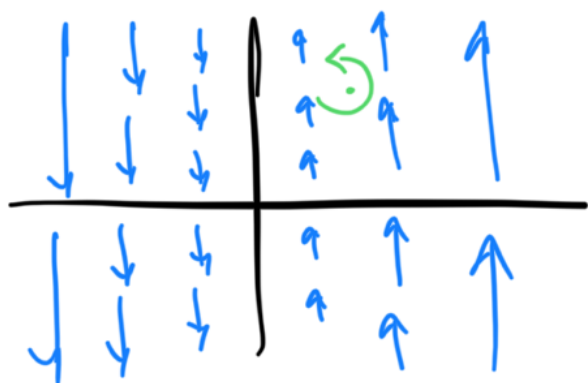


expect $\nabla \cdot \vec{F} = 0$.

$$\frac{d}{dx}(-y) + \frac{d}{dy}(x) = 0.$$

Just rotating.

3.



$$\frac{d}{dx}(0) + \frac{d}{dy}(x) = 0$$

only expanding in a
single direction. Kinda like
how the area of a line is 0.

4. Similar to 2. No expansion/contraction.

Calculation on your own.

Green's Theorem

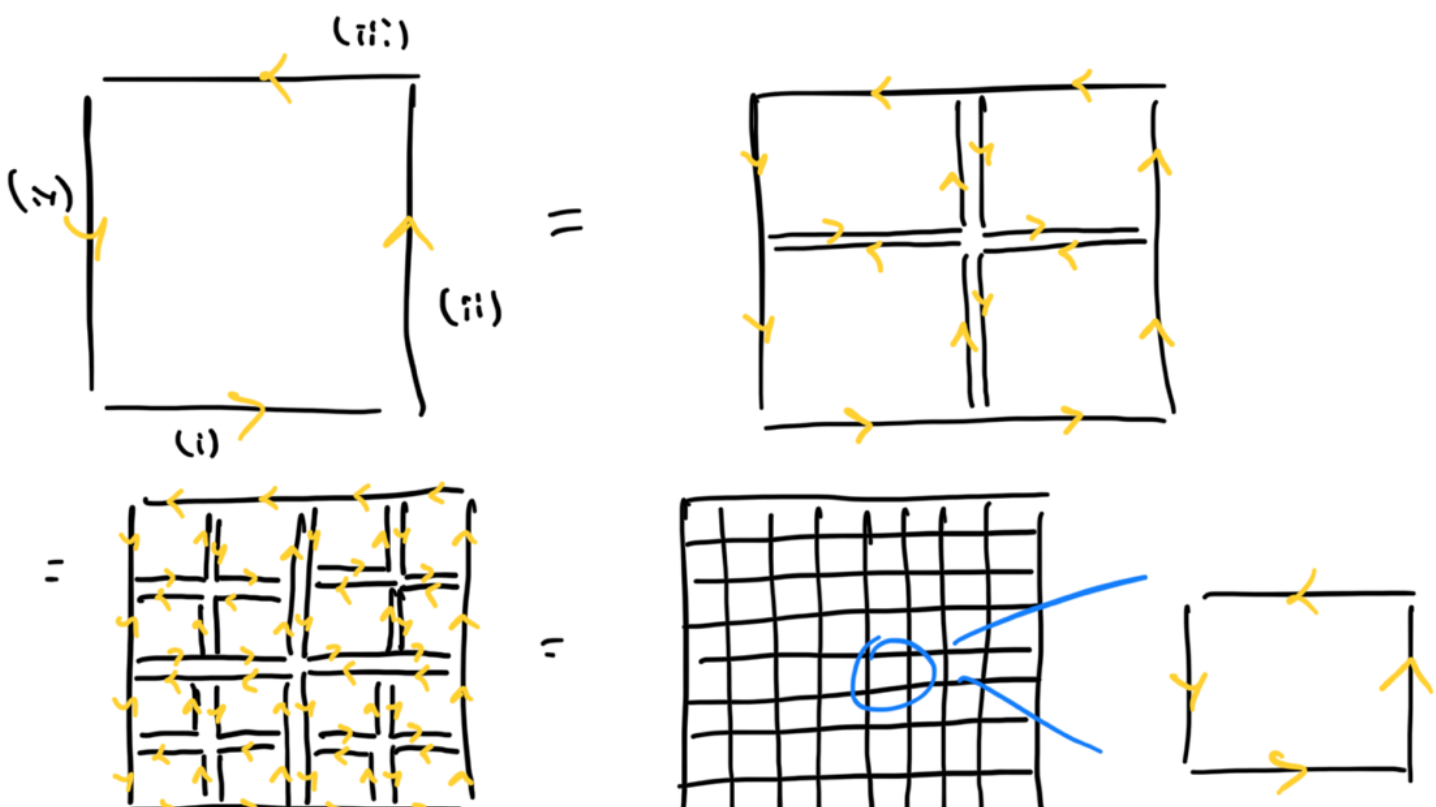
let γ be a simple closed curve positively oriented (counterclockwise). let $\vec{F} = M\hat{i} + N\hat{j}$ and $\vec{T}$ and $\vec{n}$ denote unit tangent / outward unit normal to γ . let R denote inside of γ . Then

$$\begin{aligned} \oint_{\gamma} \vec{F} \cdot \vec{T} \, ds &= \oint_{\gamma} M \, dx + N \, dy = \iint_R (\underbrace{\nabla \times \vec{F}}_{\text{curl}}) \, dA \\ &= \iint_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) \, dA \quad \text{version 1} \end{aligned}$$

Also ..

$$\begin{aligned} \oint_{\gamma} \vec{F} \cdot \vec{n} \, ds &= \oint_{\gamma} M \, dy - N \, dx = \iint_R (\underbrace{\nabla \cdot \vec{F}}_{\text{divergence}}) \, dA \\ &= \iint_R \left(\frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} \right) \, dA \quad \text{version 2} \end{aligned}$$

Why $\oint_{\gamma} \vec{F} \cdot \vec{T} \, ds = \iint_R (\nabla \times \vec{F}) \, dA$?

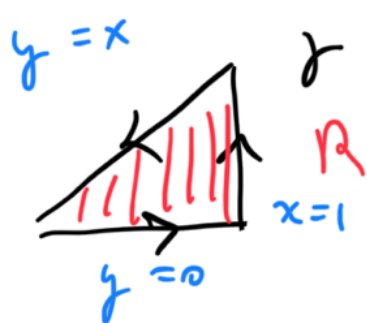


$$\begin{aligned}
 \text{So } (i) + (ii) + (iii) + (iv) &= \sum_1^4 \text{circulation of all squares} \\
 &= \sum_1^4 \frac{\text{circulation of } \Omega}{\text{area of } \Omega} \cdot \boxed{\text{area}} \rightarrow 0 \\
 \oint \vec{F} \cdot \vec{T} ds &\rightarrow \iint_R \nabla \times \vec{F} dA
 \end{aligned}$$

How you get Version 2 from Version 1 is a simple trick. Think about it! (Hint: Choose the appropriate vector field)

ex: Evaluate $\int_{\gamma} xy dx + \frac{1}{2}(x^2 + y^2) dy$

where γ is the triangle counterclockwise with vertices at $(0,0)$, $(1,0)$, $(1,1)$.



$$\begin{aligned}
 &xy dx + \frac{1}{2}(x^2 + y^2) dy \\
 &= (xy, \frac{1}{2}(x^2 + y^2)) \cdot d\vec{r} \\
 \vec{F} &= (xy, \frac{1}{2}(x^2 + y^2)) \\
 &= (M, N)
 \end{aligned}$$

So by Green's theorem...

$$I = \iint_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dA = \iint_R (x - x) dA = 0$$

(However, this is no surprise bc

$xy dx + \frac{1}{2}(x^2 + y^2) dy$ is an exact diff form on simply connected domain!)

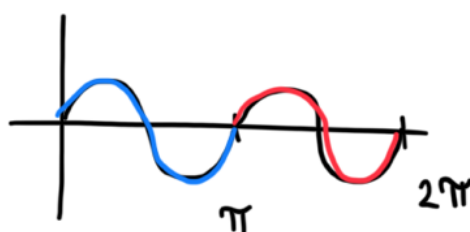
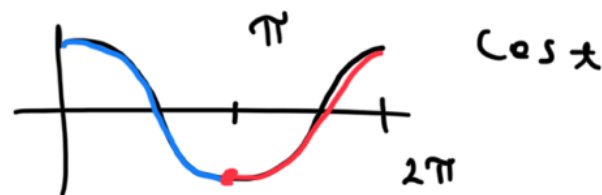
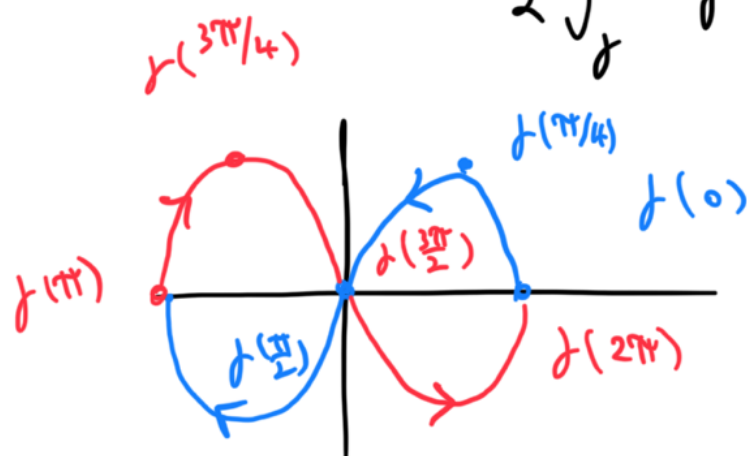
ex: Calculate the area of the region bounded
by $x(t) = \cos(t)$ $y = \sin(2t)$ for $0 \leq t \leq 2\pi$.

Trick: $\text{Area of } R = \iint_R 1 \, dA = \iint_R \frac{1}{2} + \frac{1}{2} \, dA$

$$\frac{dN}{dx} = \frac{1}{2} \quad \frac{dM}{dy} = -\frac{1}{2} \quad \text{so} \quad \frac{dN}{dx} - \frac{dM}{dy} = 1$$

$M = -y/2$, $N = x/2$ then Green's theorem says

$$\text{Area} = \frac{1}{2} \oint_{\gamma} x - y \, dx + x \, dy //$$



$$\text{Area} = 2 (\text{left loop}) = 2 \oint^{\text{opp!}} -y \, dx + x \, dy$$

$$\text{Area left loop} = \oint_{\gamma} y \, dx - x \, dy$$

$$dx = -\sin(t) \, dt$$

$$dy = 2 \cos(2t) \, dt$$

$$\begin{aligned} & \int_{\pi/2}^{3\pi/2} \sin(2t) (-\sin(t)) \, dt \\ & - \cos(t) (2 \cos(2t)) \, dt \\ & = 8/3 \end{aligned}$$

$$\text{So total area} = 16/3 //$$

Word of warning: Need $\vec{F}$ to be 'nice' on
interior of γ to apply Green's theorem. So

be sure to double check it has derivatives and stuff on $\mathbb{R}$.

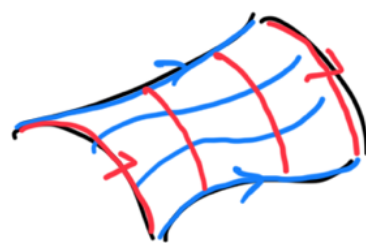
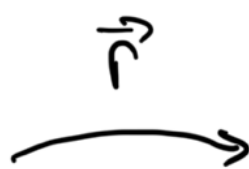
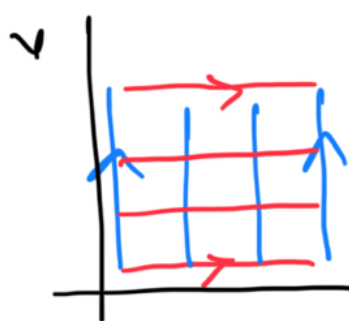
16.5: Surfaces and Area

a curve is a map from $\mathbb{R} \xrightarrow{\gamma} \mathbb{R}^2$ or $\mathbb{R}^3$



one-dimensional

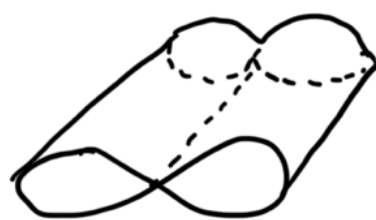
a surface is a map from $\mathbb{R}^2 \xrightarrow{\vec{r}} \mathbb{R}^3$



$$\vec{r}(u,v) = f(u,v)\hat{i} + g(u,v)\hat{j} + h(u,v)\hat{k}$$

We don't want our surface to self intersect.

so none of



← bad.

$$\text{so } \vec{r}(u,v) \neq \vec{r}(u',v') \text{ if } (u,v) \neq (u',v')$$

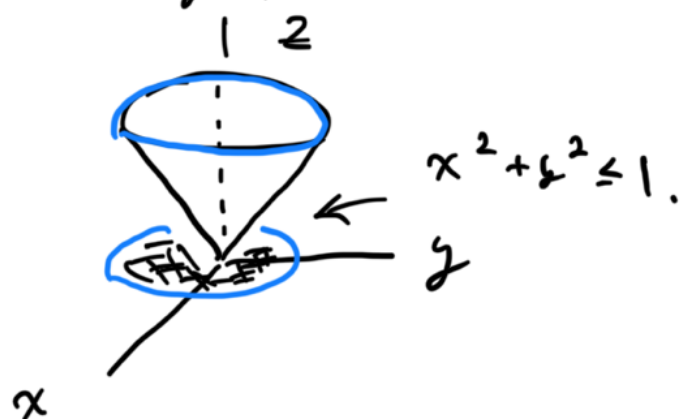
ex: Parametrize the cone

$$x^2 + y^2 = z^2 \text{ where } 0 \leq z \leq 1.$$

$$\text{... solve for } z = \sqrt{x^2 + y^2}$$

One way is to write

so $\vec{r}(x, y) = (x, y, \sqrt{x^2 + y^2})$ where $x^2 + y^2 \leq 1$.



another is $\vec{r}(r, \theta) = (r \cos \theta, r \sin \theta, r)$

bc $x^2 + y^2 = z^2$ so $r^2 = z^2 \sim r = z$

and $(r \cos \theta, r \sin \theta)$ gives you circle.

ex: Parametrize the sphere $x^2 + y^2 + z^2 = a^2$

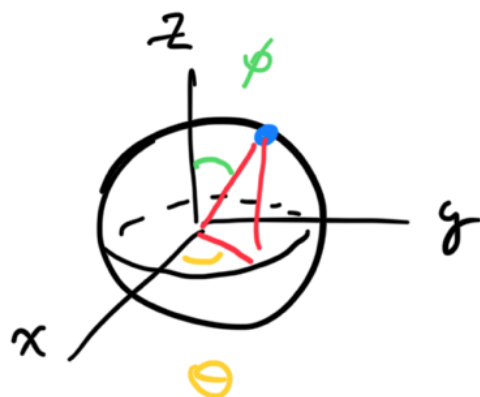
where $a > 0$. (spherical co-ordinates

give this to us). $\rho = a$

Recall $x = \rho \sin \phi \cos \theta$

$y = \rho \sin \phi \sin \theta$

$z = \rho \cos \phi$



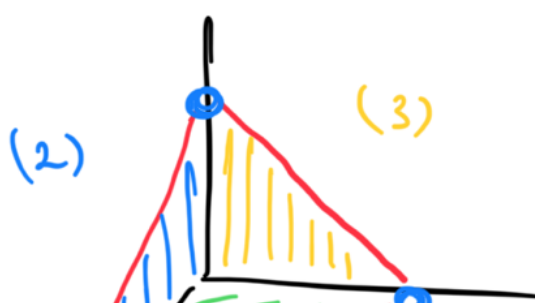
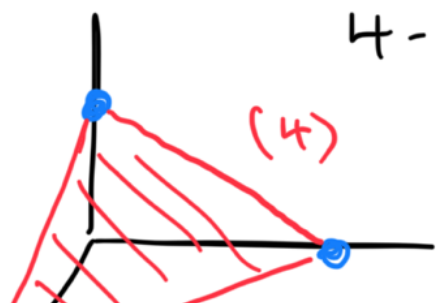
so $\vec{r}(\theta, \phi) = (a \sin \phi \cos \theta, a \sin \phi \sin \theta, a \cos \phi)$

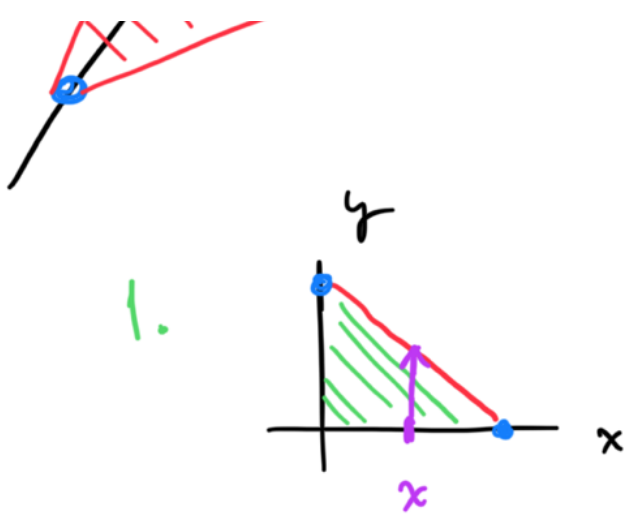
where $0 \leq \theta \leq 2\pi$ and $0 \leq \phi \leq \pi$.

ex: Parametrize tetrahedron with vertices at

$(0, 0, 0), (1, 0, 0), (0, 1, 0), (0, 0, 1)$.

4-pieces.



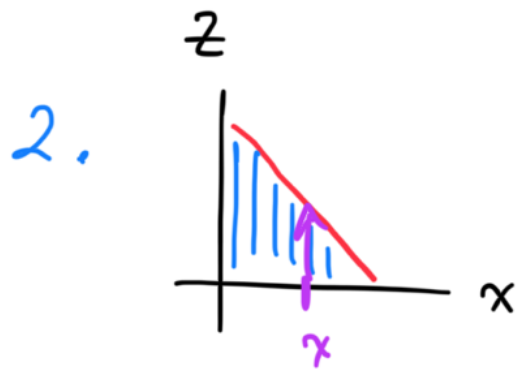


$$\vec{r}(u, v) = (u, v(g))$$

$$0 \leq u \leq 1 \quad = (u, v(1-u))$$

$$0 \leq v \leq 1$$

$$\vec{r}(u, v) = (u, v(1-u), 0) \text{ in } \mathbb{R}^3$$



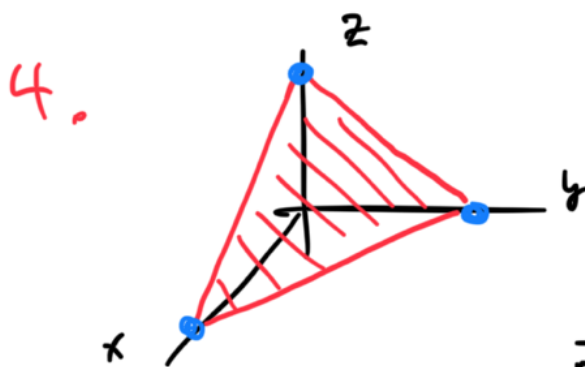
$$\vec{r}(u, v) = (u, v, z)$$

$$= (u, v(1-u))$$

$$\vec{r}(u, v) = (u, 0, v(1-u))$$



$$\vec{r}(u, v) = (0, u, v(1-u))$$



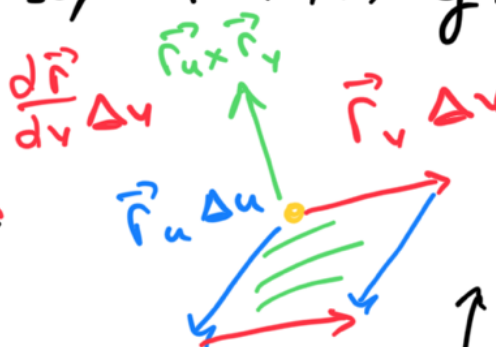
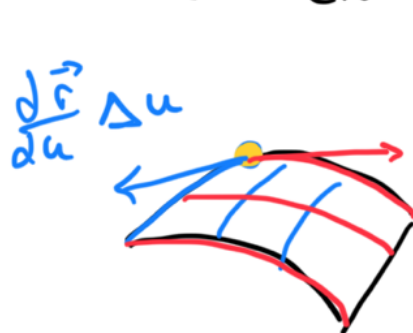
Just use (1) then add z.

$$x + y + z = 1 \text{ so}$$

$$z = 1 - x - y$$

$$\vec{r}(u, v) = (u, v(1-u), 1-u-v(1-u))$$

Surface area: let's say $\vec{r}(u, v)$ gives a surface.



$$area = |\vec{r}_u \times \vec{r}_v| \Delta u \Delta v$$

outward pointing normal.

add all these,

$$\text{So get Area} = \iint |\vec{r}_u \times \vec{r}_v| dA$$

R'

ex: A sphere $x^2 + y^2 + z^2 = a^2$

$$\text{then } \vec{r}(\theta, \phi) = (a \sin \phi \cos \theta, a \sin \phi \sin \theta, a \cos \phi)$$

$$\text{so } \frac{d\vec{r}}{d\theta} = (-a \sin \phi \sin \theta, a \sin \phi \cos \theta, 0)$$

$$\frac{d\vec{r}}{d\phi} = (a \cos \phi \cos \theta, a \cos \phi \sin \theta, -a \sin \phi)$$

$$\text{so } \vec{r}_\theta \times \vec{r}_\phi = (-a^2 \cos \theta \sin^2 \phi, -a^2 \sin^2 \phi \sin \theta, -a^2 \cos \phi \sin \phi)$$

$$\text{so } |\vec{r}_\theta \times \vec{r}_\phi| = a^2 |\sin \phi| \text{ thus,}$$

$$\begin{aligned} \text{Area} &= \iint_R a^2 |\sin \phi| dA = \int_{\theta=0}^{\theta=2\pi} \int_{\phi=0}^{\phi=\pi} a^2 \sin \phi d\phi d\theta \\ &= 4\pi a^2 \end{aligned}$$

ex: Calculate the surface area of the surface $z = x^2 - y^2$ defined on $x^2 + y^2 \leq 1$



$$\vec{s}(r, \theta) = (r \cos \theta, r \sin \theta, (r \cos \theta)^2 - (r \sin \theta)^2)$$

$$\text{so } \frac{d\vec{s}}{dr} = (\cos \theta, \sin \theta, 2r \cos(2\theta))$$

$$\frac{d\vec{s}}{d\theta} = (-r \sin \theta, r \cos \theta, -4r^2 \cos \theta \sin \theta)$$

$$\vec{S}_r \times \vec{S}_\theta = (-2r^2 \cos \theta, 2r^2 \sin \theta, r) \text{ so}$$

$$|\vec{S}_r \times \vec{S}_\theta| = \sqrt{r^2 + 4r^4}$$

$$\begin{aligned} \iint_B \sqrt{r^2 + 4r^4} dA &= \int_{\theta=0}^{\theta=2\pi} \int_{r=0}^{r=1} r \sqrt{1+4r^2} dr d\theta \\ &= \frac{\pi}{6} (5\sqrt{5} - 1) \end{aligned}$$

Sometimes surfaces are defined implicitly, e.g.

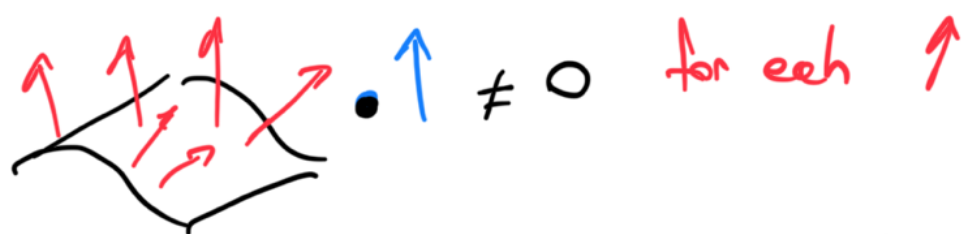
$$F(x, y, z) = c \text{ for some constant } c.$$

$$\text{e.g. } x^2 + y^2 - z^3 = 1$$



idea is assume $\nabla \vec{F}(x, y, z) \neq \vec{0}$ and also

$$\nabla \vec{F}(x, y, z) \cdot \hat{k} \neq 0 \text{ with a region.}$$



then one can write $\vec{r}(u, v) = u \hat{i} + v \hat{j} + h(u, v) \hat{k}$

for some function $h(u, v)$. (Implicit function theorem).

$$\begin{aligned} \text{then } \vec{r}_u &= (1, 0, \frac{\partial h}{\partial u}) & \text{so } \vec{r}_u \times \vec{r}_v &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 0 & h_u \\ 0 & 1 & h_v \end{vmatrix} \\ \vec{r}_v &= (0, 1, \frac{\partial h}{\partial v}) & & = (\quad , \quad , \quad) \end{aligned}$$

$$(-n_u, -n_v, 1)$$

However, $F(x, y, z) = c$ and around small region

$$\bar{F}(u, v, h(u, v)) = 0 \text{ so}$$

$$\frac{d\bar{F}}{dx} \cdot \frac{dx}{du} + \frac{d\bar{F}}{dy} \cdot \frac{dy}{du} + \frac{d\bar{F}}{dz} \frac{dz}{du} = 0$$

$\begin{matrix} \text{"} \\ 1 \end{matrix}$
 $\begin{matrix} \text{"} \\ 0 \end{matrix}$
 $\begin{matrix} \text{"} \\ \frac{dh}{du} \end{matrix}$
so

$$\frac{dh}{du} = -\frac{d\bar{F}/dx}{d\bar{F}/dz} \quad \text{Similarly,}$$

$$\frac{d\bar{F}}{dx} \frac{dx}{dv} + \frac{d\bar{F}}{dy} \frac{dy}{dv} + \frac{d\bar{F}}{dz} \frac{dz}{dv} = 0$$

$\begin{matrix} \text{"} \\ 0 \end{matrix}$
 $\begin{matrix} \text{"} \\ 1 \end{matrix}$
 $\begin{matrix} \text{"} \\ \frac{dh}{dv} \end{matrix}$
so

$$\frac{dh}{dv} = -\frac{d\bar{F}/dy}{d\bar{F}/dz} \quad \text{so}$$

$$\begin{aligned} \vec{r}_u \times \vec{r}_v &= (+F_x/F_z, +F_y/F_z, 1) \\ &= \nabla \bar{F} / F_z = \nabla \bar{F} / (\nabla \bar{F} \cdot \hat{z}) \end{aligned}$$

$$\text{So } SA = \iint_R \nabla \bar{F} / (\nabla \bar{F} \cdot \hat{z}) dA \quad \text{In fact, ...}$$

thm: let $F(x, y, z) = c$ over a region R parallel to xy -plane. Then

$$SA = \iint_R \frac{|\nabla \bar{F}|}{|\nabla \bar{F} \cdot \hat{z}|} dA \quad \text{provided } \nabla \bar{F} \cdot \hat{z} \neq 0 \text{ on } R.$$

Moreover, we also have

$$SA = \iint_R \frac{|\nabla \bar{F}|}{|\nabla \bar{F} \cdot \hat{x}|} dA \quad \text{provided } \nabla \bar{F} \cdot \hat{x} \neq 0 \text{ on } R \text{ in } yz\text{-plane}$$

$$SA = \iint_R \frac{|\nabla \vec{F}|}{|\nabla \vec{F} \cdot \hat{y}|} dA \quad \text{provided } \nabla \vec{F} \cdot \hat{y} \neq 0 \quad \text{on } R \text{ in } xy\text{-plane.}$$

Note in particular, if $z = f(x, y)$ then we have

$$A = \iint_R \sqrt{f_x^2 + f_y^2 + 1} dA$$

$$\text{bc } \nabla \vec{F} = (f_x, f_y, -1)$$

One issue with this is how to evaluate $\nabla \vec{F}$ if you don't know z ! (only works in really nice cases).

ex: Calculate area of cone $x^2 + y^2 = z^2$ bounded by $z \geq 0$ and square centered at $(0,0)$ side length 2.



$$F = x^2 + y^2 - z^2 \quad \text{so}$$

$$\nabla F = (2x, 2y, -2z)$$

$$\nabla F \cdot \hat{z} = -2z \quad \text{so}$$

$$|\nabla F| / |\nabla F \cdot \hat{z}| = \sqrt{4x^2 + 4y^2 + 4z^2} / 2z$$

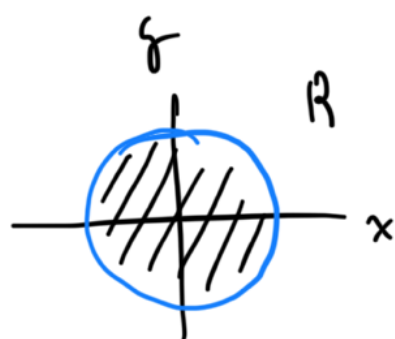
$$= \sqrt{x^2 + y^2 + z^2} / z = \sqrt{x^2 + y^2} / z$$

$$\text{So } = \sqrt{2x^2 + 2y^2} / \sqrt{x^2 + y^2} = \sqrt{2}.$$

$$\text{So } SA = \iint_R \sqrt{2} dA = \sqrt{2} (\text{Area of } \square) = 4\sqrt{2}$$

ex: Calculate surface area of $z = x^2 + y^2$
on region bounded by $0 \leq x^2 + y^2 \leq 1$.

$$SA = \iint_R \sqrt{f_x^2 + f_y^2 + 1} \, dA$$



$$f_x = 2x$$

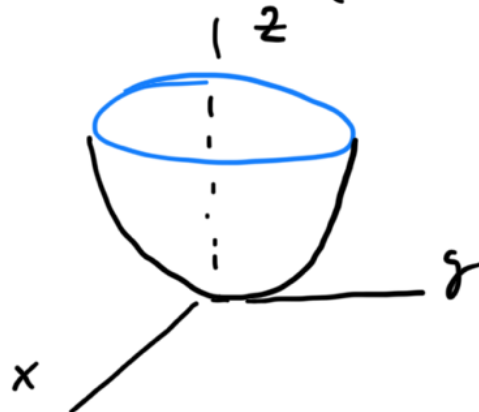
$$f_y = 2y$$

$$\sqrt{(2x)^2 + (2y)^2 + 1} \, dx \, dy$$

$$= \sqrt{4(x^2 + y^2) + 1} \, dx \, dy$$

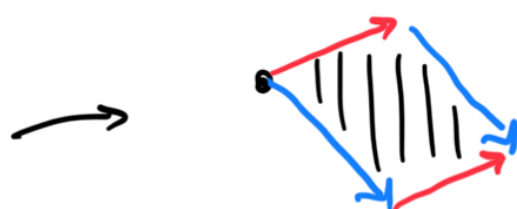
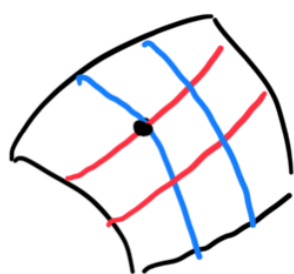
$$= \sqrt{4r^2 + 1} \, r \, dr \, d\theta$$

$$\text{So } SA = \int_{\theta=0}^{\theta=2\pi} \int_{r=0}^{r=1} r \sqrt{4r^2 + 1} \, dr \, d\theta = \frac{\pi}{6} (5\sqrt{5} - 1)$$



16.6: Surface Integrals

Motivated by physical exmple. Say you have surface S with non-uniform density. How to calculate its mass? Or if you need to integrate x -coordinate to find 1st moment about a plane for surface. Point being we need to integrate functions over surfaces.



∴ differential area is denoted by $d\sigma$.

if $\vec{r}(u,v)$ parametrizes S then
 $d\sigma = |\vec{r}_u \times \vec{r}_v| du dv$ like in last section.

Ways to integrate scalar function over surface

1. Have a parametrization $\vec{r}(u,v)$, then

$$\iint_S G d\sigma = \iint_R (G \circ \vec{r})(u,v) |\vec{r}_u \times \vec{r}_v| du dv$$

2. If S is implicitly $F(x,y,z) = c$ and satisfies $\nabla F \cdot \hat{k} \neq 0$ on region R then

$$\iint_S G d\sigma = \iint_R G \frac{|\nabla F|}{|\nabla F \cdot \hat{k}|} dA \quad \left(\begin{array}{c} \text{similar statement for} \\ \uparrow, \hat{j} \end{array} \right)$$

3. If S given explicitly as $z = f(x, y)$ then

$$\iint_S G \, d\sigma = \iint_R G(x, y, f(x, y)) \sqrt{f_x^2 + f_y^2 + 1} \, dA$$

ex: let S be a cube below. Assume its mass is given by $\rho(x, y, z) = x^2 y z$. Calculate its center of mass.

M_{yz} = 1st moment about yz -plane

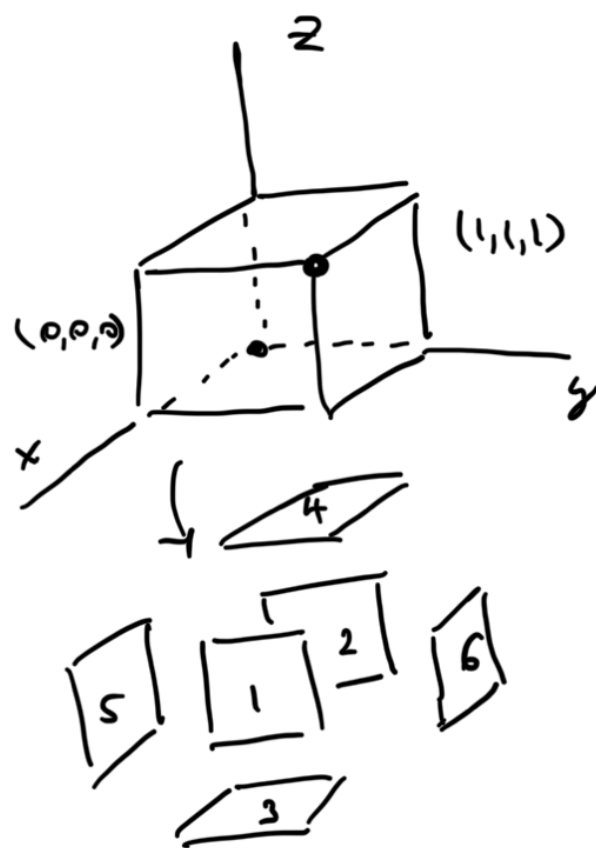
$$= \iint_S x \rho \, d\sigma$$

M_{xz} = 1st moment about xz -plane

$$= \iint_S y \rho \, d\sigma$$

M_{xy} = 1st moment about xy -plane

$$= \iint_S z \rho \, d\sigma$$



$$M = \iint_S \rho \, d\sigma = \iint_1 \rho \, d\sigma + \iint_2 \rho \, d\sigma + \dots + \iint_6 \rho \, d\sigma$$

well 3 of them are zero, namely 5, 3, 2

because on 5, 3, 2, $\rho \equiv 0$ as either x, y , or $z = 0$

on them. So $\rho = x^2 y z$

$$M = \iint \rho \, d\sigma + \iint \rho \, d\sigma + \iint \rho \, d\sigma$$

$$\rho \text{ on } 1 = 1^2 y z = y z$$

$$\rho \text{ on } 4 = x^2 y \cdot 1 = x^2 y$$

$$\rho \text{ on } 6 = x^2 \cdot 1 \cdot z = x^2 z$$

$$\begin{aligned} \text{So } M &= \frac{1}{4} + \frac{1}{6} + \frac{1}{6} \\ &= 7/12 \text{ kg} \end{aligned}$$

$$\iint_1 \rho d\sigma = \int_{y=0}^{y=1} \int_{z=0}^{z=1} y z dz dy$$

$$= 1/4$$

$$\iint_4 \rho d\sigma = \int_{x=0}^{x=1} \int_{y=0}^{y=1} x^2 y dy dx$$

$$= 1/6$$

$$\iint_6 \rho d\sigma = \int_{x=0}^{x=1} \int_{z=0}^{z=1} x^2 z dz dx$$

$$= 1/6$$

M_{yz} very similar calculation.

$$M_{yz} = \iiint_S x \rho d\sigma = \iint_1 x \rho d\sigma + \iint_4 x \rho d\sigma + \iint_6 x \rho d\sigma$$

$$= \frac{1}{4} + \frac{1}{8} + \frac{1}{8} = \frac{1}{2} \text{ m kg}$$

$$M_{xz} = \iiint_S y \rho d\sigma = \iint_1 y \rho d\sigma + \iint_4 y \rho d\sigma + \iint_6 y \rho d\sigma$$

$$= \frac{1}{6} + \frac{1}{9} + \frac{1}{6} = 4/9 \text{ m kg}$$

$$M_{xy} = \iiint_S z \rho d\sigma = \iint_1 z \rho d\sigma + \iint_4 z \rho d\sigma + \iint_6 z \rho d\sigma$$

$$= \frac{1}{6} + \frac{1}{6} + \frac{1}{9} = 4/9 \text{ m kg}$$

$$\text{So } (\bar{x}, \bar{y}, \bar{z}) = \left(\frac{1}{2}, \frac{4}{9}, \frac{4}{9} \right) / \left(\frac{7}{12} \right) = \left(\frac{6}{7} \text{ m}, \frac{16}{21} \text{ m}, \frac{16}{21} \text{ m} \right)$$

ex: let S be upper hemisphere of a sphere of radius a

whose density is $\rho(x, y, z) = z$

Calculate the various moments of inertia of S .

$$I_x = \iiint_S (y^2 + z^2) \rho \, d\sigma \quad I_y = \iiint_S (x^2 + z^2) \rho \, d\sigma \quad I_z = \iiint_S (x^2 + y^2) \rho \, d\sigma$$



$$x^2 + y^2 + z^2 = a^2$$

$$\vec{S}(\phi, \theta) = (a \sin \phi \cos \theta, a \sin \phi \sin \theta, a \cos \phi)$$

where $0 \leq \theta \leq 2\pi, 0 \leq \phi \leq \pi/2$.

$$\frac{\partial \vec{S}}{\partial \phi} = (a \cos \phi \cos \theta, a \cos \phi \sin \theta, -a \sin \phi)$$

$$\frac{\partial \vec{S}}{\partial \theta} = (-a \sin \phi \sin \theta, a \sin \phi \cos \theta, 0)$$

$$\vec{S}_\phi \times \vec{S}_\theta = (a^2 \cos \theta \sin^2 \phi, a^2 \sin^2 \phi \sin \theta, a^2 \cos \phi \sin \phi)$$

$$|\vec{S}_\phi \times \vec{S}_\theta| = a^2 |\sin \phi|$$

so $d\sigma = a^2 \sin \phi \, d\phi \, d\theta$ (bc $\sin \phi \geq 0$ for $0 \leq \phi \leq \pi$)

$$\begin{aligned} \text{So } \theta=2\pi \quad \phi=\pi/2 \\ I_x &= \int_{\theta=0}^{2\pi} \int_{\phi=0}^{\pi/2} \left(\frac{(a \sin \phi \sin \theta)^2 + (a \cos \phi)^2}{y^2 + z^2} \right) \frac{(a \cos \phi)}{z} (a^2 \sin \phi) \, d\phi \, d\theta \\ &= \frac{3}{4} a^5 \pi / 4 \end{aligned}$$

$$\begin{aligned} \theta=2\pi \quad \phi=\pi/2 \\ I_y &= \int_{\theta=0}^{2\pi} \int_{\phi=0}^{\pi/2} \left(\frac{(a \sin \phi \cos \theta)^2 + (a \cos \phi)^2}{x^2 + z^2} \right) \frac{(a \cos \phi)}{z} (a^2 \sin \phi) \, d\phi \, d\theta \\ &= \frac{3}{4} a^5 \pi / 4 \end{aligned}$$

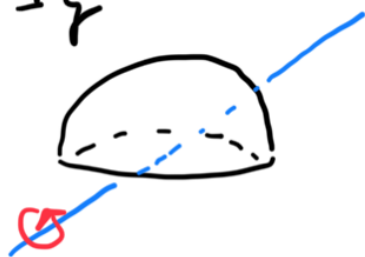
$$\begin{aligned} \theta=2\pi \quad \phi=\pi/2 \\ I_z &= \int_{\theta=0}^{2\pi} \int_{\phi=0}^{\pi/2} \left(\frac{(a \sin \phi \cos \theta)^2 + (a \sin \phi \sin \theta)^2}{x^2 + y^2} \right) (a \cos \phi) (a^2 \sin \phi) \, d\phi \, d\theta \end{aligned}$$

$$= a^5 \pi / 2$$

not $I_z \neq I_x$ and I_y

$$\text{and } I_x = I_y$$

I_x results to



I_y results to

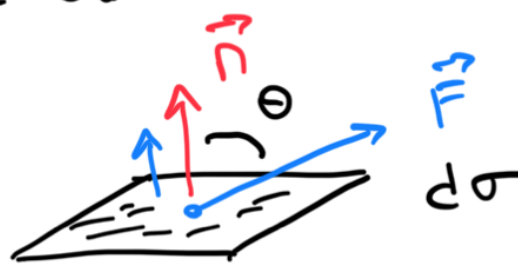
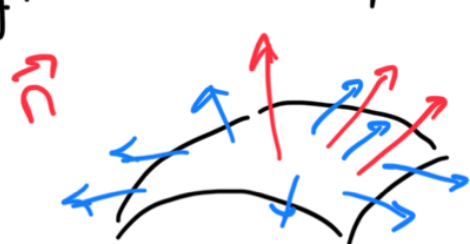


I_z results to



Flux Integrals

Imagine a velocity vector field over a surface



$$\text{proj}_{\vec{n}} \vec{F} = \vec{F} \cdot \vec{n}$$

How much of $\vec{F}$ goes through $d\sigma$

$$= (\vec{F} \cdot \vec{n}) d\sigma$$

So define

Flux of $\vec{F}$
through S in
direction of $\vec{n}$

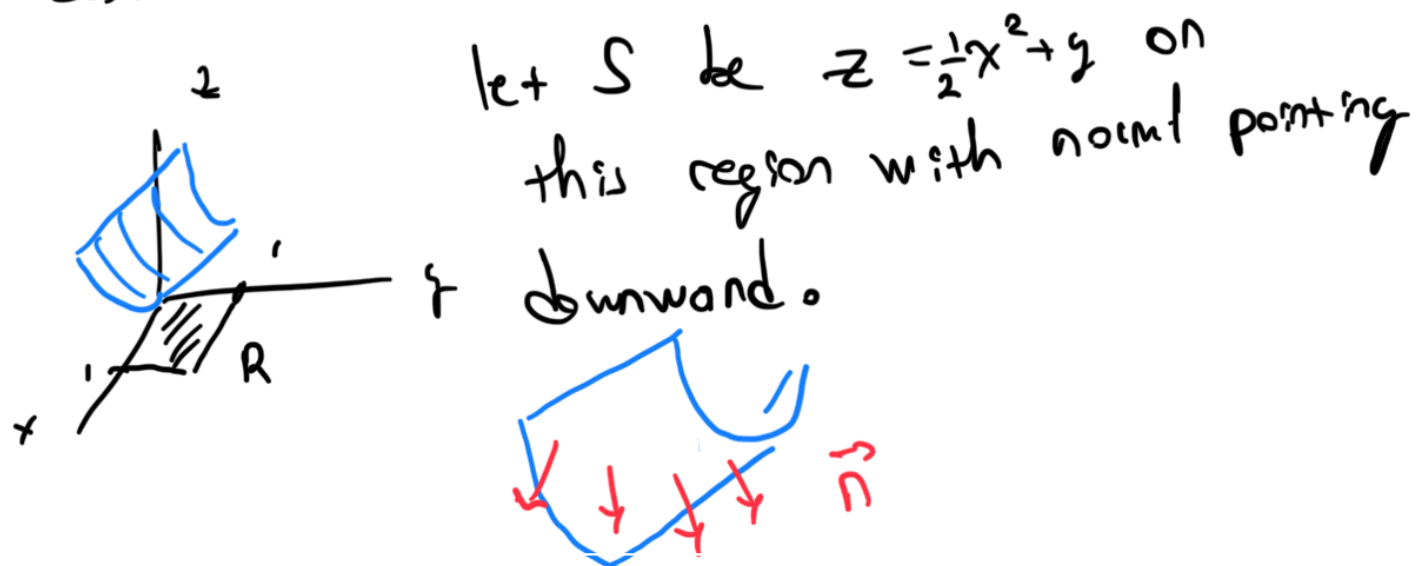
$$= \iint_S (\vec{F} \cdot \vec{n}) d\sigma //$$

(not requires S to be oriented
choice of a normal direction)

$$= \iint_S (1 - x^2 - y^2) d\sigma$$

Ex: Consider the function $z = \frac{1}{2}x^2 + y$

defined on the square $0 \leq x, y \leq 1$.



Let S be $z = \frac{1}{2}x^2 + y$ on

this region with normal pointing downward.

Let $\vec{F} = (y, x, z) = y\hat{i} + x\hat{j} + z\hat{k}$. Calculate
flux of $\vec{F}$ over S in direction of $\vec{n}$.

$$\text{let } g(x, y, z) = \frac{1}{2}x^2 + y - z \text{ so } \nabla g = (x, 1, -1)$$

$$|\nabla g| = \sqrt{x^2 + 2}$$

$$|\nabla g \cdot \hat{k}| = 1$$

$$\text{so } d\sigma = \sqrt{x^2 + 2} dA$$

$$\vec{n} = \frac{\nabla g}{|\nabla g|} = \frac{(x, 1, -1)}{\sqrt{x^2 + 2}} \text{ note } \vec{n} \text{ has negative } z \text{ so it's pointing down.}$$

$$\text{So } \vec{F} = (y, x, \frac{1}{2}x^2 + y) \text{ on } S$$

$$\begin{aligned} \vec{F} \cdot \vec{n} d\sigma &= \vec{F} \cdot \frac{\nabla g}{|\nabla g|} \frac{|\nabla g|}{|\nabla g \cdot \hat{k}|} dA \\ &= \vec{F} \cdot \frac{\nabla g}{|\nabla g \cdot \hat{k}|} dA \end{aligned}$$

$$\text{In general, } \iint_S \vec{F} \cdot \vec{n} d\sigma = \iint_R \frac{\vec{F} \cdot \nabla g}{|\nabla g \cdot \hat{k}|} dA \quad (\text{nice to remember})$$

$$= \int_{x=0}^{x=1} \int_{y=0}^{y=1} (xy + x - \frac{1}{2}x^2 - y) dx dy = 1/12$$

ex: let S be surface $x^2 + y^2 = 4$ between $z=0$ and $z=1$, with normal pointing away from z -axis. let $\vec{F} = (x+y, x-y, x^2)$. Calculate flux of $\vec{F}$ through S in direction of $\vec{n}$.

Parametrize S via $\vec{r}(\theta, h) = (2\cos\theta, 2\sin\theta, h)$ where $0 \leq \theta \leq 2\pi$ and $0 \leq h \leq 1$.



Recall $\vec{r}_u \times \vec{r}_v$ normal to surface so
 $\vec{n} = \frac{\vec{r}_u \times \vec{r}_v}{|\vec{r}_u \times \vec{r}_v|}$ (up to a sign) and

$$d\sigma = |\vec{r}_u \times \vec{r}_v| dA$$

$$\iint_S (\vec{F} \cdot \vec{n}) d\sigma = \iint_R \vec{F} \cdot \frac{\vec{r}_u \times \vec{r}_v}{|\vec{r}_u \times \vec{r}_v|} |\vec{r}_u \times \vec{r}_v| dA$$

$$= \iint_R \vec{F} \cdot (\vec{r}_u \times \vec{r}_v) dA //$$

another helpful one to know.

$$\text{So } \vec{F}(\theta, h) = (2\cos\theta + 2\sin\theta, 2\cos\theta - 2\sin\theta, (2\cos\theta)^2)$$

$$\vec{r}_\theta = (-2\sin\theta, 2\cos\theta, 0) \quad \vec{r}_h = (0, 0, 1)$$

$$\text{so } \vec{r}_\theta \times \vec{r}_h = (2\cos\theta, 2\sin\theta, 0)$$

the obvious choice anyway!

but that was

$$\text{So } \vec{F} \cdot (\vec{r}_\theta \times \vec{r}_h) = 4 (\cos(2\theta) + \sin(2\theta))$$

$h=1 \quad \theta=2\pi$

$$\text{thus } \oint_S (\vec{F} \cdot \vec{n}) d\sigma = \int_{h=0}^1 \int_{\theta=0}^{2\pi} 4 (\cos(2\theta) + \sin(2\theta)) d\theta dh = 0!$$

Stokes' theorem 16.7

Recall for a vector field $\vec{F} = (M, N, P)$

We have

$$\nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ M & N & P \end{vmatrix} = \hat{i} \left(\frac{\partial P}{\partial y} - \frac{\partial N}{\partial z} \right) - \hat{j} \left(\frac{\partial P}{\partial x} - \frac{\partial M}{\partial z} \right) + \hat{k} \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right)$$

What is it? It's kind of like a tool that knows how much spinning is happening in a region.

For example

$(\nabla \times \vec{F})(a, b, c) \cdot \hat{n} \stackrel{''}{=} \text{How much particle circulates in } \vec{F} \text{ in region } \perp \text{ to } \hat{n} \text{ at point } (a, b, c) \text{ relative to induced orientation of } \hat{n}.$

(right hand rule)



$(\nabla \times \vec{F}) \cdot \hat{n} > 0$ means spinning with red

$(\nabla \times \vec{F}) \cdot \hat{n} < 0$ means spinning against

$$(\nabla \times \vec{F}) \cdot \hat{n} = 0 \quad \text{red}$$

$$(\nabla \times \vec{F}) \cdot \hat{n} = 0 \quad \text{no spin}$$

Recall Green's theorem says that for a planar region A with boundary $\vec{r}$,

$$\text{we have } \oint_{\vec{r}} \vec{F} \cdot d\vec{r} = \iint_A \left(\frac{dN}{dx} - \frac{dM}{dy} \right) dA$$

$$= \iint_A (\nabla \vec{F} \cdot \hat{k}) dA$$


Stokes' theorem generalizes this to non-planar regions.

$$\iint_S (\nabla \times \vec{F}) \cdot \hat{n} d\sigma = \oint_{\vec{r}} \vec{F} \cdot d\vec{r}$$



ex: let $\vec{F} = (xy, y, z)$ and S be surface defined by hemisphere $x^2 + y^2 + z^2 = 1$ and $z \geq 0$. let $\vec{n}$ point upward.

Verify Stokes' theorem for this example.

$$(i). \quad \nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ xy & y & z \end{vmatrix} = (0, 0, -x) = -x \hat{k}$$

$$g(x, y, z) = x^2 + y^2 + z^2 - 1$$

$$\nabla g = (2x, 2y, 2z) \quad \text{so } \vec{n} = \frac{\nabla g}{|\nabla g|} = \frac{2(x, y, z)}{2\sqrt{x^2 + y^2 + z^2}}$$

$$\nabla g \cdot \hat{k} = 2z$$

$$= (x, y, z)$$

but again we knew that!

$$d\sigma = \frac{|\nabla g|}{|\nabla g \cdot \hat{k}|} dA = \frac{2\sqrt{x^2+y^2+z^2}}{2z} dA = \frac{1}{z} dA$$

so $(\nabla \times \vec{F}) \cdot \vec{n} = -xz$ and

$$\iint_S (\nabla \times \vec{F}) \cdot \vec{n} d\sigma = \iint_S (-xz) \frac{1}{z} dA = - \iint_S x dA$$

$$= - \int_{\theta=0}^{\theta=2\pi} \int_{\phi=0}^{\phi=\pi/2} (\sin \phi \cos \theta) (1^2 \sin \phi d\phi d\theta)$$

$$= 0$$



$$\oint_{\gamma} \vec{F} \cdot d\vec{r}, \quad \gamma(t) = (\cos t, \sin t, 0)$$

$$d\vec{r} = (-\sin t, \cos t, 0) dt$$

$$(\vec{F} \circ \gamma)(t) = (\cos t \sin t, \sin t, 0)$$

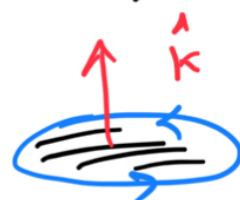
$$\text{so } \oint_{\gamma} \vec{F} \cdot d\vec{r} = \int_{t=0}^{t=2\pi} (-\cos t \sin^2 t + \cos t \sin t) dt$$

$$= 0$$

$$\text{So } \iint_S (\nabla \times \vec{F}) \cdot \vec{n} d\sigma = \oint_{\gamma} \vec{F} \cdot d\vec{r}$$

Also now, let's change S to unit disk in xy -plane.

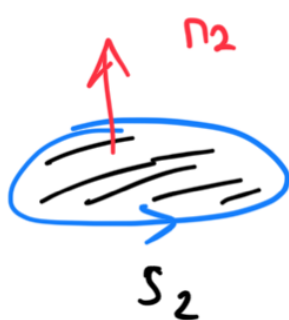
then $\hat{n} = \hat{k}$, $d\sigma = r dr d\theta$



$$(\nabla \times \vec{F}) \cdot \hat{n} = (0, 0, -x) \cdot (0, 0, 1) = -x$$

$$\begin{aligned} \text{then } \iint_S (\nabla \times \vec{F}) \cdot \hat{n} \, d\sigma &= \iint_R (-x) \, dA \\ &= \int_{\theta=0}^{\theta=2\pi} \int_{r=0}^{r=1} (-r \cos \theta) r \, dr \, d\theta = 0 \end{aligned}$$

Observation: A bunch of surfaces bound unit circle. Here are some,



Stokes' theorem says $\iint_{S_1} (\nabla \times \vec{F}) \cdot n_1 \, d\sigma_1$

more of the
story, choose
easier one!

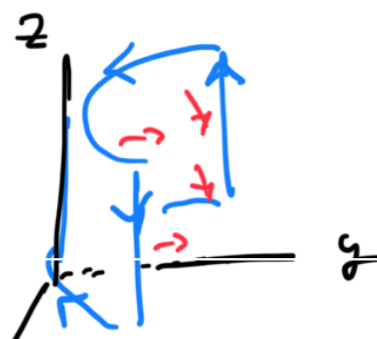
$$= \iint_{S_2} (\nabla \times \vec{F}) \cdot n_2 \, d\sigma_2$$

$$= \iint_{S_3} (\nabla \times \vec{F}) \cdot n_3 \, d\sigma_3$$

ex: Consider surface $\vec{r}(u, v) = (u, u^2, v)$

where $-1 \leq u \leq 1$ and $0 \leq v \leq \pi/2$ with normal pointing towards +z-axis. Verify Stokes' theorem for

$$\vec{F} = (\sin(z), x, y)$$



$$(i). \quad \vec{r}_u = (1, 2u, 0)$$

$$\vec{r}_v = (0, 0, 1)$$

$$\vec{r}_u \times \vec{r}_v = (2u, -1, 0) \text{ so need}$$

$$\text{to take } \vec{n} = -\vec{r}_u \times \vec{r}_v \text{ so}$$

y - positive.

$$\nabla \times \vec{F} = (1, \cos z, 1) = \hat{i} + \cos z \hat{j} + \hat{k} \text{ so}$$

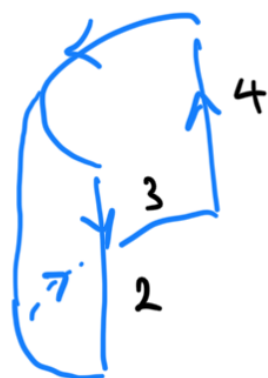
$$-(\nabla \times \vec{F}) \cdot (\vec{r}_u \times \vec{r}_v) = -2u + \cos(v)$$

$$\iint_S (\nabla \times \vec{F}) \cdot \vec{n} \, d\sigma = \iint_R (\nabla \times \vec{F}) \cdot (-\vec{r}_u \times \vec{r}_v) \, dA$$

$$= \int_{v=0}^1 \int_{u=-1}^{\pi/2} (-2u + \cos(u)) \, du \, dv$$

$$= 2$$

(ii).



$$1: \alpha(t) = (t, t^2, \pi/2) \quad -1 \leq t \leq 1$$

$$2: \beta(t) = (1, 1, \pi/2 - t) \quad 0 \leq t \leq \pi/2$$

$$3: \gamma(t) = (1-t, (1-t)^2, 0) \quad 0 \leq t \leq 1$$

$$4: \delta(t) = (-1, 1, t) \quad 0 \leq t \leq \pi/2$$

$$1. \, d\vec{r} = (1, 2t, 0) \, dt$$

$$(\vec{F} \circ \alpha)(t) = (1, t, t^2)$$

$$\oint_C \vec{F} \cdot d\vec{r} = \int_{-1}^1 (1 + 2t^2) \, dt = \frac{10}{3}$$

$$2. \, d\vec{r} = (0, 0, -1) \, dt$$

$$(\vec{F} \circ \beta)(t) = (\cos t, 1, 1)$$

$$\oint_{\partial S} \vec{F} \cdot d\vec{r} = \int_0^{\pi/2} (-1) dx = -\pi/2$$

$$3. d\vec{r} = (-1, -2(1-x), 0) dx$$

$$(\vec{F} \circ \gamma)(x) = (0, (1-x), (1-x)^2)$$

$$\oint_{\partial S} \vec{F} \cdot d\vec{r} = \int_0^2 -2(1-x)^2 dx = -4/3$$

$$4. d\vec{r} = (0, 0, 1) dx$$

$$(\vec{F} \circ \gamma)(x) = (\sin x, -1, x)$$

$$\oint_{\partial S} \vec{F} \cdot d\vec{r} = \int_0^{\pi/2} (x+1) dx = +\pi/2$$

$$\text{so } \oint_{\partial S} \vec{F} \cdot d\vec{r} = \frac{10}{6} - \frac{\pi}{2} - \frac{4}{3} + \frac{\pi}{2} = 2$$

$$\text{so } \iint_S (\nabla \times \vec{F}) \cdot \vec{n} d\sigma = \oint_{\partial S} \vec{F} \cdot d\vec{r}$$

One last bit about Stokes' theorem,

Need to assume $\vec{F}$ and $\nabla \times \vec{F}$ are 'nice' on surface. Theorem is false if $\vec{F}$ is badly

behaved on surface. Also another neat bit

$$\text{is that } (\nabla \times \vec{F}) \cdot \hat{u} \Big|_Q = \lim_{p \rightarrow 0} \frac{\iint_S (\nabla \times \vec{F}) \cdot \vec{u} d\sigma}{\text{Area of small disk about } Q.}$$



$$= \lim_{r \rightarrow 0} \frac{1}{\pi r^2} \iint_S (\nabla \times \vec{F}) \cdot \vec{u} d\sigma$$



$$p \rightarrow 0 \quad \text{if} \quad \frac{Q}{S} \rightarrow 0$$

$$= \lim_{p \rightarrow 0} \frac{1}{\pi p^2} \oint \vec{F} \cdot d\vec{r} = \text{infinitesimal circulation density}$$

Note this means direction of greatest circulation is $\nabla \times \vec{F}$!

Also if let $\vec{F} = \nabla f$ then we have

$$\iint_S (\nabla \times \vec{F}) \cdot \hat{n} d\sigma = \oint_{\partial S} \vec{F} \cdot d\vec{r}$$

$$= \oint_{\partial S} \nabla f \cdot d\vec{r} = 0 \quad \text{by conservative vector field}$$

if true for any surface S

then $\nabla \times \vec{F} = \vec{0}$ (can check by direct calculation too).

But this says

$$\nabla \times (\nabla f) = \vec{0}.$$

Finally if $\nabla \times \vec{F} = \vec{0}$ on a simply connected region S

then $\oint_{\partial S} \vec{F} \cdot d\vec{r} = 0$ where ∂ is boundary of S .

thus on simply connected regions the following are equivalent.

1. $\vec{F}$ conservative on D (path integrals depend only on beginning/end points)

2. $\oint \vec{F} \cdot d\vec{r} = 0$ for any loop γ in D

$$3. \quad \nabla \times \vec{F} = \vec{0} \quad \text{on } D$$

$$4. \quad F = \nabla f \quad \text{on } D$$

16.8: Divergence Theorem

Just like in (2D) given a vector field

$\vec{F} = (M, N, P)$ we associate the scalar

function

$$\operatorname{div} \vec{F} = \nabla \cdot \vec{F} = \frac{dM}{dx} + \frac{dN}{dy} + \frac{dP}{dz}$$

$\nabla \cdot \vec{F}$ is a measure of how much a fluid/gas is expanding/contracting at a point under the vector field $\vec{F}$. If $\operatorname{div} \vec{F} > 0$ expanding
 $\operatorname{div} \vec{F} < 0$ contracting
 $\operatorname{div} \vec{F} = 0$ no flux.

Measured in flux/unit volume so frequently called 'flux density'.

ex: $\vec{F} = (x, y, z)$ $\operatorname{div} \vec{F} = 1 + 1 + 1 > 0$

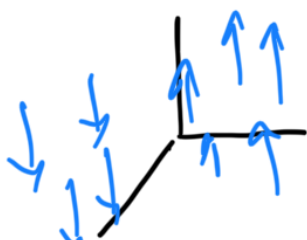


similarly $\vec{F} = (-x, -y, -z)$
then $\operatorname{div} \vec{F} = -3 < 0$

ex: $\vec{F} = (-y, x, 0)$ then $\operatorname{div} \vec{F} = 0$ because
fluid just spinning

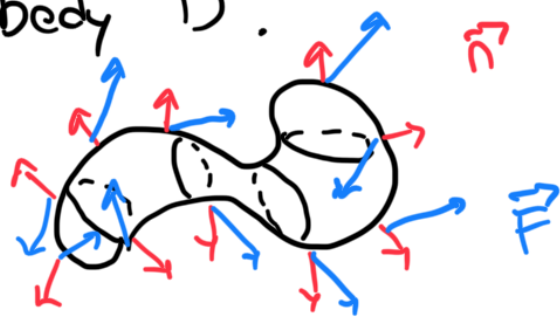


ex: $\vec{F} = (0, 0, z)$ then $\operatorname{div} \vec{F} > 0$ because
stuff moving out



Divergence theorem : let S be a closed oriented

surface. The flux of $\vec{F}$ across S in the direction of outward unit normal $\vec{n}$ equals the integral of the divergence over the body D .



$$\begin{aligned} \text{Flux } \vec{F} \text{ over } S &= \iint_S (\vec{F} \cdot \vec{n}) d\sigma \\ &= \iiint_D (\nabla \cdot \vec{F}) dV \end{aligned}$$

ex: Verify Divergence Theorem for $\vec{F} = (y^2, x^2, 0)$ over the sphere.

$$\iint_S (\vec{F} \cdot \vec{n}) d\sigma : \text{Recall } \iint_S \vec{F} \cdot \vec{n} d\sigma = \iint_R \vec{F} \cdot (\vec{r}_u \times \vec{r}_v) dA$$

for a parametrization $\vec{r}$. let $\vec{r}(\phi, \theta) = \begin{pmatrix} \sin \phi \cos \theta \\ \sin \phi \sin \theta \\ \cos \phi \end{pmatrix}$

$$\text{so that } \vec{r}_\phi \times \vec{r}_\theta = (\cos \theta \sin^2 \phi, \sin \theta \sin^2 \phi, \cos \phi \sin \phi)$$

$$\begin{aligned} \text{then } \vec{F} \cdot (\vec{r}_\phi \times \vec{r}_\theta) &= \cos \phi \sin^3 \phi \cos \theta \sin \theta \\ &\quad + \cos^2(\theta) \sin(\theta) \sin^4 \phi \\ &\quad + \cos \theta \sin^2 \theta \sin^4 \phi \end{aligned}$$

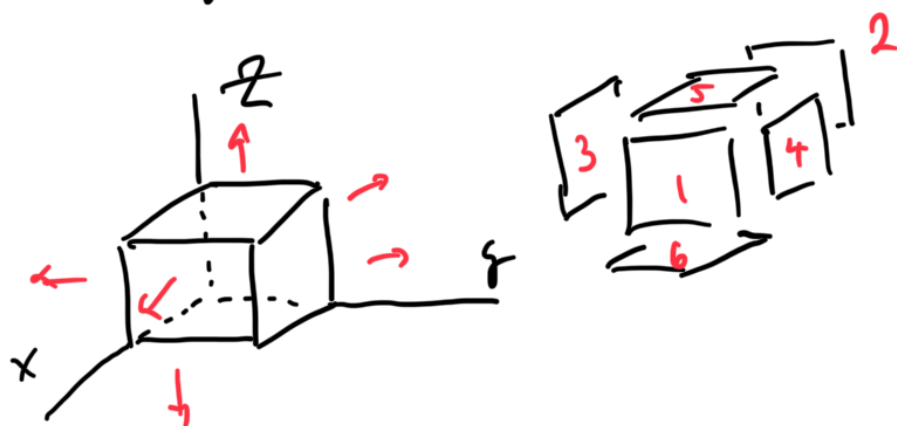
Each blue term integrates to 0 on $0 \leq \theta \leq 2\pi$,

$$\text{So } \iint_S \vec{F} \cdot \vec{n} \, d\sigma = 0.$$

$$\text{Similarly: } \iiint_D (\nabla \cdot \vec{F}) \, dV = \iiint_D 0 \, dV = 0$$

$$\nabla \cdot \vec{F} = (0 + 0 + 0) = 0$$

ex: Calculate $\iint (\vec{F} \cdot \vec{n}) \, d\sigma$ over box $0 \leq x, y, z \leq 1$
of vector field $\vec{F} = (x^2, y^2, z^2)$ in both ways
using Divergence theorem.



$$\vec{F}|_3 = (x^2, y^2, z^2) = (x^2, 0, z^2) \text{ and } \vec{n}_3 = (0, -1, 0)$$

$$\vec{F}|_6 = (x^2, y^2, 0^2) \text{ and } \vec{n}_6 = (0, 0, -1)$$

$$\vec{F}|_2 = (0^2, y^2, z^2) \text{ and } \vec{n}_2 = (-1, 0, 0)$$

$$\text{So on } 3, 6, 2 \quad \vec{F} \cdot \vec{n} = 0$$

$$\text{However, } \vec{F}|_1 = (1^2, y^2, z^2) \quad \vec{n}_1 = (1, 0, 0)$$

$$\vec{F}|_4 = (x^2, 1^2, z^2) \quad \vec{n}_4 = (0, 1, 0)$$

$$\vec{F}|_5 = (x^2, y^2, 1^2) \quad \vec{n}_5 = (0, 0, 1)$$

$$\text{So Flux} = \iint 1 \, dA + \iint 1 \, dA + \iint 1 \, dA_5$$

$$= 3 \circ \text{Area of unit square} = 3.$$

On other hand, $\nabla \cdot \vec{F} = 2x + 2y + 2z$

$$\begin{aligned} \text{so } \iiint_D (\nabla \cdot \vec{F}) dV &= 2 \iiint_D (x + y + z) dV \\ &= 2 \int_{x=0}^{x=1} \int_{y=0}^{y=1} \int_{z=0}^{z=1} (x + y + z) dV = 2 \left(\frac{3}{2} \right) = 3 \end{aligned}$$

Relation between curl and divergence

theorem: if $\vec{F} = (M, N, P)$ with nice partial derivatives then

$$\text{div}(\nabla \times \vec{F}) = \nabla \cdot (\nabla \times \vec{F}) = 0$$

Proof: Some algebra

ex: Calculate $\iint_S (\vec{F} \cdot \vec{n}) d\sigma$ over the cube in the previous example

$\vec{F}$ is the vector field $\vec{F} = (2y - 2z, -2x + 2z, 2x - 2y)$

let's say you were having a good math day and noticed that

$$\vec{F} = \nabla \times \vec{r} \quad \text{where } \vec{r} = (x^2 + z^2, x^2 + z^2, x^2 + y^2)$$

$$\vec{F} = \nabla \times \vec{G} \text{ where } \vec{G} = (x, y, z)$$

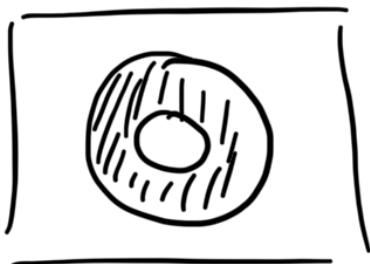
then by divergence theorem,

$$\begin{aligned} \iint_S (\vec{F} \cdot \vec{n}) d\sigma &= \iiint_D (\operatorname{div} \vec{F}) dV = \iiint_D \operatorname{div} (\nabla \times \vec{G}) dV \\ &= \iiint_D 0 dV = 0 \end{aligned}$$

Also it's a neat way to check if $\vec{F} = \nabla \times \vec{G}$
for some $\vec{G}$. ex: $\vec{F} = (x, y, z)$ has
 $\operatorname{div} \vec{F} \neq 0$ so no solution to $\vec{F} = \nabla \times \vec{G}$.

Divergence theorem holds for more general regions.

e.g. let D be region between two
concentric spheres.

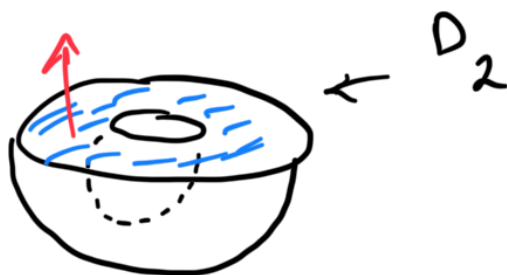


Slice of D

Can break D up into



$\leftarrow D_1$



$\leftarrow D_2$

S_1 = semi-outer sphere
semi-inner sphere
flat annulus

S_2 = semi-outer sphere
semi-inner sphere
flat annulus

By Divergence theorem $\iiint_{D_1} (\nabla \cdot \vec{F}) dV = \iint_{S_1} \vec{F} \cdot \vec{n} d\sigma$

and $\iiint_{D_2} (\nabla \cdot \vec{F}) dV = \iint_{S_2} \vec{F} \cdot \vec{n} d\sigma$. so

$$\iiint_D (\nabla \cdot \vec{F}) dV = \iint_{S_1} (\vec{F} \cdot \vec{n}) d\sigma + \iint_{S_2} (\vec{F} \cdot \vec{n}) d\sigma$$

$$= \iint_{\text{outer sphere}} (\vec{F} \cdot \vec{n}) d\sigma + \iint_{\text{inner sphere}} \vec{F} \cdot \vec{n} d\sigma$$

$$+ \iint_{\text{Annulus 1}} (\vec{F} \cdot \vec{n}) d\sigma + \iint_{\text{Annulus 2}} (\vec{F} \cdot \vec{n}) d\sigma$$

two could be opposite orientation!

$$\iint_{\partial D} (\vec{F} \cdot \vec{n}) d\sigma = \iiint_D (\nabla \cdot \vec{F}) dV \text{ where } \partial D \text{ is boundary of } D \text{ with possibly many pieces.}$$

ex: let $\vec{F} = (x, y, z)/p^3$ where $p = \sqrt{x^2 + y^2 + z^2}$

and calculate the flux of $\vec{F}$ across the boundary of

D as above. One can calculate for $p \neq 0$

that $\text{div } \vec{F} = 0$ (a little weird, looks like it wouldn't)

$$\text{so } \iiint_D \text{div } \vec{F} dV = \iint_{S_1} (\vec{F} \cdot \vec{n}) d\sigma + \iint_{S_2} (\vec{F} \cdot \vec{n}) d\sigma = 0$$

So $\iint_{\text{Sphere}} (\vec{F} \cdot \vec{n}) d\sigma$ independent of radius of sphere.

In fact if we choose sphere to be radius a

$$\text{Then } \vec{F} \cdot \vec{n} = \frac{(x, y, z)}{a^3} \cdot \frac{(x, y, z)}{a} = \frac{x^2 + y^2 + z^2}{a^4} = 1/a^2$$

$$\text{So Flux} = \iint_{\text{sphere}} (\vec{F} \cdot \vec{n}) d\sigma = \iint_{\text{sphere}} (1/a^2) d\sigma = (4\pi a^2)/a^2 = 4\pi$$

Gauss' Law: let $\vec{E} = \frac{1}{4\pi \epsilon_0} q \frac{\vec{r}}{|\vec{r}|^3}$

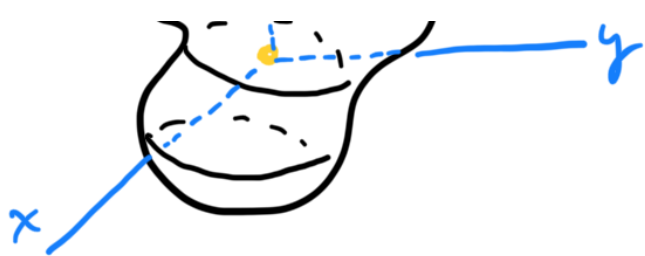
where ϵ_0 is a physical constant (electric permittivity of free space $\approx 10^{-11} \frac{\text{Coulomb}}{\text{Nm}^2}$)
 q is point charge located at origin, $\vec{r}$ is position vector.

Note by previous calculations, $\nabla \cdot \vec{E} = 0$.

So if S is any surface containing the origin point charge

$$\text{Flux of } \vec{E} \text{ across } S = \iint_S \vec{E} \cdot \vec{n} d\sigma = 4\pi \cdot \frac{q}{4\pi \epsilon_0} = q/\epsilon_0$$





Note that Green's theorem from before was

$$\oint_{\gamma} \vec{F} \cdot \vec{n} \, ds = \iint_R \left(\frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} \right) dA$$

So if we consider $\vec{F} = (M, N, 0)$ then $\text{div } \vec{F} = \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y}$

$$\text{So } \oint_{\gamma} (\vec{F} \cdot \vec{n}) \, ds = \iint_R (\nabla \cdot \vec{F}) \, dA$$

Similarly $(\nabla \times \vec{F}) \cdot \hat{k} = \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right)$ so

$$\begin{aligned} \oint_{\gamma} (\vec{F} \cdot \vec{T}) \, ds &= \iint_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dA \\ &= \iint_R (\nabla \times \vec{F}) \cdot \hat{k} \, dA \end{aligned}$$

Comparing:

Tangential Green in plane: $\oint_{\gamma} (\vec{F} \cdot \vec{T}) \, ds = \iint_R (\nabla \times \vec{F}) \cdot \hat{k} \, dA$

Stokes: $\oint_{\gamma} (\vec{F} \cdot \vec{T}) \, ds = \iint_S (\nabla \times \vec{F}) \cdot \vec{n} \, d\sigma$

Normal Green in plane: $\oint_{\gamma} (\vec{F} \cdot \vec{n}) \, ds = \iint_R (\nabla \cdot \vec{F}) \, dA$

Divergence:
$$\iint_S (\vec{F} \cdot \vec{n}) d\sigma = \iiint_D (\nabla \cdot \vec{F}) dV$$

All of these can be unified by a more
 general Stokes' Theorem. Very loosely

speaking

$$\int_D \text{derivative of something} = \int \partial D \text{ something}$$

Something is a differential form.